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internal.v

```

1 `timescale 1ns / 1ps
2 `include "defines.v"
3 module internal(
4     reset, clock,
5     model_select,
6     paddle_up, paddle_down, paddle_speed, ball_initial_speed, // game inputs
7
8     ram0_data, ram0_address, ram0_we_b, // ram 0 buss
9     ram1_data, ram1_address, ram1_we_b, // ram 1 buss
10
11    mouse0_clock, mouse0_data, // ps/2 0 buss
12    mouse1_clock, mouse1_data, // ps/2 1 buss
13    buttons,
14
15    vga_rgb, vga_blank_b, vga_hsync, vga_vsync // vga outputs
16 );
17
18 input clock;
19 input reset;
20
21 input [3:0] model_select;
22
23 input paddle_up;
24 input paddle_down;
25 input [3:0] paddle_speed;
26 input [3:0] ball_initial_speed;
27
28 inout [35:0] ram0_data;
29 output [18:0] ram0_address;
30 output ram0_we_b;
31
32 inout [35:0] ram1_data;
33 output [18:0] ram1_address;
34 output ram1_we_b;
35
36 input mouse0_clock;
37 input mouse0_data;
38 input mouse1_clock;
39 input mouse1_data;
40 input [~NUM_BUTTONS-1:0] buttons;
41
42 output [23:0] vga_rgb;
43 output vga_blank_b;
44 output vga_hsync;
45 output vga_vsync;
46
47 wire [23:0] read_rgb, df_rgb;
48 wire blank_b, hsync, vsync, enable, blanking;
49 wire [9:0] pixel_count, line_count;
50 vga vgal(
51     .reset(reset),
52     .pixel_clock(clock),
53     .blank_b(blank_b),
54     .hsync(hsync),
55     .vsync(vsync),
56     .pixel_count(pixel_count),
57     .line_count(line_count),
58     .blanking(blanking),
59     .enable(enable));
60
61
62
63

```

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internal.v

```

64 delay #(5) dyl (reset, clock, blank_b, vga_blank_b);
65 delay #(5) dy2 (reset, clock, hsync, vga_hsync);
66 delay #(5) dy3 (reset, clock, vsync, vga_vsync);
67
68 wire [9:0] paddle_y;
69 wire [9:0] ball_x;
70 wire [9:0] ball_y;
71 display_field df(
72     (reset, pixel_count, line_count,
73      paddle_y, ball_x, ball_y, 24'b0, df_rgb);
74 add_rgb #(0, 1) ar(
75     (reset, clock, read_rgb,
76      df_rgb & (~{(24){model_select[0]||model_select[1]})), vga_rgb);
77
78 wire switch_buffer;
79 wire [9:0] write_pixel_count, write_line_count;
80 wire [11:0] write_z;
81 wire [23:0] write_rgb;
82 wire pixel_next;
83 screen_buffer sb(
84     .reset(reset),
85     .clock(clock),
86     .switch_buffer(switch_buffer),
87
88     .write_pixel_count(write_pixel_count),
89     .write_line_count(write_line_count),
90     .write_z(write_z),
91     .write_rgb(write_rgb),
92     .write_noop(pixel_noop),
93     .write_next(pixel_next),
94
95     .read_pixel_count(pixel_count),
96     .read_line_count(line_count),
97     .read_rgb(read_rgb),
98
99     .ram0_data(ram0_data),
100    .ram0_address(ram0_address),
101    .ram0_we_b(ram0_we_b), // ram 0 buss
102
103    .ram1_data(ram1_data),
104    .ram1_address(ram1_address),
105    .ram1_we_b(ram1_we_b) // ram 1 buss
106 );
107
108 wire [`TRIANGLE_BITS+`NORMAL_BITS-1:0] triangle_data;
109 wire triangle_empty, triangle_noop, triangle_next, next_frame;
110 triangle_source ts (reset,
111     clock,
112     model_select,
113     triangle_data,
114     triangle_empty,
115     triangle_noop,
116     triangle_next,
117     next_frame);
118
119 controller cr(
120     .reset(reset),
121     .clock(clock),
122     .blanking(blanking),
123     .empty(pixel_empty),
124     .next_frame(next_frame),
125     .switch_buffer(switch_buffer));
126

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internal.v

```

127
128
129
130 fsm fsm1 (.reset(reset),
131   .clock(clock),
132   .enable(enable),
133   .speed(ball_initial_speed),
134   .paddle_speed(paddle_speed),
135   .up_sync(paddle_up),
136   .down_sync(paddle_down),
137   .paddle_y(paddle_y),
138   .ball_x(ball_x),
139   .ball_y(ball_y));
140
141 wire [`COORD_BITS*3-1:0] translation_vector, light_vector,
142   ball_vector, paddle_vector;
143 wire [9*`TRIG_OUT_BITS-1:0] rotation_matrix, rotor_matrix;
144 wire [`COORD_BITS-1:0] zoom;
145 orienter ornt(
146   reset,
147   clock,
148   mouse0_clock, mouse0_data, mousel_clock, mousel_data, buttons,
149   enable, switch_buffer,
150   paddle_y, ball_x, ball_y,
151   translation_vector,
152   rotation_matrix,
153   light_vector,
154   zoom,
155   rotor_matrix,
156   ball_vector,
157   paddle_vector);
158
159 wire [`TRIANGLE_BITS-1:0] out_triangle;
160 wire out_noop, out_empty, out_next;
161
162 triangle_pipeline tp(
163   .reset(reset),
164   .clock(clock),
165   .in_triangle(triangle_data),
166   .in_noop(triangle_noop),
167   .in_empty(triangle_empty),
168   .in_next(triangle_next),
169   .out_triangle(out_triangle),
170   .out_noop(out_noop),
171   .out_empty(out_empty),
172   .out_next(out_next),
173   .translation_vector(translation_vector),
174   .rotation_matrix(rotation_matrix),
175   .light_vector(light_vector),
176   .zoom(zoom),
177   .rotor_matrix(rotor_matrix),
178   .ball_vector(ball_vector),
179   .paddle_vector(paddle_vector));
180
181 triangle_shader pshdr(
182   .reset(reset),
183   .clock(clock),
184   .triangle_data(out_triangle),
185   .triangle_empty(out_empty),
186   .triangle_noop(out_noop),
187   .triangle_next(out_next),
188   .pixel_data({write_pixel_count,
189     write_line_count,

```

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```

190   write_z, write_rgb}),
191   .pixel_empty(pixel_empty),
192   .pixel_noop(pixel_noop),
193   .pixel_next(pixel_next));
194 endmodule
195
196 module add_rgb(reset, clock, a, b, c);
197   parameter A_SHIFT = 1;
198   parameter B_SHIFT = 1;
199
200   localparam T_WIDTH = 9;
201   input reset, clock;
202   input [23:0] a, b;
203   output [23:0] c;
204
205   reg [23:0] c;
206   wire [23:0] next_c;
207   wire [7:0] a_r, a_g, a_b,
208   b_r, b_g, b_b,
209   c_r, c_g, c_b;
210
211   assign {a_r, a_g, a_b} = a;
212   assign {b_r, b_g, b_b} = b;
213   assign next_c = {c_r, c_g, c_b};
214
215   wire [T_WIDTH-1:0] t_r, t_g, t_b;
216
217   assign t_r = a_r[7-A_SHIFT:0] + b_r[7-B_SHIFT:0];
218   assign t_g = a_g[7-A_SHIFT:0] + b_g[7-B_SHIFT:0];
219   assign t_b = a_b[7-A_SHIFT:0] + b_b[7-B_SHIFT:0];
220
221   assign c_r = t_r > 255 ? 255 : t_r[7:0];
222   assign c_g = t_g > 255 ? 255 : t_g[7:0];
223   assign c_b = t_b > 255 ? 255 : t_b[7:0];
224
225   always @(posedge clock)
226     if (reset)
227       c <= 24'b0;
228     else
229       c <= next_c;
230 endmodule
231
232 module controller(reset, clock, blanking, empty, next_frame, switch_buffer);
233   input reset;
234   input clock;
235   input blanking;
236   input empty;
237   output next_frame;
238   output switch_buffer;
239
240   reg [2:0] state;
241   localparam IDLE = 3'd0;
242   localparam WAIT_FOR_BLANKING = 3'd1;
243   localparam SEND_SIGNALS = 3'd2;
244   localparam NEITHER_LOW = 3'd3;
245   localparam EMPTY_LOW = 3'd4;
246   localparam BLANKING_LOW = 3'd5;
247
248   reg [2:0] next_state;
249
250   always @ (posedge clock)
251     if (reset)
252       state <= IDLE;

