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## Characterization of taper effects in TFGs

# MIT's Laboratory for Mfg. & Productivity

An interdepartmental laboratory within SoE

Manufacturing-centric research



**Laboratory for Manufacturing  
and Productivity**

Founded more than 30 years ago

Over \$7M research volume per year

**PROCESSES AND EQUIPMENT**

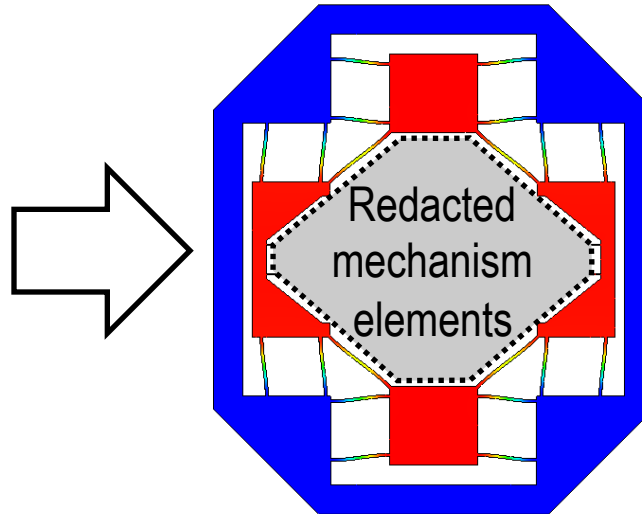
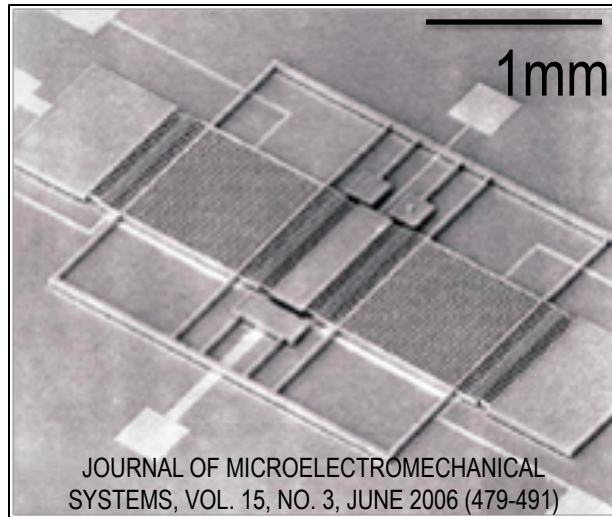
**GREEN**

**SYSTEMS**



## Purpose:

Sensitivity analysis for meso-scale solid-state gyroscope



Due to sponsor and IP restrictions, only a portion of the mechanism may be shown

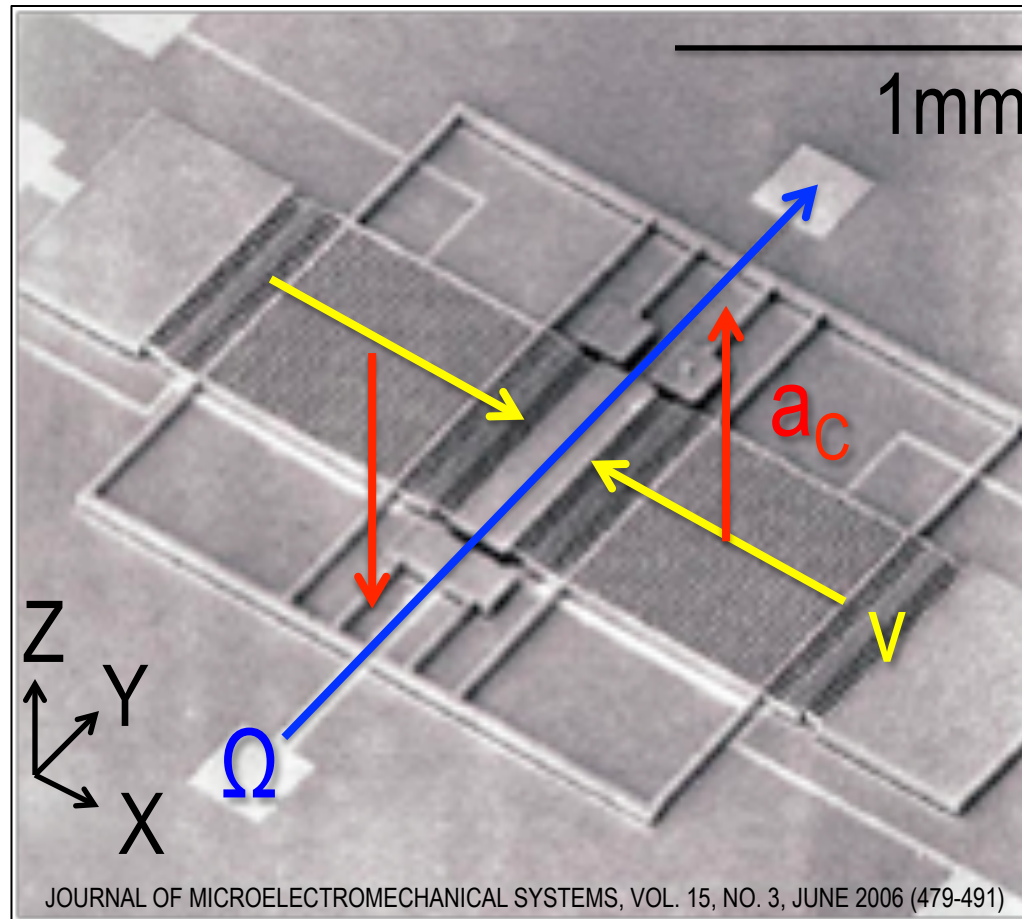
## Import:

High performance solid-state gyroscope for inertial guidance and positioning

## Impact:

*Impact only if sensitivity to geometric errors is acceptable*  
*Obtaining physical prototype requires 5 axis machine*

