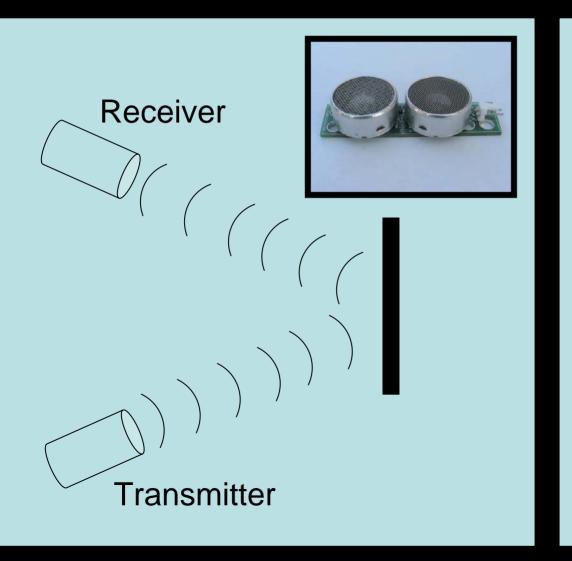
# 2-D Mapping with Sonar

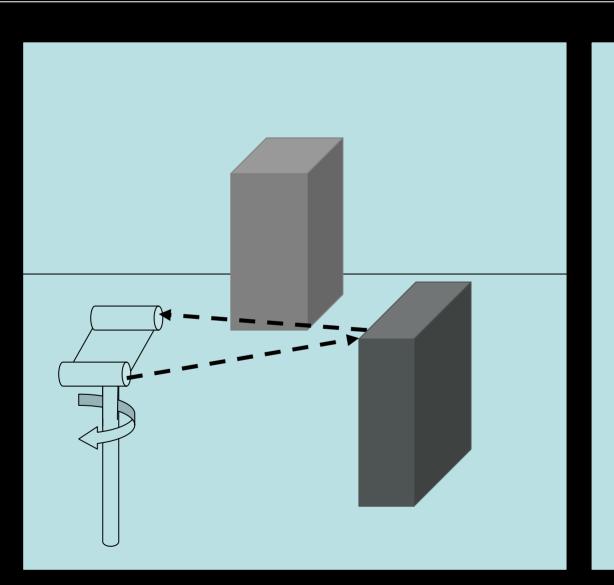
Leon Fay
Miranda Ha
Vinith Misra
Not Chris

#### **Basic Sonar**



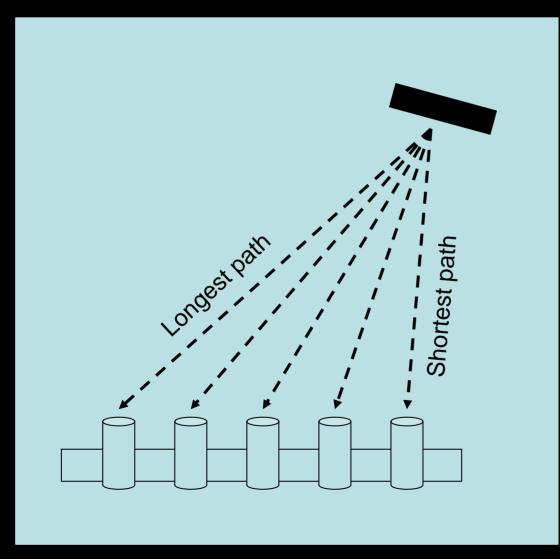
- Ultrasound cannot be heard by people
- Small wavelength=> good for shortdistances
- Time of flight can be used to estimate distance

# **Basic Mapping**



- Rotate receiver/ transmitter to measure distance at every angle
- Slow update rates because of many distance measurements

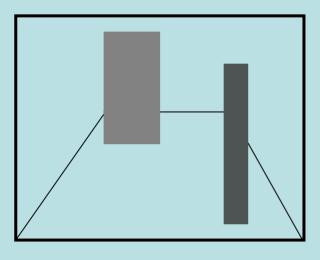
## **Phase Array**

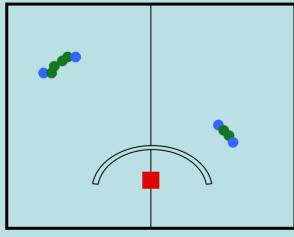


- Use multiple receivers, measure different angles using phase relationships
- No moving parts => more reliable
- Faster update rate