```

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```

internal.v
_____
253      else
254          state <= next_state;
255
256      always @ (state or blanking or empty) begin
257          next_state = state;
258          case (state)
259              IDLE:
260                  if (empty)
261                      if (blanking)
262                          next_state = SEND_SIGNALS;
263                  else
264                      next_state = WAIT_FOR_BLANKING;
265
266              WAIT_FOR_BLANKING:
267                  if (blanking)
268                      next_state = SEND_SIGNALS;
269              SEND_SIGNALS:
270                  if (!empty && !blanking)
271                      next_state = IDLE;
272                  else if (!empty)
273                      next_state = EMPTY_LOW;
274                  else if (!blanking)
275                      next_state = BLANKING_LOW;
276                  else
277                      next_state = NEITHER_LOW;
278              NEITHER_LOW:
279                  if (!empty && !blanking)
280                      next_state = IDLE;
281                  else if (!empty)
282                      next_state = EMPTY_LOW;
283                  else if (!blanking)
284                      next_state = BLANKING_LOW;
285              EMPTY_LOW:
286                  if (!blanking)
287                      next_state = IDLE;
288              BLANKING_LOW:
289                  if (!empty)
290                      next_state = IDLE;
291          endcase
292      end
293
294      assign next_frame = (state == SEND_SIGNALS);
295      assign switch_buffer = (state == SEND_SIGNALS);
296
297  endmodule
298
299 `timescale 1ns / 1ps
300 module delay(reset, clock, in, out);
301     input reset;
302     input clock;
303
304     parameter DELAY = 2;
305
306     input in;
307     output out;
308
309     reg [DELAY-1:0] data;
310
311     assign out = data[DELAY-1];
312
313     always @ (posedge clock) begin
314         if (reset)

```

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internal.v
_____
316             data <= {DELAY{1'b0}};
317         else
318             data <= {data[DELAY - 2: 0], in};
319     end
320
321 endmodule
322
323 // VGA Module from Problem Set 3
324 module vga (reset, pixel_clock, sync_b,
325             blank_b, hsync, vsync, pixel_count,
326             line_count, enable, blanking);
327
328     input reset; // system reset
329     input pixel_clock; // 31.5 MHz pixel clock
330     output sync_b; // hardwired to Vdd
331     output blank_b; // composite blank
332     output hsync; // horizontal sync
333     output vsync; // vertical sync
334     output [9:0] pixel_count; // number of the current pixel
335     output [9:0] line_count; // number of the current line
336     output enable; // 1-clock enable once per screen refresh
337     output blanking;
338
339 // // 640x480 75Hz parameters
340 // parameter PIXELS = 800;
341 // parameter LINES = 525;
342 // parameter HACTIVE_VIDEO = 640;
343 // parameter HFRONT_PORCH = 16;
344 // parameter HSYNC_PERIOD = 96;
345 // parameter HBACK_PORCH = 48;
346 // parameter VACTIVE_VIDEO = 480;
347 // parameter VFRONT_PORCH = 11;
348 // parameter VSYNC_PERIOD = 2;
349 // parameter VBACK_PORCH = 32;
350 // 640x480, 75Hz 31.500 640 16 96 48 480 11 2 32
351 // 640x480, 60Hz 25.175 640 16 96 48 480 11 2 31
352 // 640x480 60Hz parameters
353 parameter PIXELS = 800;
354 parameter LINES = 524;
355 parameter HACTIVE_VIDEO = 640;
356 parameter HFRONT_PORCH = 16;
357 parameter HSYNC_PERIOD = 96;
358 parameter HBACK_PORCH = 48;
359 parameter VACTIVE_VIDEO = 480;
360 parameter VFRONT_PORCH = 11;
361 parameter VSYNC_PERIOD = 2;
362 parameter VBACK_PORCH = 31;
363
364
365 // current pixel count
366 reg [9:0] pixel_count = 10'b0;
367 reg [9:0] line_count = 10'b0;
368
369 reg hsync = 1'b1;
370 reg vsync = 1'b1;
371 reg blank_b = 1'b1;
372 reg enable = 1'b0;
373 reg blanking;
374 wire sync_b; // connected to Vdd
375
376 wire pixel_clock;
377 wire [9:0] next_pixel_count;
378 wire [9:0] next_line_count;

```

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```

internal.v
379   wire next_enable;
380
381   always @ (posedge pixel_clock)
382     begin
383       if (reset)
384         begin
385           pixel_count <= 10'b0;
386           line_count <= 10'b0;
387           hsync <= 1'b1;
388           vsync <= 1'b1;
389           blank_b <= 1'b1;
390           enable <= 1'b0;
391         end
392       else
393         begin
394           pixel_count <= next_pixel_count;
395           line_count <= next_line_count;
396           hsync <=
397             (next_pixel_count < HACTIVE_VIDEO + HFRONT_PORCH) |
398             (next_pixel_count >= HACTIVE_VIDEO+HFRONT_PORCH+
399              HSYNC_PERIOD);
400           vsync <=
401             (next_line_count < VACTIVE_VIDEO+VFRONT_PORCH) |
402             (next_line_count >= VACTIVE_VIDEO+VFRONT_PORCH+
403               VSYNC_PERIOD);
404           // this is the end of hblank and vblank
405           blank_b <=
406             (next_pixel_count < HACTIVE_VIDEO) &
407             (next_line_count < VACTIVE_VIDEO);
408           enable <= next_enable;
409           blanking <=
410             (next_line_count > VACTIVE_VIDEO &&
411               next_line_count < LINES);
412         end
413       end
414
415   // next state is computed with combinational logic
416   assign next_pixel_count =
417     (pixel_count == PIXELS-1) ?
418       10'h000 : pixel_count + 1'b1;
419   assign next_line_count =
420     (pixel_count == PIXELS-1) ?
421       (line_count == LINES-1) ? 10'h000 :
422         line_count + 1'b1 : line_count;
423   // can hardwire composite sync to Vdd.
424   assign sync_b = 1'b1;
425
426   assign next_enable =
427     (pixel_count == 1) && (line_count == VACTIVE_VIDEO - 2);
428
429
430 endmodule
431

```