# Tuning Fork Gyroscope



$$\vec{a}_C = 2\vec{\Omega} \times \vec{v}$$



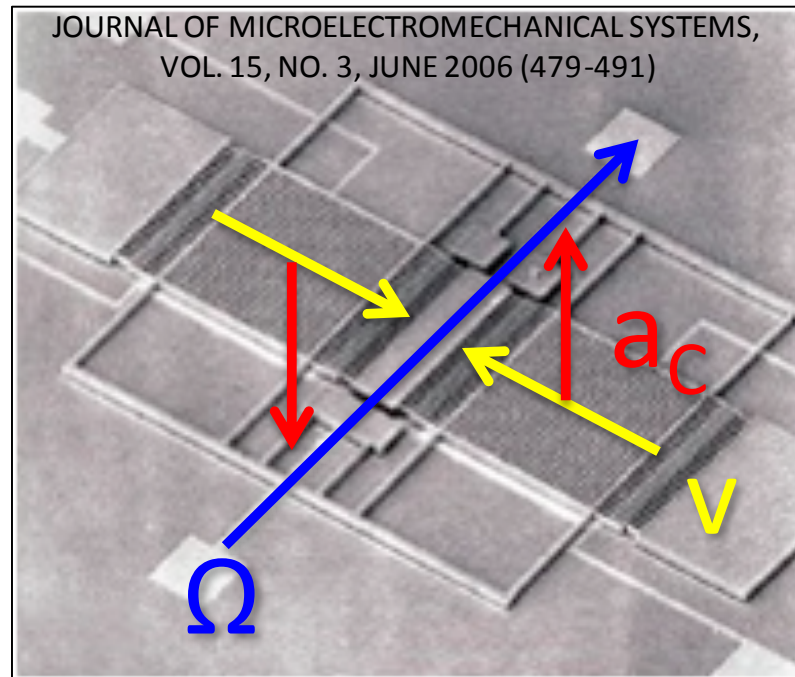
# Fundamental problem

Mass and stiffness of components need to be closely matched

Sub-micron taper and thickness variations in beams ruin performance

Masses with opposing motions (yellow and red arrows) required

$$\vec{a}_C = 2\vec{\Omega} \times \vec{v}$$

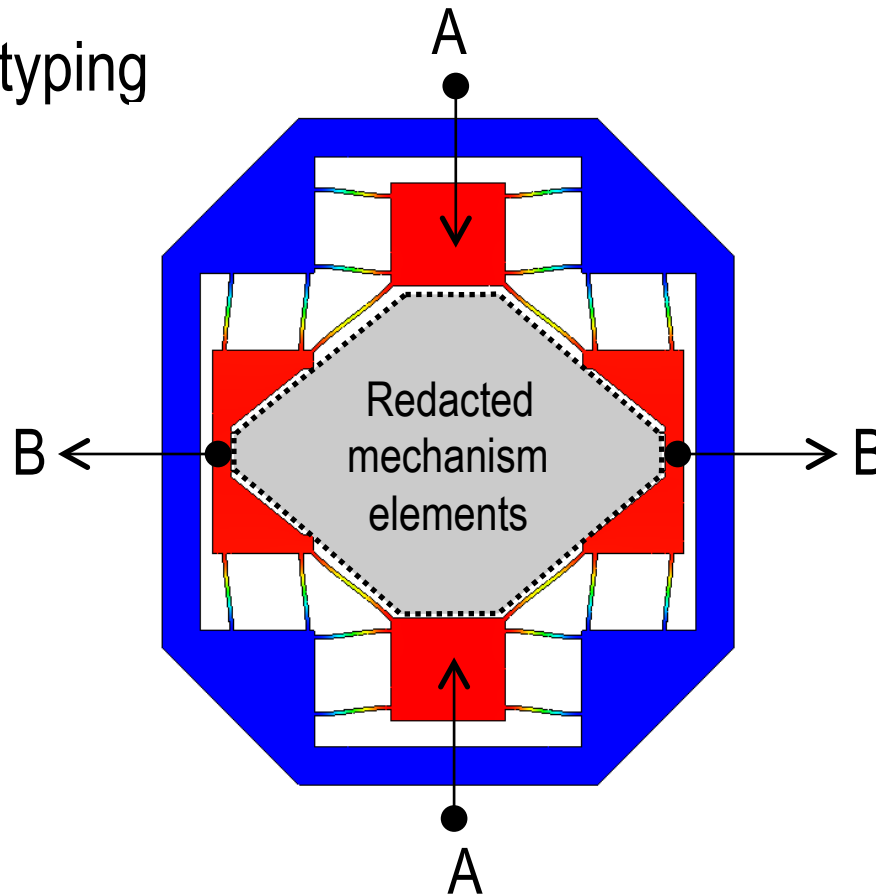


# Solution

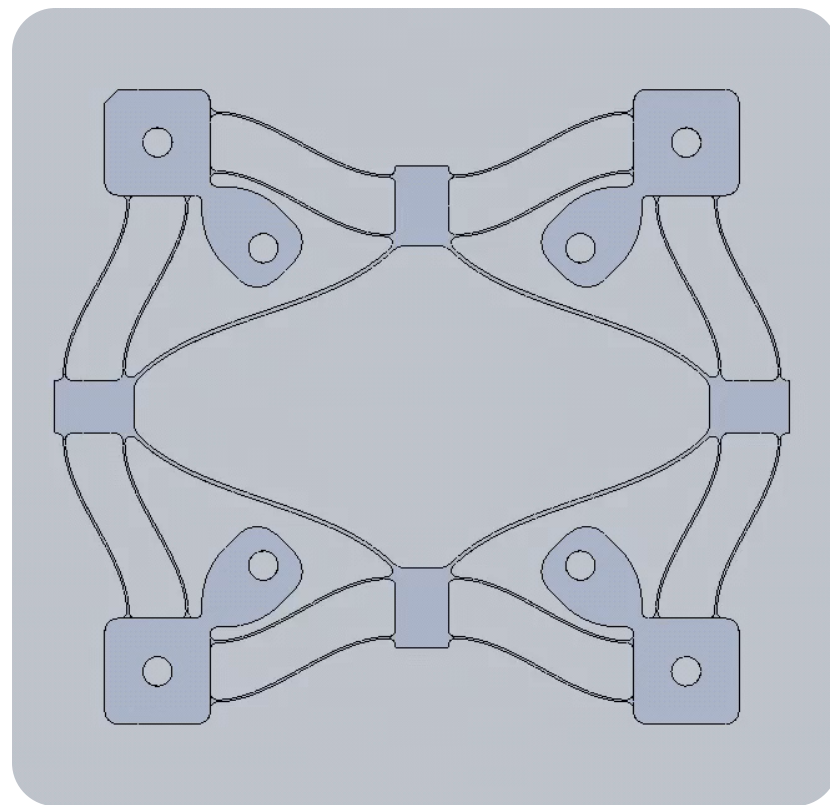
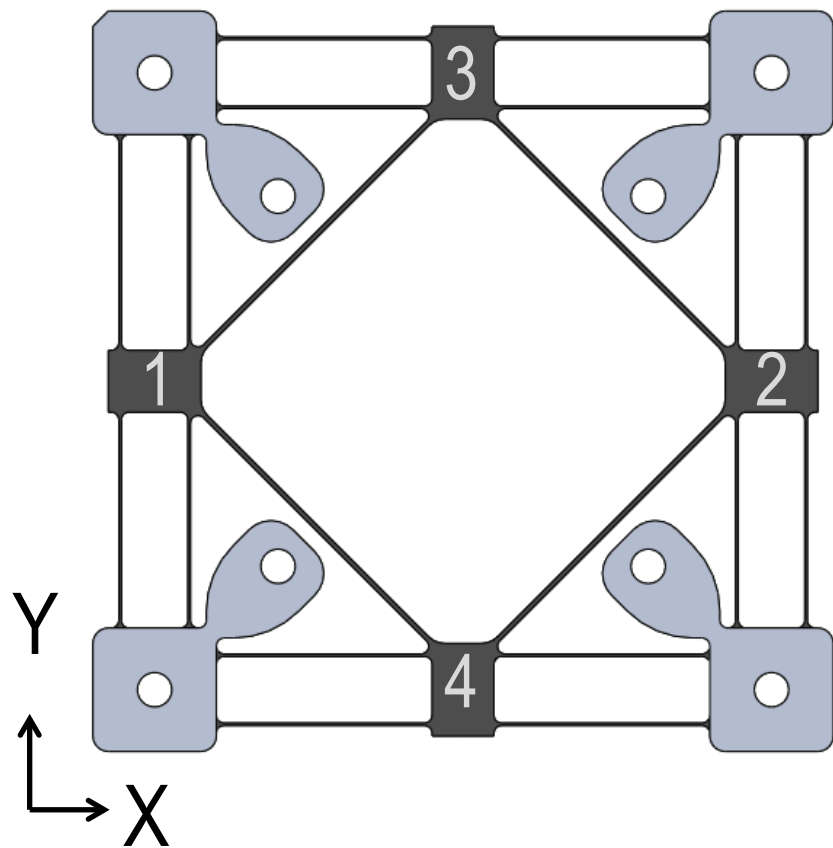
New design is inherently better at providing correct motions than prior art