Basic Sonar Basic Map Phase Array

# Applications

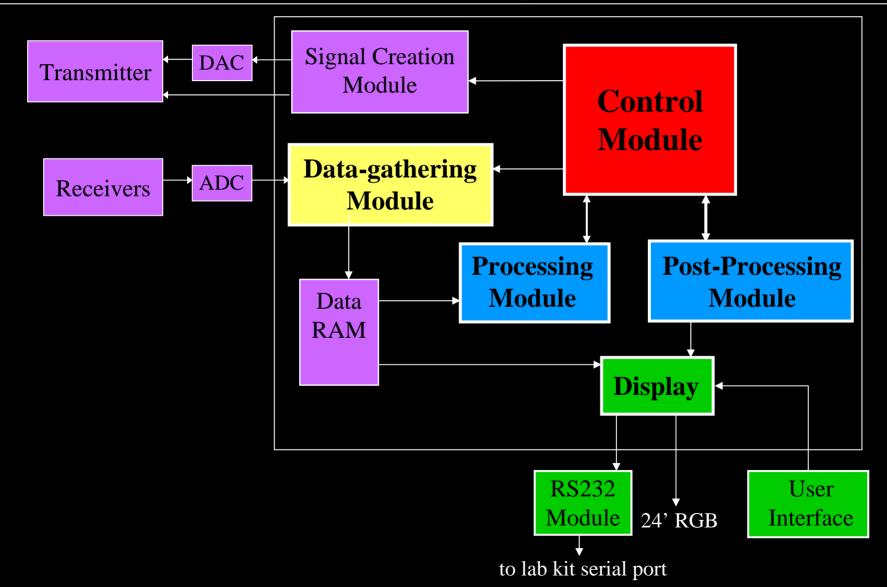




- Draw a top view map of environment
- Security system that detects changes in surroundings