```

screen_buffer.v
1  `timescale 1ns / 1ps
2  `include "defines.v"
3  module screen_buffer(
4    reset, clock,
5    switch_buffer,
6
7    write_pixel_count, write_line_count,
8    write_z, write_rgb, write_noop, write_next,
9
10   read_pixel_count, read_line_count, read_rgb,
11
12   ram0_data, ram0_address, ram0_we_b, // ram 0 buss
13   raml_data, raml_address, raml_we_b // ram 1 buss
14 );
15   input reset;
16   input clock;
17   input switch_buffer;
18
19   input [9:0] write_pixel_count;
20   input [9:0] write_line_count;
21   input [11:0] write_z;
22   input [23:0] write_rgb;
23   input write_noop;
24   output write_next;
25
26   input [9:0] read_pixel_count;
27   input [9:0] read_line_count;
28   output [23:0] read_rgb;
29
30   inout [35:0] ram0_data;
31   output [18:0] ram0_address;
32   output ram0_we_b;
33
34   inout [35:0] raml_data;
35   output [18:0] raml_address;
36   output raml_we_b;
37
38   // wiring
39   wire [35:0] read_data;
40   wire [18:0] read_address;
41   wire read_we_b;
42
43   wire [18:0] write_address;
44   wire write_we_b;
45   wire hold;
46
47   // state
48   reg ram_select;
49
50   always @(posedge clock)
51     if (reset)
52       ram_select <= 0;
53     else
54       ram_select <= switch_buffer ? !ram_select : ram_select;
55
56   assign {ram0_we_b, raml_we_b} = ram_select ?
57     {read_we_b, write_we_b}:
58       {write_we_b, read_we_b};
59
60   assign {ram0_address, raml_address} = ram_select ?
61     {read_address, write_address}:
62       {write_address, read_address};
63

```

screen_buffer.v

```

64
65 assign read_data = ram_select ? ram0_data: ram1_data;
66
67 zbt_reader reader(reset, clock, read_pixel_count, read_line_count, read_rgb,
68   read_we_b,
69   read_address,
70   read_data);
71
72
73 zbt_out out(reset, clock, write_pixel_count, write_line_count,
74   write_z, write_rgb, write_noop,
75   write_we_b, write_address, ram_select,
76   ram0_data, ram1_data, switch_buffer, write_next);
77 endmodule
78
79 module zbt_out(reset, clock, pixel_count, line_count, pixel_z, rgb, noop,
80   ram_we_b, ram_address, ram_select,
81   ram0_data, ram1_data, switch_buffer, next);
82
83
84 parameter DEFAULT_VALUE = {12'b111111111111, 24'b0};
85 parameter MAX_ADDRESS = `SCREEN_HEIGHT * `SCREEN_WIDTH;
86
87 input reset;
88 input clock;
89 input [9:0] pixel_count;
90 input [9:0] line_count;
91 input [23:0] rgb;
92 input [11:0] pixel_z;
93 input noop;
94 output next;
95
96 output ram_we_b; // physical line to ram we_b
97 output [18:0] ram_address; // physical line to ram address
98 input ram_select;
99
100 inout [35:0] ram0_data; // physical line to ram data
101 inout [35:0] ram1_data; // physical line to ram data
102
103 input switch_buffer;
104
105 // buffer the outputs
106 reg ram_we_b;
107 reg [18:0] ram_address;
108 reg [35:0] ram_data_out;
109 reg next;
110
111 // internal state
112 reg oe;
113 reg [1:0] state;
114
115 localparam CLEARING = 0;
116 localparam WRITING = 1;
117 localparam READING = 2;
118
119 // additional input
120 wire [35:0] ram_data_in = (ram_select) ? ram1_data: ram0_data;
121 assign ram1_data = (oe && ram_select) ? ram_data_out : {36{1'bZ}};
122 assign ram0_data = (oe && !ram_select) ? ram_data_out : {36{1'bZ}};
123
124 // shift registers
125 reg [35:0] ram_data_in0, ram_data_in1, ram_data_in2;
126 reg [18:0] ram_address0, ram_address1, ram_address2;

```

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screen_buffer.v

```

127
128 reg [23:0] rgb0, rgb1, rgb2;
129 reg [11:0] pixel_z0, pixel_z1, pixel_z2;
130 reg noop0, noop1, noop2;
131
132 always @ (posedge clock) begin
133   {ram_data_in0, ram_data_in1, ram_data_in2}
134     <= {ram_data_in, ram_data_in0, ram_data_in1};
135   {ram_address0, ram_address1, ram_address2}
136     <= {ram_address, ram_address0, ram_address1};
137   {rgb0, rgb1, rgb2} <= {rgb, rgb0, rgb1};
138   {pixel_z0, pixel_z1, pixel_z2} <= {pixel_z, pixel_z0, pixel_z1};
139   {noop0, noop1, noop2} <= {noop, noop0, noop1};
140 end
141
142 // next state wires
143 reg next_we;
144 reg [18:0] next_address;
145 reg [35:0] next_data_out;
146 reg next_oe;
147 reg [1:0] next_state;
148
149 always @ (posedge clock)
150   if (reset) begin
151     ram_we_b <= 1'b1;
152     ram_address <= 19'b0;
153     ram_data_out <= 36'b0;
154     oe <= 1'b0;
155     state <= READING;
156   end else begin
157     ram_we_b <= !next_we;
158     ram_address <= next_address;
159     ram_data_out <= next_data_out;
160     oe <= next_oe;
161     state <= next_state;
162   end
163
164 always @ (state, ram_address, switch_buffer, line_count, pixel_count, oe,
165   ram_we_b, ram_data_out, noop, pixel_z2, ram_data_in0, rgb2,
166   noop1, ram_data_in) begin
167   next_state = state;
168   next_address = ram_address;
169   next_oe = oe;
170   next_we = !ram_we_b;
171   next_data_out = ram_data_out;
172   next = 1'b0;
173   case (state)
174     CLEARING:
175       begin
176         next = 1'b0;
177         if (ram_address == MAX_ADDRESS+1) begin
178           next_state = READING;
179           next_data_out = DEFAULT_VALUE;
180           next_oe = 1'b1;
181           next_we = 1'b0;
182         end else begin
183           next_address = ram_address + 1;
184           next_data_out = DEFAULT_VALUE;
185           next_oe = 1'b1;
186           next_we = 1'b1;
187         end
188       WRITING:
189       begin

```

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screen_buffer.v