Need to determine sensitivity to taper/thickness variations in beams

5 axis need for prototyping

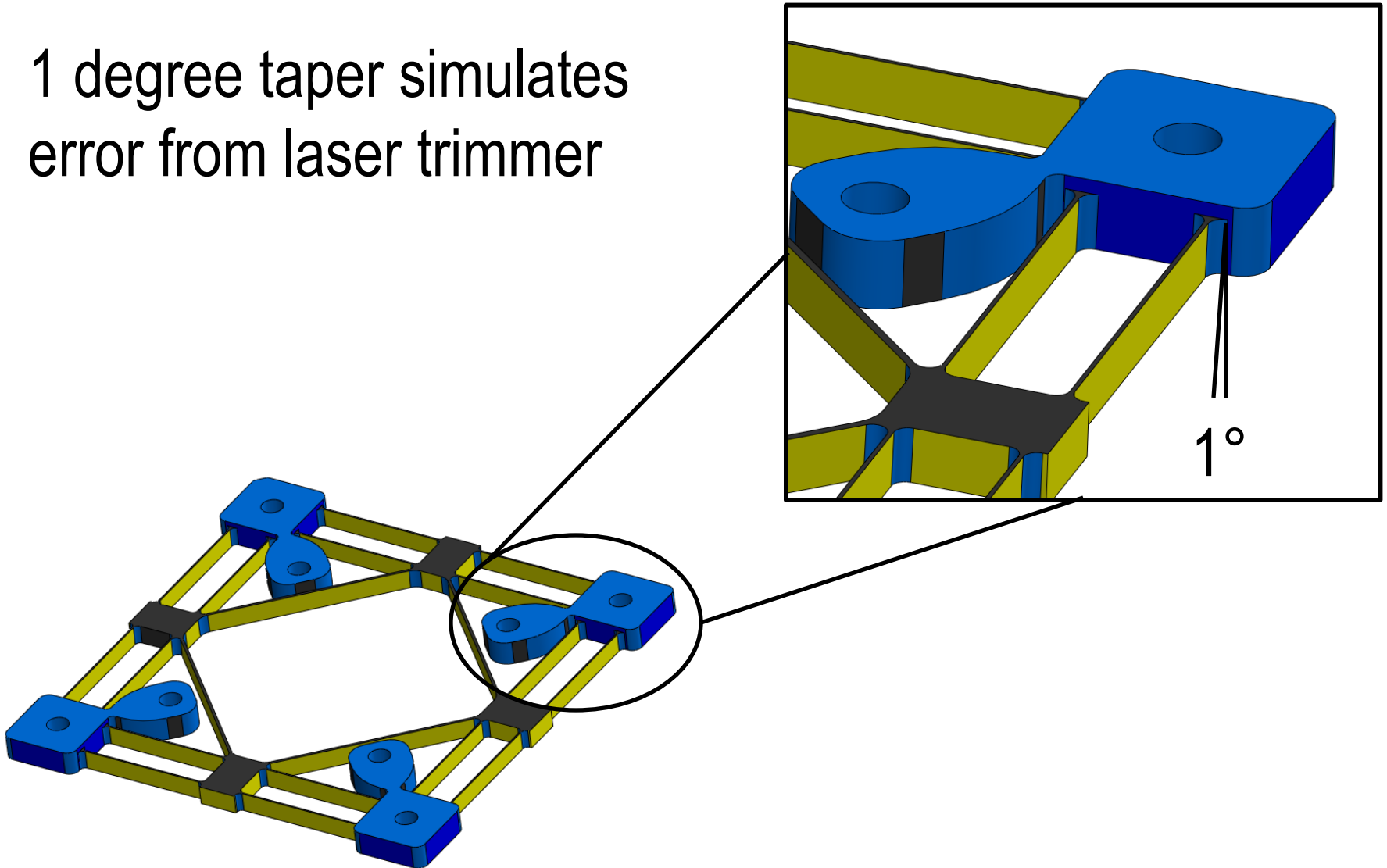


