## University of Pennsylvania

## ESE 605 Modern Convex Optimization Homework 8

Due on Friday April 6

1. Robust least-squares with interval coefficient matrix: An interval matrix in  $R^{m \times n}$  is a matrix whose entries are intervals:

$$\mathcal{A} = \{ A \in \mathbb{R}^{m \times n} | A_{ij} - \bar{A}_{ij} | \le R_{ij}, \quad i = 1, \dots, m, \quad j = 1, \dots, n \}.$$

The matrix  $\bar{A} \in \mathbb{R}^{m \times n}$  is called the nominal value or center value, and  $R \subset \mathbb{R}^{m \times n}$ , which is element-wise nonnegative, is called the radius. The robust least-squares problem, with interval matrix, is

minimize 
$$\sup_{A \in \mathcal{A}} ||Ax - b||_2$$
,

with optimization variable  $x \in \mathbb{R}^n$ . The problem data are  $\mathcal{A}$  (i.e.,  $\bar{A}$  and R) and  $b \in \mathbb{R}^m$ . The objective, as a function of x, is called the worst-case residual norm. The robust least-squares problem is evidently a convex optimization problem.

- (a) Formulate the interval matrix robust least-squares problem as a standard optimization problem, e.g., a QP, SOCP, or SDP. You can introduce new variables if needed. Your reformulation should have a number of variables and constraints that grows linearly with m and n, and not exponentially.
- (b) Consider an over-determined specific problem instance with m = 10, n = 5, with A generated in Matlab as  $\bar{A}$ =round(10\*rand(10,5)), b=round(5\*rand(10,1)). The matrix R should be chosen in such a way that the uncertainty in each entry of A is  $\pm 0.1$ . Find the solution  $x_{ls}$  of the nominal problem (i.e., minimize  $||\bar{A}x b||_2$ ), and robust least-squares solution  $x_{rls}$ . For each of these, find the nominal residual norm, and also the worst-case residual norm. You need to use CVX for this problem.
- 2. Assume the set A in problem 1 is given by  $\bar{A} + U$ , where  $||U||_2 \le 0.1$ . Find the robust least squares solution with the same problem data as before. Find the worst case residual norm.
- 3. Problem 8.9 and 8.20 from the text
- 4. State and solve the optimality conditions for the problem

**minimize** 
$$\log \det \begin{bmatrix} X_1 & X_2 \\ X_2^T & X_3 \end{bmatrix}^{-1}$$

subject to

$$\mathbf{tr} X_1 = \alpha$$

$$\operatorname{tr} X_2 = \beta$$

$$\mathbf{tr} X_3 = \gamma$$

The optimization variable is  $X = \begin{bmatrix} X_1 & X_2 \\ X_2^T & X_3 \end{bmatrix}$  with  $X_1 \in \mathbb{S}^n, \ X_2 \in \mathbb{R}^{n \times n}, \ X_3 \in \mathbb{S}^n$ . The domain of the objective function is  $\mathbb{S}^{2n}_{++}$ . We assume  $\alpha > 0$ , and  $\alpha \gamma > \beta^2$ .