```

190      next = 1'b1;
191      if (switch_buffer) begin
192          next = 1'b0;
193          next_state = CLEARING;
194          next_address = 19'b0;
195          next_oe = 1'b0;
196          next_we = 1'b1;
197      end else begin
198          next_address =
199              (line_count>=`SCREEN_HEIGHT ||
200               pixel_count>=`SCREEN_WIDTH)
201              ? -1 : line_count * `SCREEN_WIDTH + pixel_count;
202          next_oe = 1'b0;
203          next_we = 1'b0;
204          next_state = READING;
205      end
206  end
207 READING:
208 begin
209     next = 1'b0;
210     if (switch_buffer) begin
211         next_state = CLEARING;
212         next_address = 19'b0;
213         next_oe = 1'b0;
214         next_we = 1'b1;
215     end else begin
216         next_we = !noop0///!noop///1'b1;
217         next_oe = !noop2///!noop1//1'b1;
218         next_data_out = (pixel_z2 > ram_data_in[35:24])
219             ? ram_data_in : {pixel_z2, rgb2};
220         next_state = WRITING;
221     end
222 end
223 endcase
224 end
225 endmodule
226
227 module zbt_reader(
228     reset, clock, pixel_count, line_count, read_rgb,
229     ram_we_b, ram_address, ram_data);
230     input clock;           // system clock
231     input reset;
232     input [9:0] pixel_count;
233     input [9:0] line_count;
234     output [23:0] read_rgb; // data read from memory
235
236     output ram_we_b;      // physical line to ram we_b
237     output [18:0] ram_address; // physical line to ram address
238     input [35:0] ram_data; // physical line to ram data
239
240     assign ram_we_b = 1'b1;
241     reg [18:0] ram_address;
242     reg [23:0] read_rgb, read_rgb0, read_rgb1;
243
244     wire [18:0] next_address =
245         (line_count>=`SCREEN_HEIGHT ||
246          pixel_count>=`SCREEN_WIDTH)
247          ? -1 : line_count * `SCREEN_WIDTH + pixel_count;
248     always @ (posedge clock)
249     if (reset) begin
250         ram_address <= 36'b0;
251         read_rgb <= 36'b0;
252         read_rgb0 <= 36'b0;

```

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screen_buffer.v

```

253     read_rgb1 <= 36'b0;
254     end else begin
255         ram_address <= next_address;
256         {read_rgb, read_rgb0, read_rgb1}
257             <= {read_rgb0, read_rgb1, ram_data[23:0]};
258     end
259 endmodule

```

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```

triangle_shader.v
1 `timescale 1ns / 1ps
2 `include "defines.v"
3 module triangle_shader(
4   reset, clock, triangle_data, triangle_empty,
5   triangle_noop, triangle_next,
6   pixel_data, pixel_empty, pixel_noop, pixel_next);
7 // input
8   input reset;
9   input clock;
10  input [`TRIANGLE_BITS-1:0] triangle_data;
11  input triangle_empty;
12  input triangle_noop;
13  output triangle_next;
14
15 // output
16  output [`PIXEL_BITS-1:0] pixel_data;
17  output pixel_empty;
18  output pixel_noop;
19  input pixel_next;
20
21 // register some outputs
22 reg [`PIXEL_BITS-1:0] pixel_data;
23 reg pixel_empty;
24 reg triangle_next;
25
26 // register state
27 reg [1:0] state;
28 localparam RHOMBUS_A = 0;
29 localparam RHOMBUS_B = 1;
30 localparam NEXT = 2;
31
32 // inputs to rhombus shader
33 reg [`RHOMBUS_BITS-1:0] rhombus_data;
34 reg rhombus_noop;
35 wire rhombus_next;
36
37 // next state values
38 reg [1:0] next_state;
39 wire [`PIXEL_BITS-1:0] next_pixel_data;
40 wire [`POINT_BITS-1:0] next_point_data;
41 reg next_pixel_empty;
42 reg next_rhombus_noop;
43 reg [`RHOMBUS_BITS-1:0] next_rhombus_data;
44
45 rhombus_shader rs (reset, clock, rhombus_data, rhombus_noop, rhombus_next,
46   next_point_data, pixel_noop, pixel_next);
47
48 // split up rhombus_painter inputs
49 wire [`RHOMBUS_BITS-1:0] rhombus_a, rhombus_b;
50 wire [`COORD_BITS-1:0] a_min_x, a_min_y, a_max_x, a_max_y,
51   b_min_x, b_min_y, b_max_x, b_max_y,
52   a_z, b_z;
53 wire [`LINE_BITS-1:0] a_left_line, a_right_line, b_left_line, b_right_line;
54 assign rhombus_a = {a_left_line, a_right_line,
55   a_min_x, a_min_y, a_max_x, a_max_y, a_z};
56 assign rhombus_b = {b_left_line, b_right_line,
57   b_min_x, b_min_y, b_max_x, b_max_y, b_z};
58
59 // split up triangle_data inputs
60 wire [`POINT_BITS-1:0] top_point, left_point,
61   right_point, bottom_point, mid_point;
62 wire [`COORD_BITS-1:0] top_x, top_y, top_z,
63   left_x, left_y, left_z, right_x, right_y, right_z,

```

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```

triangle_shader.v
64
65 wire [`COLOR_BITS-1:0] rgb;
66 assign {top_point, left_point, right_point, rgb} = triangle_data;
67 assign {top_x, top_y, top_z} = top_point;
68 assign {left_x, left_y, left_z} = left_point;
69 assign {right_x, right_y, right_z} = right_point;
70 reg [`COLOR_BITS-1:0] rgb0;
71
72 // find mid/bottom point
73 wire left_bellow_right;
74 signed_lt #(`COORD_BITS) slt (left_y, right_y, left_bellow_right);
75 assign {bottom_point, mid_point} = left_bellow_right ?
76   {left_point, right_point} : {right_point, left_point};
77 assign {bottom_x, bottom_y, bottom_z} = bottom_point;
78 assign {mid_x, mid_y, mid_z} = mid_point;
79
80 //assign min/max
81 wire [`COORD_BITS-1:0] min_x, max_x;
82 signed_outer3 #(`COORD_BITS) so3 (left_x, top_x, right_x, min_x, max_x);
83
84 assign a_min_x = min_x;
85 assign b_min_x = min_x;
86 assign a_max_x = max_x;
87 assign b_max_x = max_x;
88
89 assign a_max_y = top_y;
90 assign a_min_y = mid_y;
91 assign b_max_y = mid_y;
92 assign b_min_y = bottom_y;
93
94 // calculate average z (kind of)
95 wire [`COORD_BITS+1:0] z_sum;
96 wire [`COORD_BITS-1:0] average_z;
97 signed_add3 #(`COORD_BITS) sa3 (top_z, left_z, right_z, z_sum);
98 assign average_z = z_sum[`COORD_BITS+1:2];
99 assign a_z = average_z;
100 assign b_z = average_z;
101
102 // assign lines
103 assign a_left_line = {top_x, top_y, left_x, left_y};
104 assign a_right_line = {top_x, top_y, right_x, right_y};
105 assign b_left_line = left_bellow_right ?
106   {top_x, top_y, left_x, left_y} : {left_x, left_y, right_x, right_y};
107 assign b_right_line = left_bellow_right ?
108   {right_x, right_y, left_x, left_y} : {top_x, top_y, right_x, right_y};
109
110 //
111 always @ (posedge clock)
112   if (reset) begin
113     state <= NEXT;
114     rhombus_data <= {(`RHOMBUS_BITS){1'b0}};
115     rhombus_noop <= 1'b1;
116     pixel_empty <= 1'b0;
117     pixel_data <= {(`PIXEL_BITS){1'b0}};
118     rgb0 <= 24'b0;
119   end
120   else begin
121     state <= next_state;
122     rhombus_data <= next_rhombus_data;
123     rhombus_noop <= next_rhombus_noop;
124     pixel_empty <= next_pixel_empty;
125     pixel_data <= next_pixel_data;
126     rgb0 <= rgb;
127   end

```

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triangle_shader.v