Transmit/ Data- Control/ Display/ Process Interface

# Simplified Block Diagram

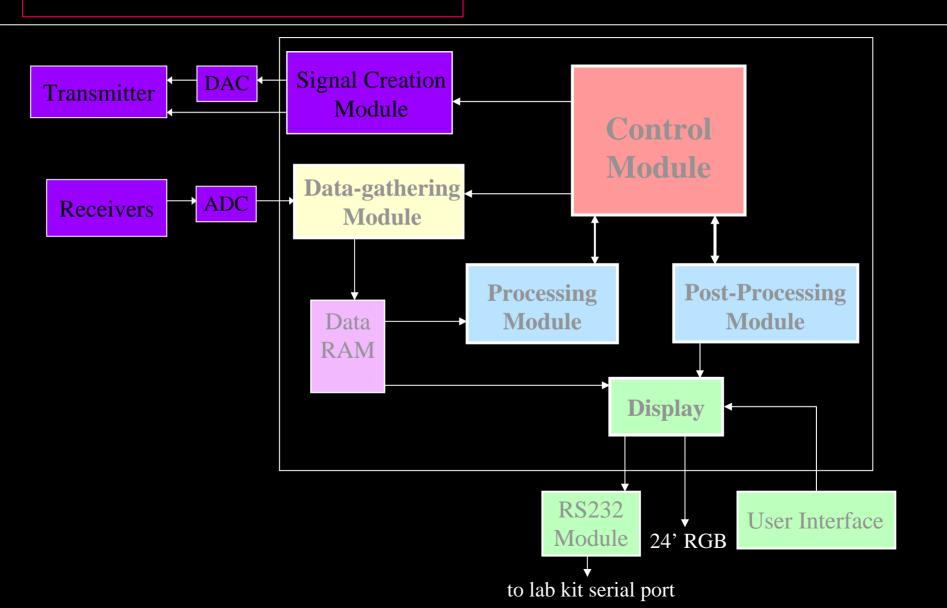


Datagathering Process Interface

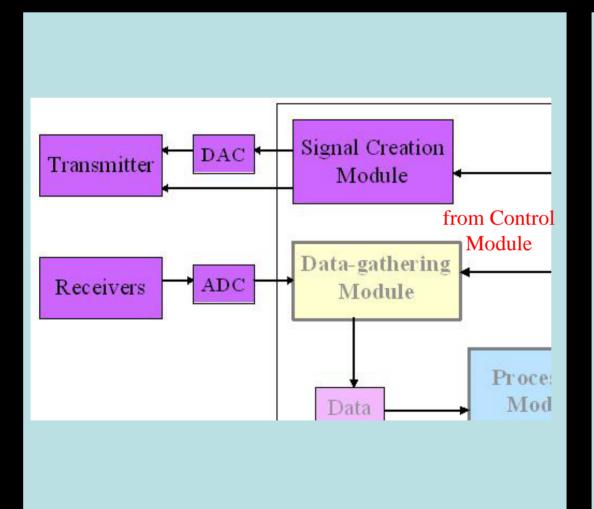
Control/

Display/

## Transmit/Receive



## Transmit/Receive



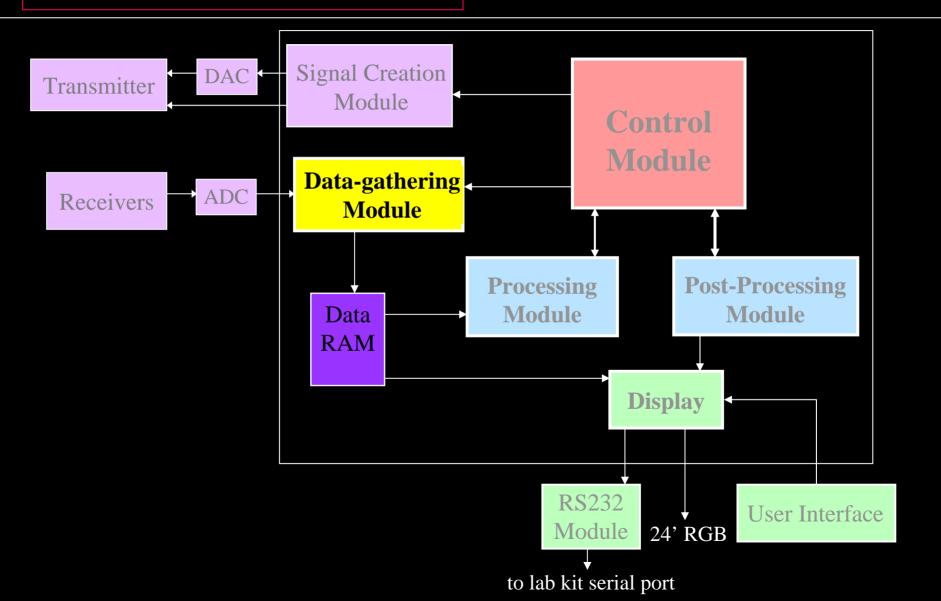
- Transmit a single
   40-kHz sine wave
   pulse (generated
   from stored values
   played through DAC)
- Multiple receivers
- Enable signals from Control Module for transmitting and receiving