# Drive Axis Flexure Concept



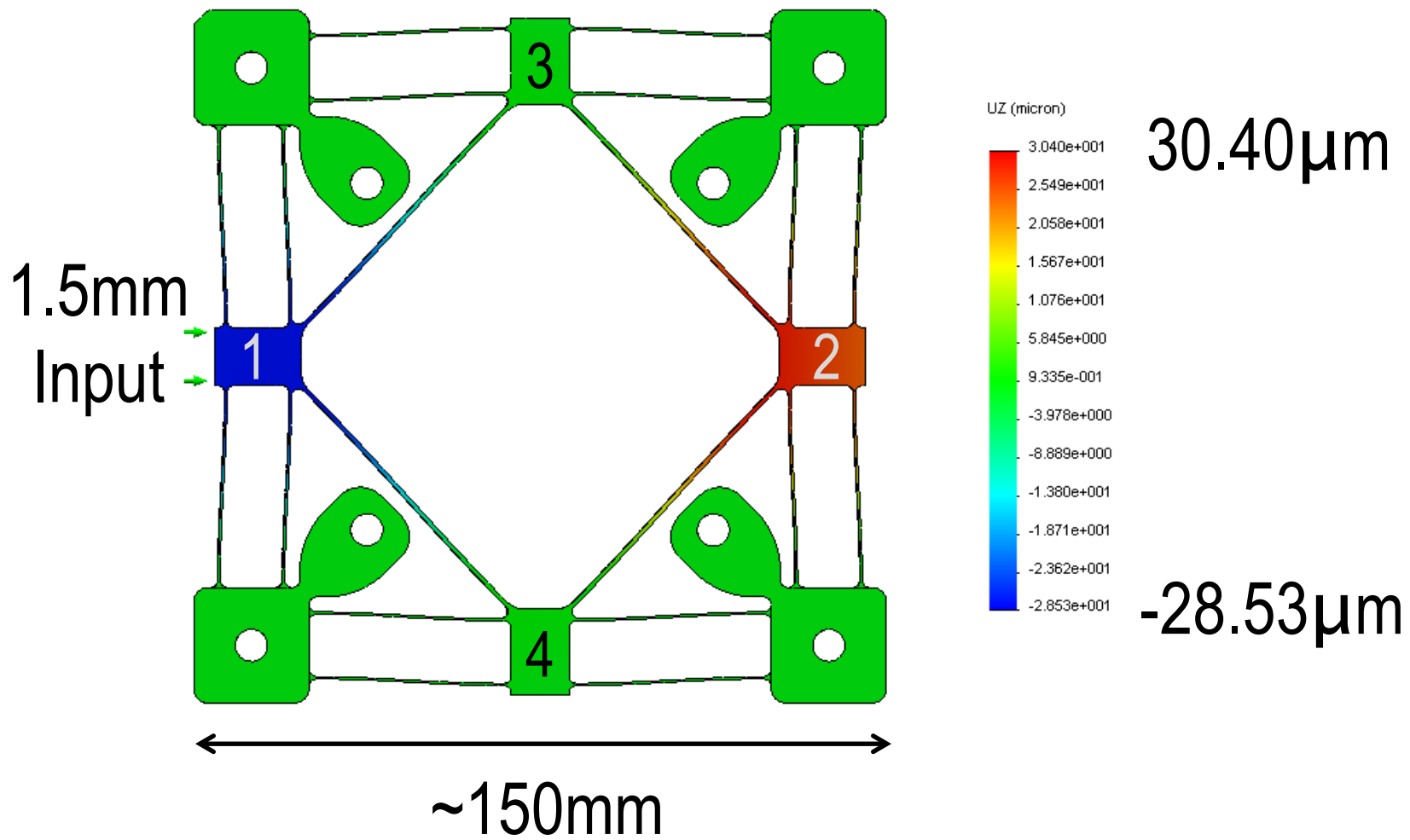
# Introduce Taper

1 degree taper simulates error from laser trimmer

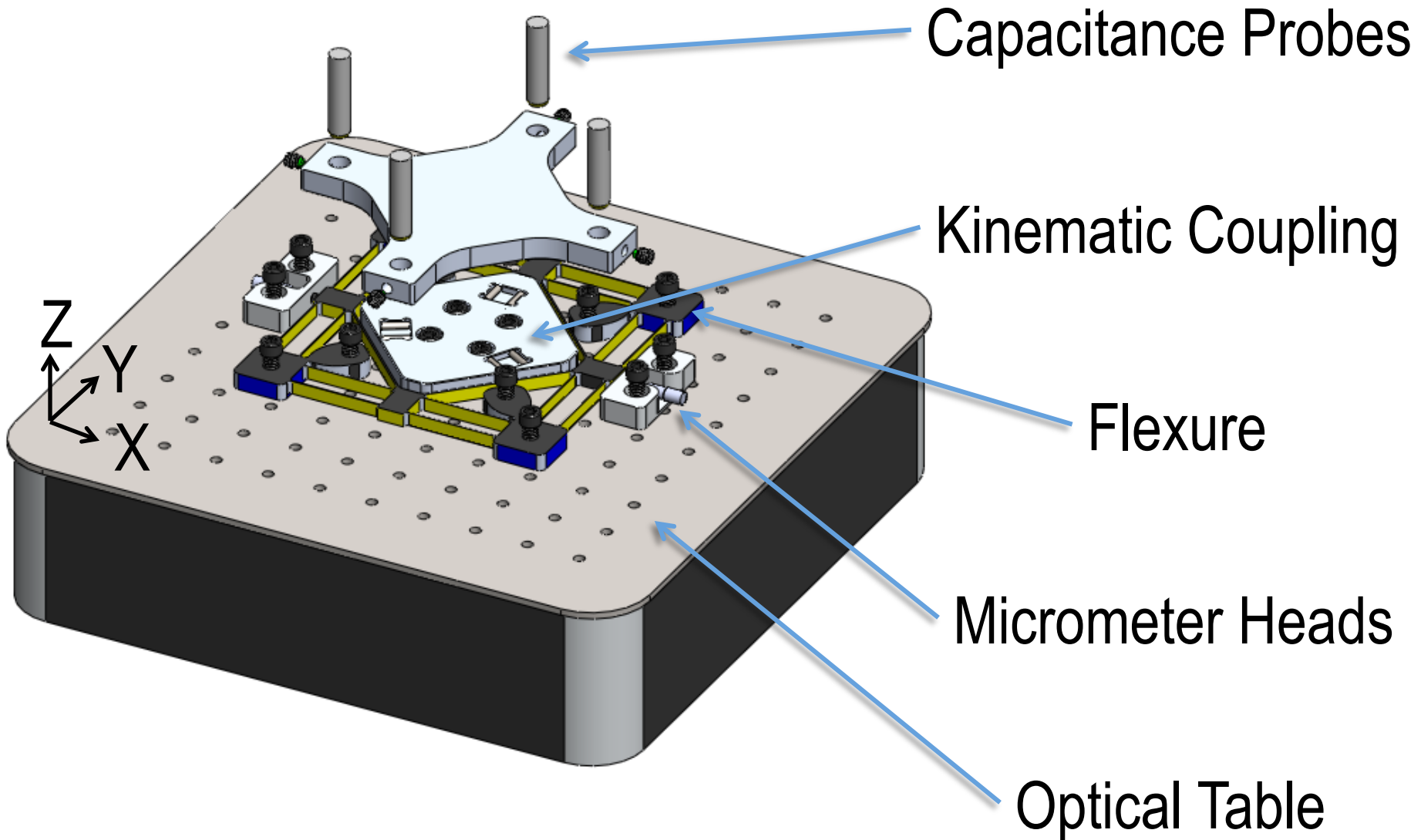