```

127
128 // calculate next values
129 point_to_pixel ptp (next_point_data, rgb0, next_pixel_data);
130   always @ (state, rhombus_noop, rhombus_data, rhombus_a, rhombus_b,
131             rhombus_next, triangle_empty, triangle_noop) begin
132     next_state = state;
133     next_pixel_empty = 1'b0;
134     next_rhombus_noop = rhombus_noop;
135     next_rhombus_data = rhombus_data;
136     triangle_next = 1'b0;
137
138     case (state)
139       RHOMBUS_A:
140         if (rhombus_next) begin
141           next_state = RHOMBUS_B;
142           next_rhombus_data = rhombus_b;
143         end
144       RHOMBUS_B:
145         if (rhombus_next) begin
146           next_state = NEXT;
147           next_rhombus_noop = 1'b1;
148           triangle_next = 1'b1;
149         end
150       NEXT:
151         begin
152           if (triangle_empty) begin
153             triangle_next = 1'b1;
154             next_pixel_empty = 1'b1;
155           end else if (triangle_noop) begin
156             triangle_next = 1'b1;
157           end else if (rhombus_next) begin
158             next_state = RHOMBUS_A;
159             next_rhombus_data = rhombus_a;
160             next_rhombus_noop = 1'b0;
161           end
162         end
163       endcase
164     end
165   endmodule
166
167 module point_to_pixel(point_data, rgb, pixel_data/*, pixel_noop*/);
168   input [`POINT_BITS-1:0] point_data;
169   input [`COLOR_BITS-1:0] rgb;
170   output [`PIXEL_BITS-1:0] pixel_data;
171   //output pixel_noop;
172
173   wire [`COORD_BITS-1:0] unsigned_x, unsigned_z;
174   wire [`COORD_BITS-1:0] point_x, point_y, point_z;
175   wire [`COORD_BITS:0] neg_y, unsigned_y;
176
177   assign {point_x, point_y, point_z} = point_data;
178
179   signed_navigate #(`COORD_BITS) sn (point_y, neg_y);
180
181   signed_to_unsigned #(`COORD_BITS, (`SCREEN_WIDTH/2))
182     stux (point_x, unsigned_x);
183   signed_to_unsigned #(`COORD_BITS+1, (`SCREEN_HEIGHT/2))
184     stuy (neg_y, unsigned_y);
185   signed_to_unsigned #(`COORD_BITS, {1'b1, {`COORD_BITS-1{1'b0}}})
186     stuz (point_z, unsigned_z);
187
188   assign pixel_data = {unsigned_x[9:0], unsigned_y[9:0],

```

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triangle_shader.v

```

190   unsigned_z[`COORD_BITS-1:`COORD_BITS-12], rgb};
191   //assign pixel_noop = (unsigned_x[`COORD_BITS-1:10] != 0) ||
192   //                  (unsigned_y[`COORD_BITS-1:10] != 0);
193 endmodule
194
195 `include "defines.v"
196 module rhombus_shader(
197   reset, clock, rhombus_data, rhombus_noop, rhombus_next,
198   next_point_data, point_noop, point_next);
199   input reset;
200   input clock;
201
202   input [`RHMOMBUS_BITS-1:0] rhombus_data;
203   input rhombus_noop;
204   output rhombus_next;
205
206   output [`POINT_BITS-1:0] next_point_data;
207   output point_noop;
208   input point_next;
209
210   // split up rhombus data
211   wire [`LINE_BITS-1:0] left_line, right_line;
212   wire [`COORD_BITS-1:0] min_x, min_y, max_x, max_y, rhombus_z;
213   assign {left_line, right_line,
214             min_x, min_y,
215             max_x, max_y, rhombus_z} = rhombus_data;
216
217   // register point data output
218   reg [`COORD_BITS-1:0] point_x, point_y, point_z;
219   reg point_noop;
220
221   // state
222   reg state;
223   localparam IDLE = 0;
224   localparam PAINTING = 1;
225
226   // next state variables
227   reg [`COORD_BITS-1:0] next_point_x, next_point_y, next_point_z;
228   assign next_point_data = {next_point_x, next_point_y, next_point_z};
229   reg next_point_noop, next_state;
230   reg rhombus_next;
231
232   wire [`COORD_BITS:0] inc_x, inc_y;
233   signed_inc #(`COORD_BITS) six(point_x, inc_x);
234   signed_inc #(`COORD_BITS) siy(point_y, inc_y);
235
236   always @ (posedge clock)
237     if (reset) begin
238       point_x = {(`POINT_BITS){1'b0}};
239       point_y = {(`POINT_BITS){1'b0}};
240       point_z = {(`POINT_BITS){1'b0}};
241       state = IDLE;
242       point_noop = 1'b1;
243     end else begin
244       point_x = next_point_x;
245       point_y = next_point_y;
246       point_z = next_point_z;
247       state = next_state;
248       point_noop = next_point_noop;
249     end
250
251   wire before_left_line;
252   wire after_right_line;

```

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triangle_shader.v