Transmit/ Receive

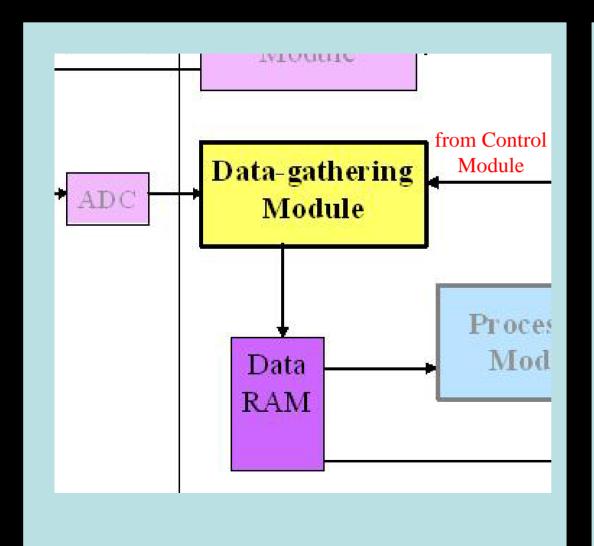
Control/ Process Interface

Display/

# **Data-gathering**

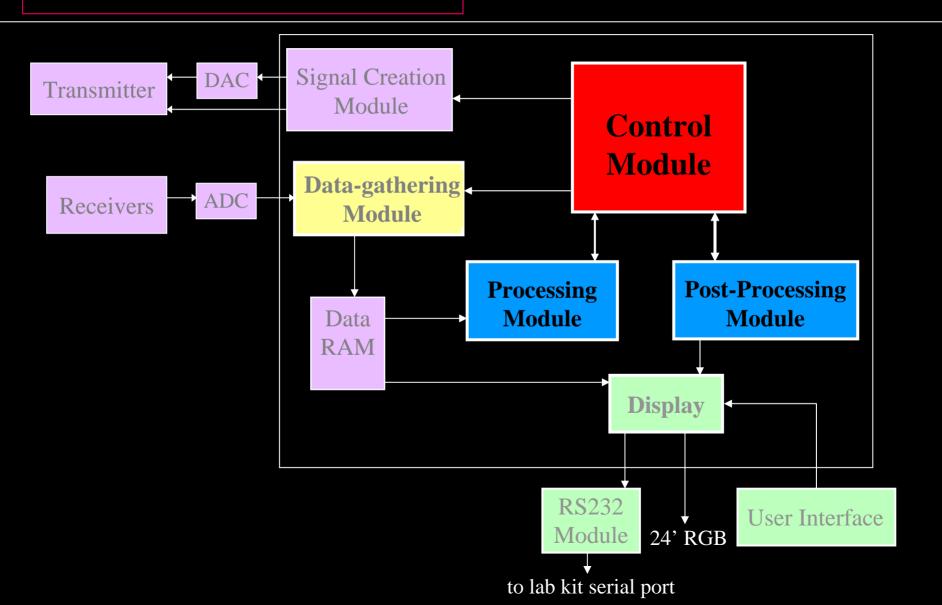


## **Data-gathering**



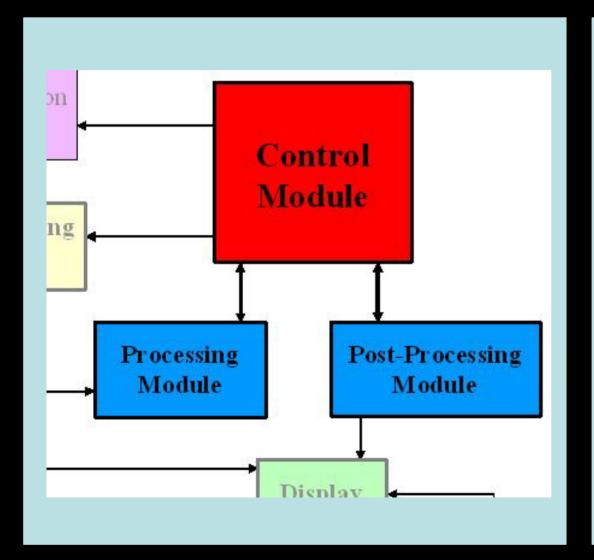
- Samples data from receivers at intervals dictated by Control Module
- Data stored in one of two RAMs
- Simultaneous storage and processing of data— "double buffering"