# FEA simulation of defects

1° of taper  $\rightarrow$   $\sim$ 2% out-of-plane motion

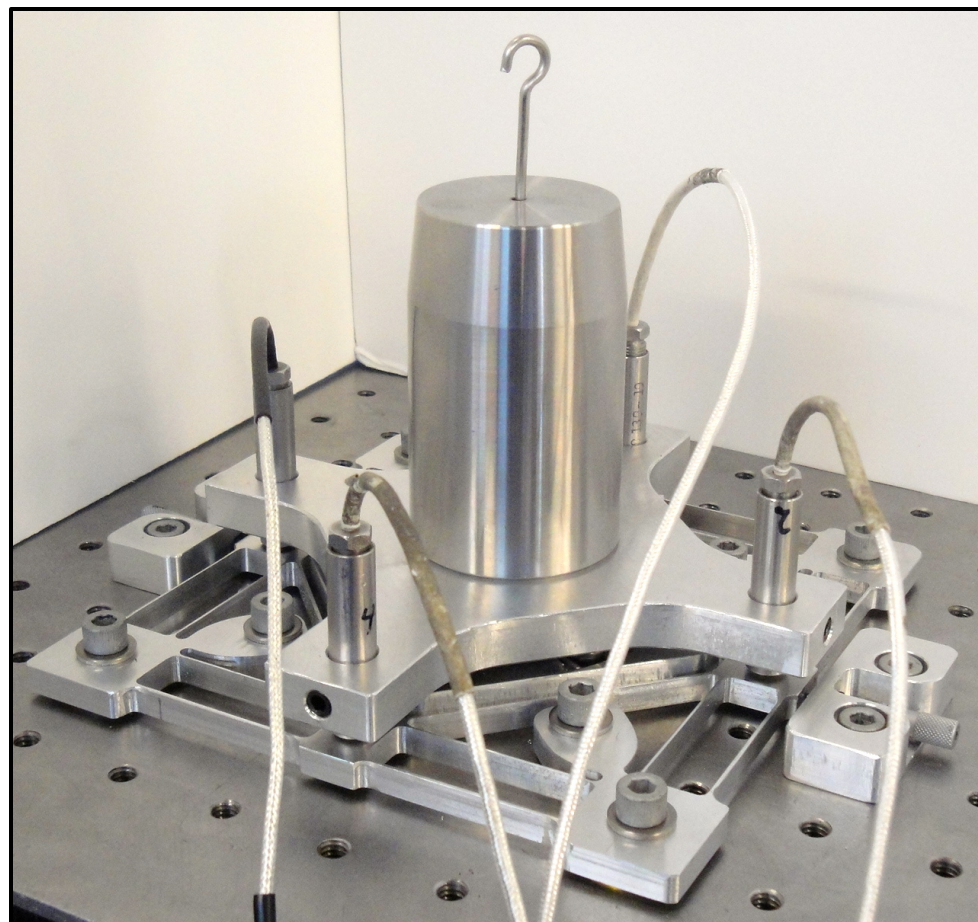
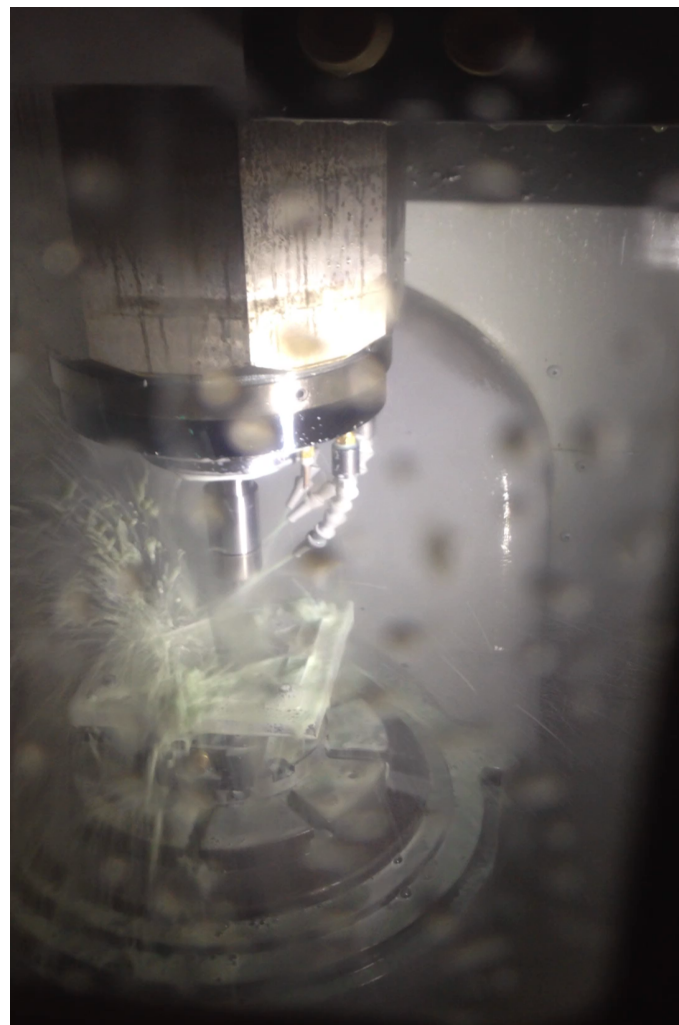