```

253
254     always @ (state, rhombus_noop, point_next, point_y, max_y, point_x,
255                 min_x, min_y, rhombus_z, max_x, max_y, point_z, point_noop,
256                 before_left_line, after_right_line, inc_y, inc_x) begin
257         next_state = state;
258         next_point_x = point_x;
259         next_point_y = point_y;
260         next_point_z = point_z;
261         next_point_noop = point_noop;
262         rhombus_next = 1'b0;
263         case (state)
264             IDLE:
265                 if (rhombus_noop) begin
266                     rhombus_next = 1'b1;
267                     next_point_noop = 1'b1;
268                 end else begin
269                     next_state = PAINTING;
270                     next_point_x = min_x;
271                     next_point_y = min_y;
272                     next_point_z = rhombus_z;
273                     next_point_noop = before_left_line || after_right_line;
274                 end
275             PAINTING:
276                 if (point_next) begin
277                     if (point_y == max_y) begin
278                         next_state = IDLE;
279                         rhombus_next = 1'b1;
280                         next_point_noop = 1'b1;
281                     end else if (point_x == max_x) begin
282                         next_point_x = min_x;
283                         next_point_y = inc_y[`COORD_BITS-1:0];
284                         next_point_noop = before_left_line || after_right_line;
285                     end else begin
286                         next_point_x = inc_x[`COORD_BITS-1:0];
287                         next_point_noop = before_left_line || after_right_line;
288                     end
289                 end
290             endcase
291         end
292
293     //point_left_of_line
294     wire before_right_line;
295
296     point_left_of_line p0l1
297         (next_point_x, next_point_y, left_line, before_left_line);
298     point_left_of_line p0l2
299         (next_point_x, next_point_y, right_line, before_right_line);
300
301     assign after_right_line = ~before_right_line;
302 endmodule
303
304 module point_left_of_line(p_x, p_y, line, out);
305     input [`COORD_BITS-1:0] p_x, p_y;
306     input [`LINE_BITS-1:0] line;
307     output out;
308
309     wire [`COORD_BITS-1:0] a_x, a_y, b_x, b_y;
310     assign {a_x, a_y, b_x, b_y} = line;
311
312
313     wire [`COORD_BITS:0] pxmax, aymby, pymay, axmbx;
314
315     signed_subtract #(`COORD_BITS) ssl (p_x, a_x, pxmax);

```

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triangle_shader.v

```

316     signed_subtract #(`COORD_BITS) ss2 (a_y, b_y, aymby);
317     signed_subtract #(`COORD_BITS) ss3 (p_y, a_y, pymay);
318     signed_subtract #(`COORD_BITS) ss4 (a_x, b_x, axmbx);
319
320     wire [2*(`COORD_BITS)+1:0] left, right;
321     signed_multiply #(`COORD_BITS+1, `COORD_BITS+1) sml (pxmax, aymby, left);
322     signed_multiply #(`COORD_BITS+1, `COORD_BITS+1) sm2 (pymay, axmbx, right);
323
324     wire left_lt_right, ay_lt_by;
325     signed_lt #(2*(`COORD_BITS)+2) slt1 (left, right, left_lt_right);
326     signed_lt #(`COORD_BITS) slt2 (a_y, b_y, ay_lt_by);
327
328     assign out = left_lt_right ^ ay_lt_by;
329 endmodule
330

```

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triangle_pipeline.v

```

1 `include "defines.v"
2 module triangle_pipeline(
3   reset, clock,
4   in_triangle, in_noop, in_empty, in_next,
5   out_triangle, out_noop, out_empty, out_next,
6   translation_vector, rotation_matrix, light_vector, zoom,
7   rotor_matrix, ball_vector, paddle_vector);
8   input reset;
9   input clock;
10
11 // incomming triangles
12 input [`TRIANGLE_BITS+`NORMAL_BITS-1:0] in_triangle;
13 input in_empty;
14 input in_noop;
15 output in_next;
16
17 // outgoing triangles
18 output [`TRIANGLE_BITS-1:0] out_triangle;
19 output out_empty;
20 output out_noop;
21 input out_next;
22
23 // control signals
24 input [3*`COORD_BITS-1:0] translation_vector, ball_vector,
25   paddle_vector, light_vector;
26 input [9*`TRIG_OUT_BITS-1:0] rotation_matrix, rotor_matrix;
27 input [`COORD_BITS-1:0] zoom;
28
29 // next propagation wiring
30 assign in_next = out_next;
31
32 // internal wiring
33
34 wire [`NORMAL_BITS-1:0] next_normal0, next_normal1, next_normal2, next_normal3,
35   next_normal4, next_normal5, next_normal6,
36   normal0, normal1, normal2, normal3, normal4,
37   normal5, normal6;
38
39 wire [`TRIANGLE_BITS-1:0]
40   next_data0, next_data1, next_data2, next_data3, next_data4, next_data5,
41   next_data6, next_data7, next_data8, next_data9, next_data10, next_data11,
42   next_data12, next_data13,
43   data0, data1, data2, data3, data4, data5, data6, data7, data8, data9,
44   data10, data11, data12, data13;
45
46 wire next_noop0, next_noop1, next_noop2, next_noop3, next_noop4, next_noop5,
47   next_noop6, next_noop7, next_noop8, next_noop9, next_noop10, next_noop11,
48   next_noop12, next_noop13,
49   noop0, noop1, noop2, noop3, noop4, noop5, noop6, noop7, noop8, noop9,
50   noop10, noop11, noop12, noop13,
51   empty0, empty1, empty2, empty3, empty4, empty5, empty6, empty7, empty8,
52   empty9, empty10, empty11, empty12, empty13;
53
54 assign {data0, normal0} = in_triangle;
55 assign noop0 = in_noop;
56 assign empty0 = in_empty;
57
58 pipeline_register #(`TRIANGLE_BITS+`NORMAL_BITS) pr0
59   (reset, clock, out_next, {data0,normal0}, noop0, empty0,
60   {data1, normal1}, noop1, empty1);
61
62 wire [`TRIANGLE_BITS-1:0] optdata2;
63 wire [`NORMAL_BITS-1:0] optnormal2;
64 wire optnoop2, optempty2;

```

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```

64
65   rotation_block b1
66     (data1, normal1, next_data1, next_normal1, next_noop1, rotor_matrix);
67   pipeline_register #(`TRIANGLE_BITS+`NORMAL_BITS) pr1
68     (reset, clock, out_next, {data1,normal1}, noop1, empty1,
69     {data2, normal2}, noop2, empty2);
70   pipeline_register #(`TRIANGLE_BITS+`NORMAL_BITS) pr1_opt
71     (reset, clock, out_next, {next_data1,next_normal1}, next_noop1, empty1,
72     {optdata2, optnormal2}, optnoop2, optempty2);
73
74   opt_block #(`ROTOR_COLOR) b2
75     (optdata2, optnormal2, optnoop2, data2, normal2,
76     next_data2, next_normal2, next_noop2);
77   pipeline_register #(`TRIANGLE_BITS+`NORMAL_BITS) pr2
78     (reset, clock, out_next, {next_data2,next_normal2}, next_noop2||noop2, empty2,
79     {data3, normal3}, noop3, empty3);
80
81   opt_translation_block #(`BALL_COLOR) b3 (data3, next_data3, next_noop3, ball_vector);
82
83 pipeline_register #(`TRIANGLE_BITS+`NORMAL_BITS) pr3
84   (reset, clock, out_next, {next_data3, normal3}, next_noop3||noop3, empty3,
85     {data4, normal4}, noop4, empty4);
86
87   opt_translation_block #(`PADDLE_COLOR) b4
88     (data4, next_data4, next_noop4, paddle_vector);
89   pipeline_register #(`TRIANGLE_BITS+`NORMAL_BITS) pr4
90     (reset, clock, out_next, {next_data4, normal4}, next_noop4||noop4, empty4,
91     {data5, normal5}, noop5, empty5);
92
93   rotation_block b5
94     (data5, normal5, next_data5, next_normal5, next_noop5, rotation_matrix);
95   pipeline_register #(`TRIANGLE_BITS+`NORMAL_BITS) pr5
96     (reset, clock, out_next, {next_data5,next_normal5}, next_noop5||noop5, empty5,
97     {data6, normal6}, noop6, empty6);
98
99   wire [9:0] next_change, change;
100  light_block b6 (data6, normal6, next_data6, next_change, next_noop6, light_vector);
101  pipeline_register #(`TRIANGLE_BITS+10) pr6
102    (reset, clock, out_next, {next_data6, next_change}, next_noop6||noop6, empty6,
103    {data7, change}, noop7, empty7);
104
105  light_block1 b7 (data7, change, next_data7, next_noop7);
106  pipeline_register #(`TRIANGLE_BITS) pr7
107    (reset, clock, out_next, next_data7, next_noop7||noop7, empty7,
108    {data8, noop8, empty8});
109
110  normal_block b8 (data8, next_data8, next_noop8);
111  pipeline_register #(`TRIANGLE_BITS) pr8
112    (reset, clock, out_next, next_data8, next_noop8||noop8, empty8,
113    {data9, noop9, empty9});
114
115  reorder_block b9 (data9, next_data9, next_noop9);
116  pipeline_register #(`TRIANGLE_BITS) pr9
117    (reset, clock, out_next, next_data9, next_noop9||noop9, empty9,
118    {data10, noop10, empty10});
119
120  zoom_block b10 (data10, next_data10, next_noop10, zoom);
121  pipeline_register #(`TRIANGLE_BITS) pr10
122    (reset, clock, out_next, next_data10, next_noop10||noop10, empty10,
123    {data11, noop11, empty11});
124
125  translation_block b11 (data11, next_data11, next_noop11, translation_vector);
126  pipeline_register #(`TRIANGLE_BITS) pr11
127    (reset, clock, out_next, next_data11, next_noop11||noop11, empty11),