#### **Control/Process**



Receive

#### **Control/Process**

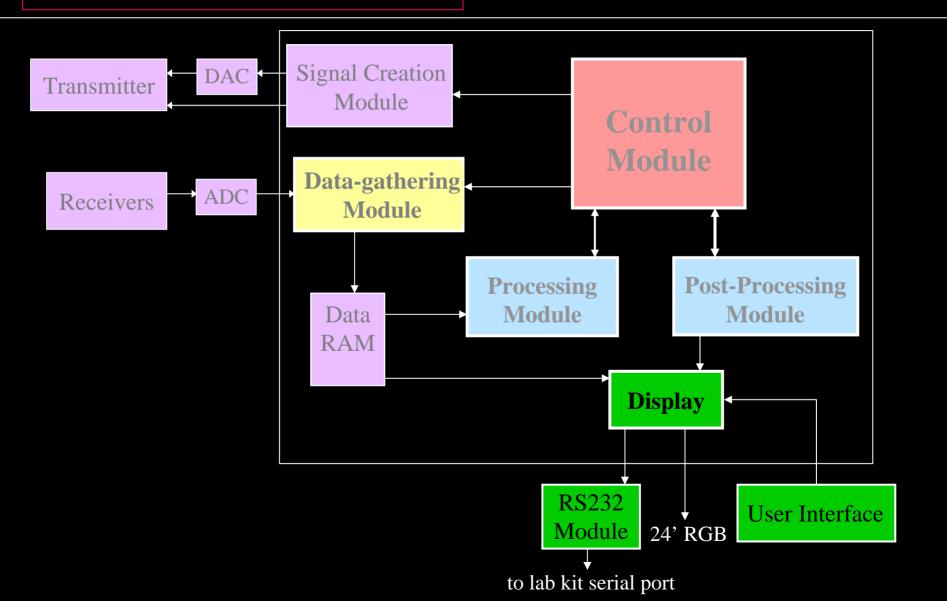


- Control Module gives Processing Module an angle; **Processing Module** gives back distance at that angle
- Post-Processor gets angle/distance pairs ready for display and tells Control Module if more data is needed

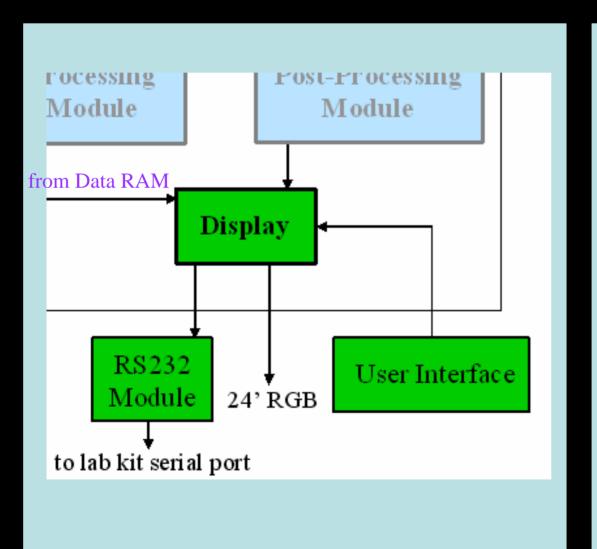
Transmit/ Data-Receive

Control/ gathering Process

## Display/Interface

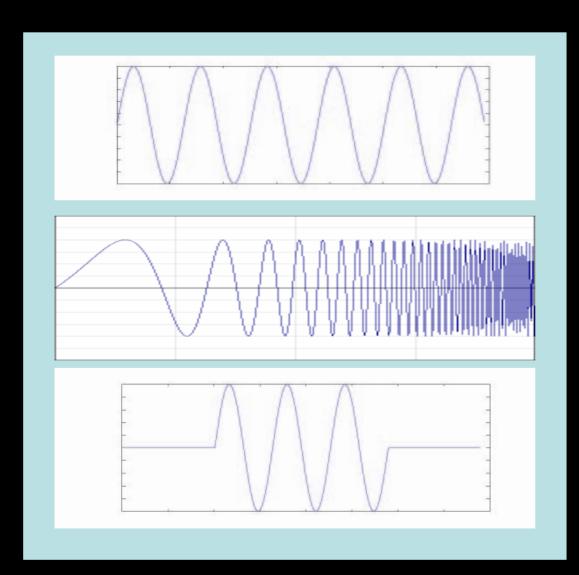


## Display/Interface



- Display Module gives VGA controller appropriate RGB signals
- Main purpose is to draw a 2-D, colorcoded map of the environment
- RS232 Module is for debugging
- User can choose what is displayed

# Sines, Chirps, and Pulses

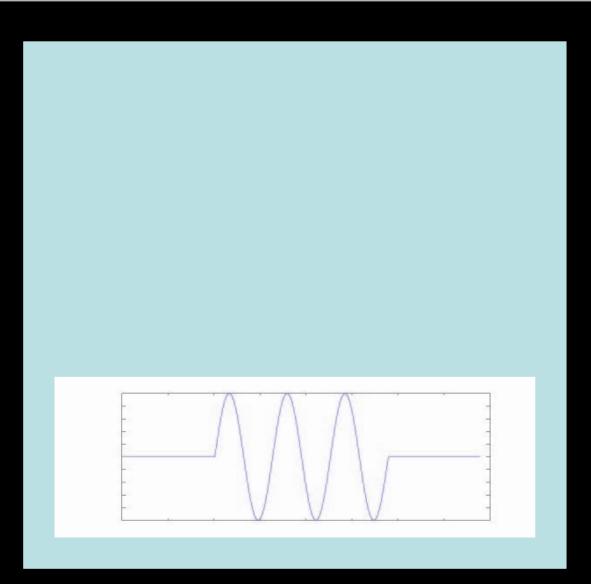


•What kind of signal to transmit?