# Experimental Design Detail



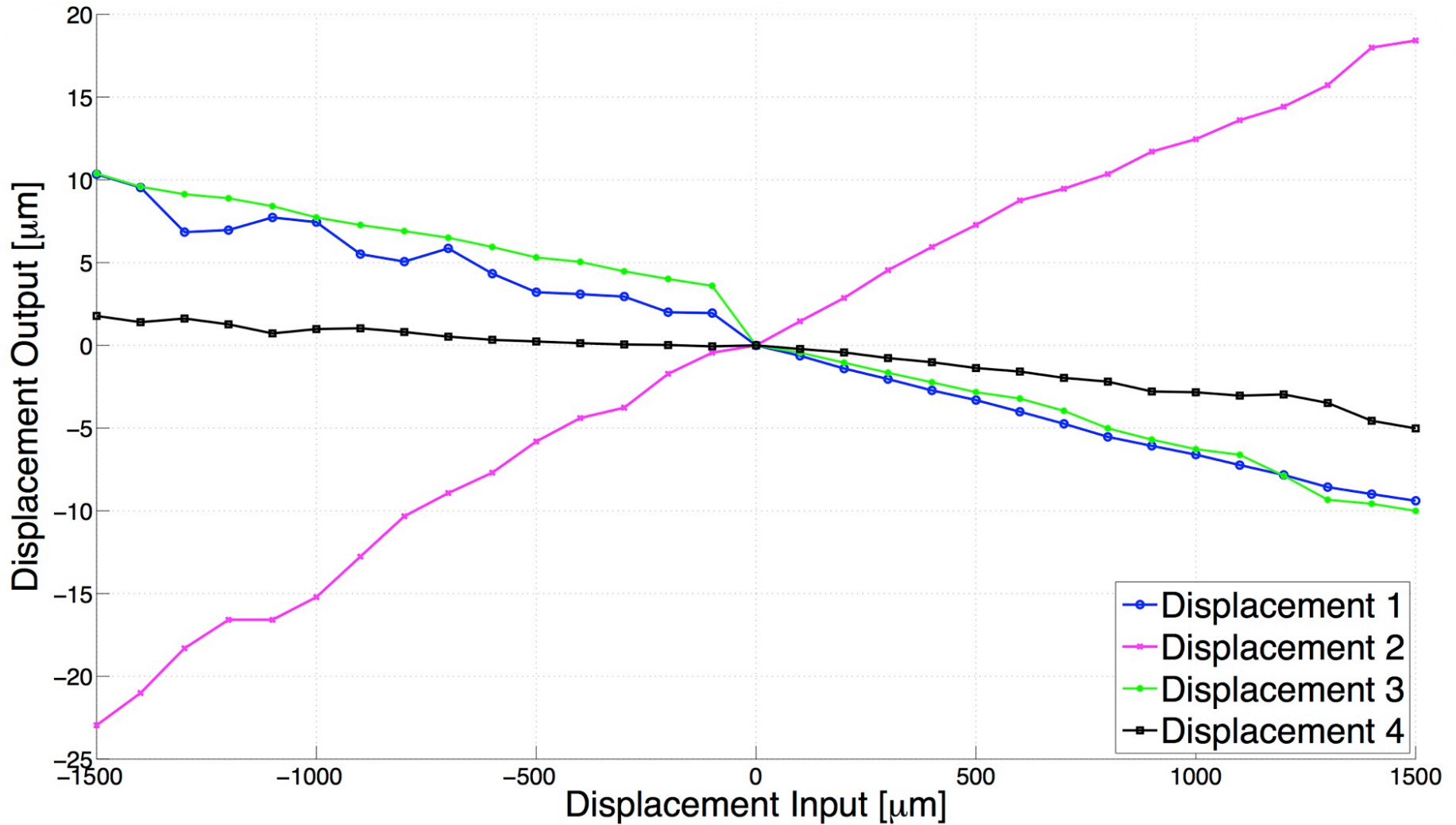


# Prototype and Experimental Setup



Mori Seiki NMV1500DCG

# Measured Displacements



# Summary

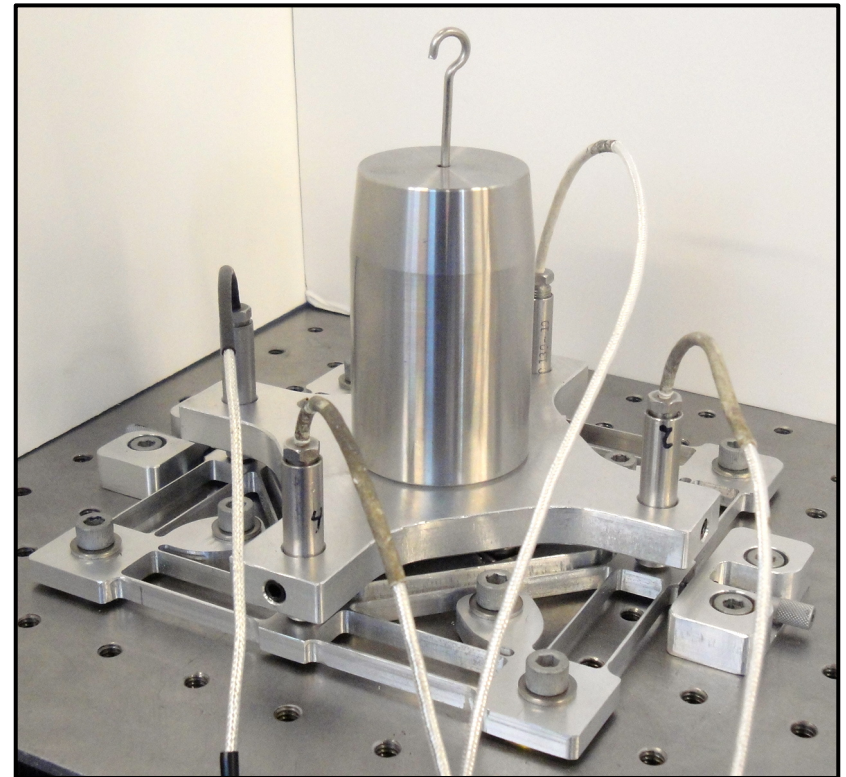
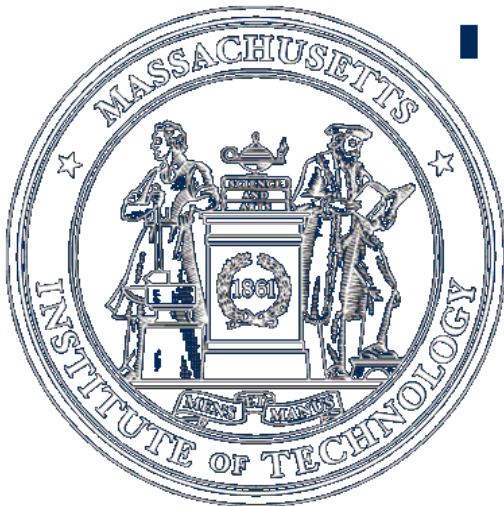
~4x reduction of out-of-plane motion from state-of-the-art