```

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```

triangle_pipeline.v
126      data12, noop12, empty12);
127
128 wire [4*(`COORD_BITS)-1:0] next_extrema, extrema;
129 keep_visible_block0 b12 (data12, next_data12, next_extrema, next_noop12);
130 pipeline_register #(`TRIANGLE_BITS+(4*(`COORD_BITS))) pr12
131   (reset, clock, out_next, {next_data12, next_extrema},
132    next_noop12||noop12, empty12,
133    {data13, extrema}, noop13, empty13);
134
135 keep_visible_block1 b13 (data13, extrema, next_data13, next_noop13);
136 pipeline_register #(`TRIANGLE_BITS) pr13
137   (reset, clock, out_next, next_data13, next_noop13||noop13, empty13,
138    out_triangle, out_noop, out_empty);
139
140 endmodule
141
142 module keep_visible_block0(in_triangle, out_triangle, out_extrema, out_noop);
143   input [`TRIANGLE_BITS-1:0] in_triangle;
144
145 // outgoing triangles
146 output [`TRIANGLE_BITS-1:0] out_triangle;
147 output [4*(`COORD_BITS)-1:0] out_extrema;
148 output out_noop;
149
150 // split up inputs
151 wire [`POINT_BITS-1:0] in_a, in_b, in_c;
152 wire [`COORD_BITS-1:0] a_x, a_y, a_z, b_x, b_y, b_z, c_x, c_y, c_z;
153 wire [`COLOR_BITS-1:0] in_rgb;
154
155 assign {in_a, in_b, in_c, in_rgb} = in_triangle;
156 assign {a_x, a_y, a_z} = in_a;
157 assign {b_x, b_y, b_z} = in_b;
158 assign {c_x, c_y, c_z} = in_c;
159 assign out_triangle = in_triangle;
160
161 // compare the y coordinates
162 wire [`COORD_BITS-1:0] min_x, max_x, min_y, max_y;
163
164 signed_outer3 #(`COORD_BITS) sox (a_x, b_x, c_x, min_x, max_x);
165 signed_outer3 #(`COORD_BITS) soy (a_y, b_y, c_y, min_y, max_y);
166
167 assign out_extrema = {min_x, max_x, min_y, max_y};
168
169 assign out_noop = 0;
170 endmodule
171
172 module keep_visible_block1(in_triangle, in_extrema, out_triangle, out_noop);
173   input [`TRIANGLE_BITS-1:0] in_triangle;
174   input [4*(`COORD_BITS)-1:0] in_extrema;
175
176 // outgoing triangles
177 output [`TRIANGLE_BITS-1:0] out_triangle;
178 output out_noop;
179
180 // split up inputs
181 assign out_triangle = in_triangle;
182
183 // compare the y coordinates
184 wire [`COORD_BITS-1:0] min_x, max_x, min_y, max_y;
185 assign {min_x, max_x, min_y, max_y} = in_extrema;
186
187 wire slt0, slt1, slt2, slt3;
188 signed_lt #(`COORD_BITS) slt_0 (max_x, -(`SCREEN_WIDTH/2), slt0);

```

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```

triangle_pipeline.v
189   signed_lt #(`COORD_BITS) slt_1 ((`SCREEN_WIDTH/2), min_x, slt1);
190   signed_lt #(`COORD_BITS) slt_2 (max_y, -(`SCREEN_HEIGHT/2), slt2);
191   signed_lt #(`COORD_BITS) slt_3 ((`SCREEN_HEIGHT/2), min_y, slt3);
192
193 // assing noop output
194 assign out_noop = 0://slt0||slt1||slt2||slt3;
195
196 endmodule
197
198 module light_block0(
199   in_triangle, in_normal, out_triangle, out_change, out_noop, light_vector);
200   input [`TRIANGLE_BITS-1:0] in_triangle;
201   input [`NORMAL_BITS-1:0] in_normal;
202
203 // outgoing triangles
204 output [`TRIANGLE_BITS-1:0] out_triangle;
205 output [9:0] out_change;
206 output out_noop;
207
208 input [3*`COORD_BITS-1:0] light_vector;
209
210 // split up inputs and outputs
211 assign out_triangle = in_triangle;
212 assign out_noop = 0;
213
214 wire [(2*`COORD_BITS+2)-1:0] correlation;
215
216 dot_product #(`COORD_BITS, `COORD_BITS) dpl (in_normal, light_vector, correlation);
217
218 assign out_change = correlation[2*`COORD_BITS-1:2*`COORD_BITS-10];
219 endmodule
220
221 module light_block1(in_triangle, in_change, out_triangle, out_noop);
222   input [`TRIANGLE_BITS-1:0] in_triangle;
223   input [9:0] in_change;
224
225 // outgoing triangles
226 output [`TRIANGLE_BITS-1:0] out_triangle;
227 output out_noop;
228
229 // split up inputs and outputs
230 wire [7:0] out_r, out_g, out_b, in_r, in_g, in_b;
231 wire [3*`POINT_BITS-1:0] in_points;
232 assign {in_points, in_r, in_g, in_b} = in_triangle;
233 assign out_triangle = {in_points, out_r, out_g, out_b};
234 assign out_noop = 0;
235
236 wire [10:0] temp_r, temp_g, temp_b;
237
238 signed_add #(10) sar ({2'b0, in_r}, in_change, temp_r);
239 signed_add #(10) sag ({2'b0, in_g}, in_change, temp_g);
240 signed_add #(10) sab ({2'b0, in_b}, in_change, temp_b);
241
242 wire [10:0] bound_r, bound_g, bound_b;
243
244 signed_bound #(11, 255, 0) sbr (temp_r, bound_r);
245 signed_bound #(11, 255, 0) sbg (temp_g, bound_g);
246 signed_bound #(11, 255, 0) sbb (temp_b, bound_b);
247
248 assign out_r = bound_r[7:0];
249 assign out_g = bound_g[7:0];
250 assign out_b = bound_b[7:0];
251
252 endmodule