- Steady Sine Wave
- Chirp (linearly changing frequency)
- Short pulsed sine wave

Game Plan

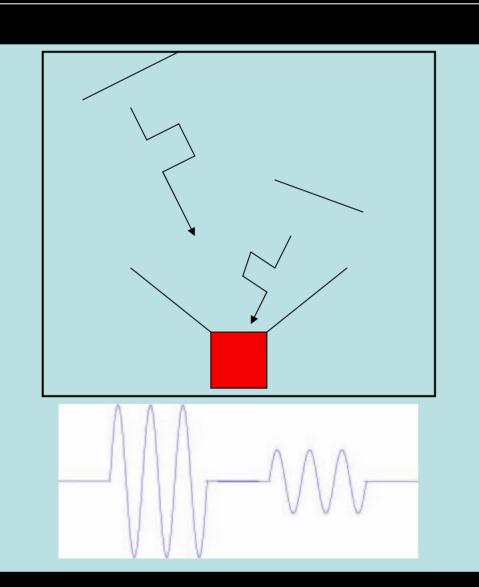
# Sines, Chirps, and Pulses



•What kind of signal to transmit?

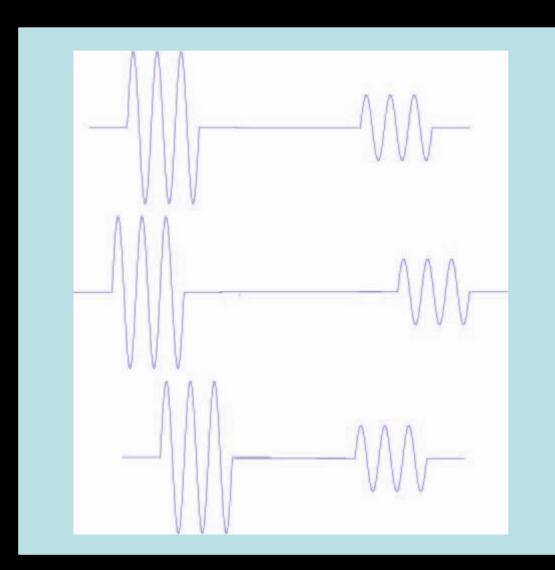
- Steady Sine Wave
- Chirp (linearly changing frequency)
- Short pulsed sine wave

# **Game Plan**



Send a pulse, receive attenuated & shifted signal

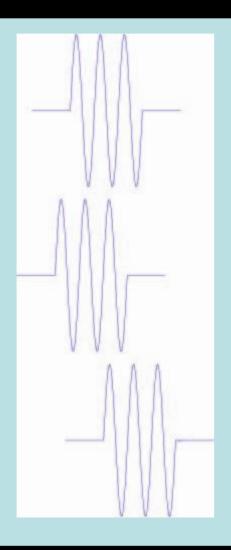
## **Game Plan**



- •For each reflection, different receivers have similar attenuation, but slight phase shifts.
- Can expand as 2 delays:
  - Object to receiver
  - 1 DISTANCE
  - Receiver 1 toReceiver N -

**DIRECTION** 

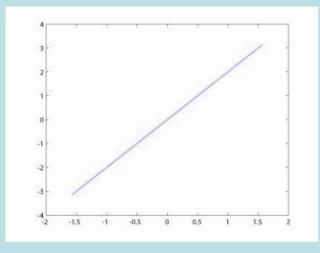
### **The Process**

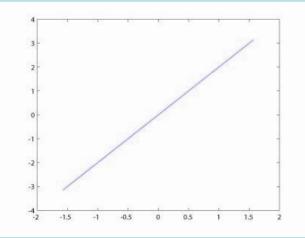


- 1. Find where a certain phase relation is most likely to have occurred (similar to matched filtering)
- 2. Record the delay to this region of the signal
- Distance = (half delay to max) \*
   (speed of sound)

What To Game
Transmit Plan

# **The Process**





After post-processing, matches almost perfectly in simulation.