Applied precision machine design principles

Kinematic Coupling

Flexure

Hands-on learning with 5-axis mill



# Education – Design & Manufacturing

2.72 (MIT student education)  
Elements of Mechanical Design

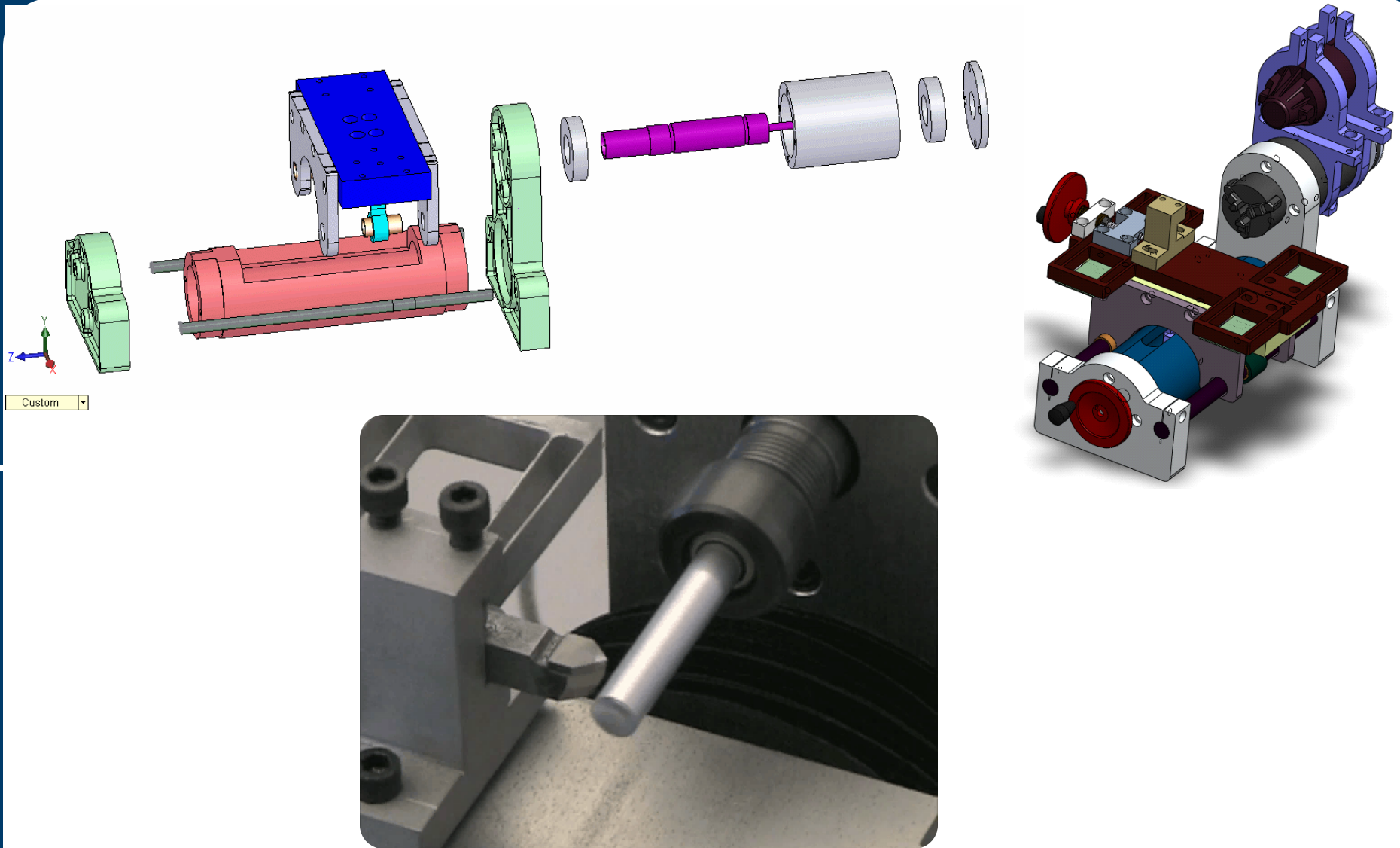
- ❑ HTM modeling
- ❑ Design example
- ❑ Stiffness
- ❑ Accuracy
- ❑ Repeatability

2.75s (Professional education)  
Advanced Design & Mfg

- ❑ HTM modeling
- ❑ Design example
- ❑ Stiffness
- ❑ Accuracy
- ❑ Repeatability



# 2.72 Precision Lathe Design/Mfg.



# Education – Design & Manufacturing

2.008

Design and Manufacturing II



□ Emphasis on

- *Physics*
- *Stochastic nature of mfg.*
- *Quality*
- *Rate*
- *Cost*
- *Flexibility*

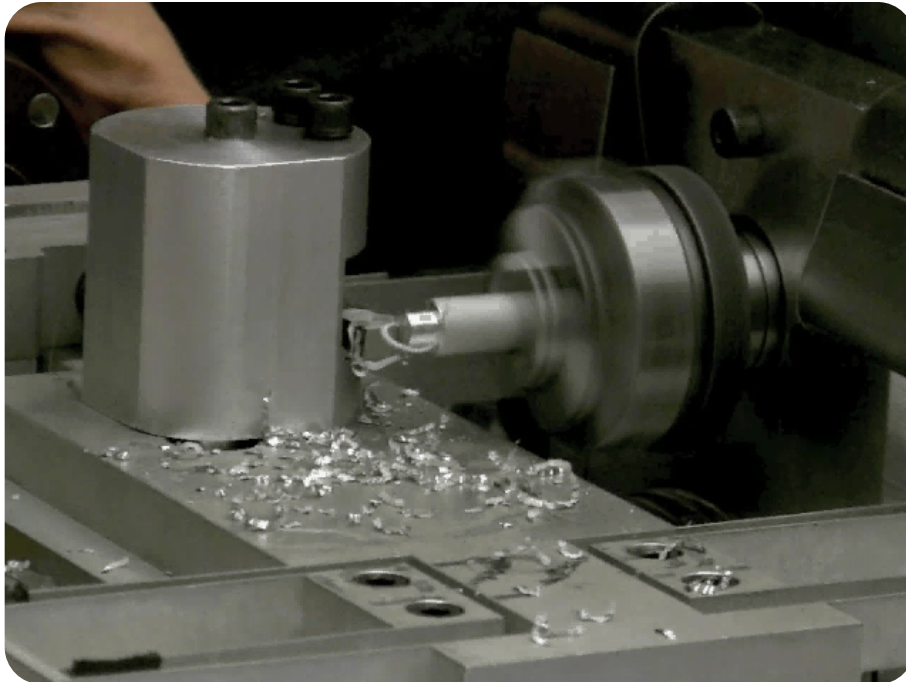
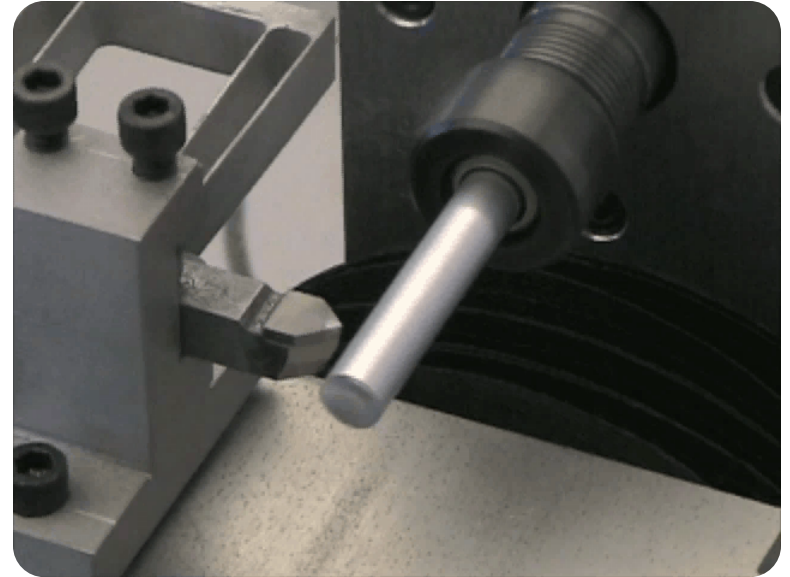


# Questions and Acknowledgements

Many thanks to our sponsors

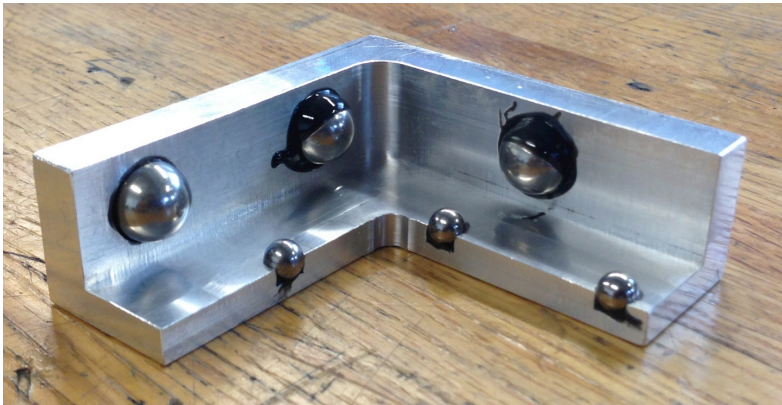
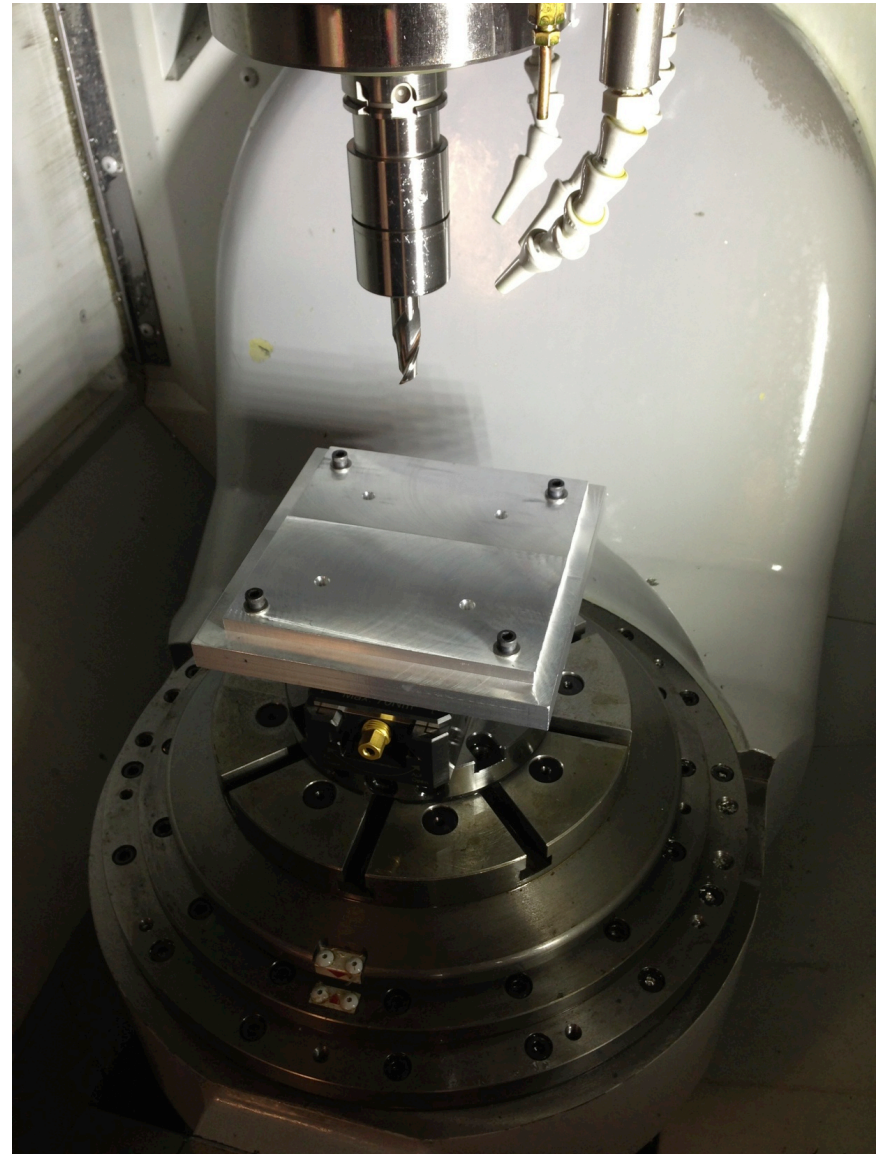
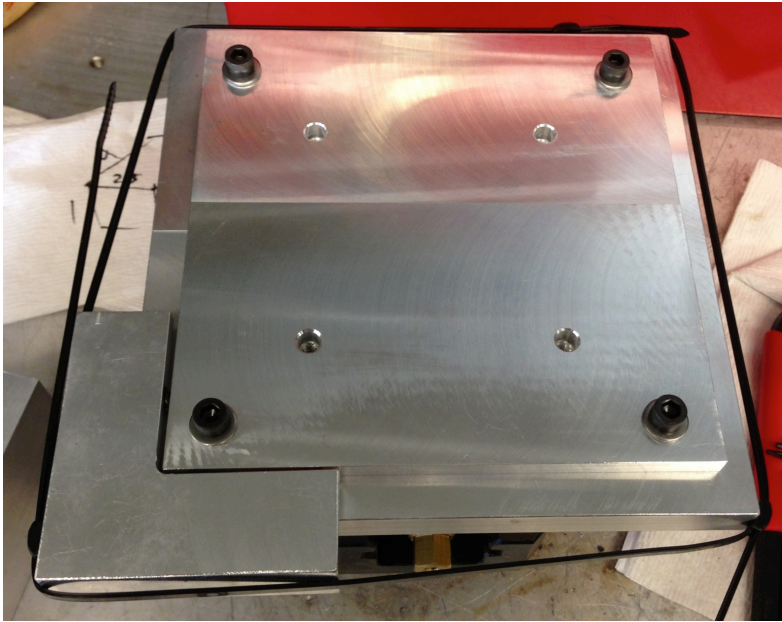
**MITTRF**

**MORI SEIKI**  
**THE MACHINE TOOL COMPANY**



# Backup Slides

# Manufacturing





# Experimental Setup