```

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```

triangle_pipeline.v
_____
252 module normal_block(in_triangle, out_triangle, out_noop);
253   input [`TRIANGLE_BITS-1:0] in_triangle;
254
255   // outgoing triangles
256   output [`TRIANGLE_BITS-1:0] out_triangle;
257   //output [3*(2*`COORD_BITS+3)-1:0] out_normal;
258
259   output out_noop;
260
261   // split up inputs and outputs
262   wire [`POINT_BITS-1:0] in_a, in_b, in_c;
263   wire [`COLOR_BITS-1:0] in_rgb;
264
265   assign {in_a, in_b, in_c, in_rgb} = in_triangle;
266   assign out_triangle = in_triangle;
267
268
269   wire [3*(`COORD_BITS+1)-1:0] a_to_b, a_to_c;
270   vector_subtract #(`COORD_BITS) vs_1 (in_b, in_a, a_to_b);
271   vector_subtract #(`COORD_BITS) vs_2 (in_c, in_a, a_to_c);
272
273   wire [(2*`COORD_BITS+3)-1:0] n_x, n_y, n_z;
274   cross_product #(`COORD_BITS+1, `COORD_BITS+1) cp (a_to_b, a_to_c, {n_x, n_y, n_z});
275
276   assign out_noop = n_z[(2*`COORD_BITS+3)-1];
277   //assign out_normal = {n_x, n_y, n_z};
278 endmodule
279
280 module opt_block(
281   opt_triangle, opt_normal, opt_noop, in_triangle, in_normal,
282   out_triangle, out_normal, out_noop);
283   parameter COLOR = 24'b1;
284
285   input [`TRIANGLE_BITS-1:0] in_triangle, opt_triangle;
286   input [`NORMAL_BITS-1:0] in_normal, opt_normal;
287   input opt_noop;
288
289   // outgoing triangles
290   output [`TRIANGLE_BITS-1:0] out_triangle;
291   output [`NORMAL_BITS-1:0] out_normal;
292   output out_noop;
293
294   assign {out_triangle, out_normal, out_noop} =
295     ((in_triangle[23:0] == COLOR) ||
296      (in_triangle[23:0] == `MIT_RED) ||
297      (in_triangle[23:0] == `MIT_GRAY))?
298     {opt_triangle, opt_normal, opt_noop};
299     {in_triangle, in_normal, 1'b0};
300 endmodule
301
302 module opt_transformation_block(in_triangle, out_triangle, out_noop, translation_vector);
303   parameter COLOR = 24'b1;
304
305   input [`TRIANGLE_BITS-1:0] in_triangle;
306
307   // outgoing triangles
308   output [`TRIANGLE_BITS-1:0] out_triangle;
309   output out_noop;
310
311   input [3*`COORD_BITS-1:0] translation_vector;
312
313   wire [`TRIANGLE_BITS-1:0] out_triangle0;
314   wire out_noop0;

```

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```

triangle_pipeline.v
_____
315
316   translation_block tb (in_triangle, out_triangle0, out_noop0, translation_vector);
317
318   assign {out_triangle, out_noop} =
319     in_triangle[23:0] == COLOR ?
320     {out_triangle0, out_noop0}:
321     {in_triangle, 1'b0};
322 endmodule
323
324 module pipeline_register(
325   reset, clock, next, in_data, in_noop, in_empty, out_data, out_noop, out_empty);
326
327   parameter WIDTH = 1;
328
329   input reset, clock, next, in_noop, in_empty;
330   output out_noop, out_empty;
331
332   input [WIDTH-1:0] in_data;
333   output [WIDTH-1:0] out_data;
334
335   reg out_noop, out_empty;
336   reg [WIDTH-1:0] out_data;
337
338   always @ (posedge clock)
339     if (reset) begin
340       out_data <= {WIDTH{1'b0}};
341       out_noop <= 1'b1;
342       out_empty <= 1'b0;
343     end else if (next) begin
344       out_data <= in_data;
345       out_noop <= in_noop;
346       out_empty <= in_empty;
347     end
348   endmodule
349
350 module reorder_block(in_triangle, out_triangle, out_noop);
351   input [`TRIANGLE_BITS-1:0] in_triangle;
352
353   // outgoing triangles
354   output [`TRIANGLE_BITS-1:0] out_triangle;
355   output out_noop;
356
357   // split up inputs
358   wire [`POINT_BITS-1:0] in_a, in_b, in_c;
359   wire [`COORD_BITS-1:0] a_x, a_y, a_z, b_x, b_y, b_z, c_x, c_y, c_z;
360   wire [`COLOR_BITS-1:0] in_rgb;
361
362   assign {in_a, in_b, in_c, in_rgb} = in_triangle;
363   assign {a_x, a_y, a_z} = in_a;
364   assign {b_x, b_y, b_z} = in_b;
365   assign {c_x, c_y, c_z} = in_c;
366
367   // compare the y coordinates
368   wire a_lt_b, a_lt_c, b_lt_c;
369   signed_lt #(`COORD_BITS) silt0 (a_y, b_y, a_lt_b);
370   signed_lt #(`COORD_BITS) silt1 (a_y, c_y, a_lt_c);
371   signed_lt #(`COORD_BITS) silt2 (b_y, c_y, b_lt_c);
372
373   // assign triangle output
374   reg [`TRIANGLE_BITS-1:0] out_triangle;
375   always @ (a_lt_b, a_lt_c, b_lt_c, in_a, in_b, in_c, in_rgb)
376     if (!a_lt_b && !a_lt_c)
377       out_triangle = {in_a, in_b, in_c, in_rgb};

```

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```

triangle_pipeline.v
_____
378     else if (!b_lt_c)
379         out_triangle = {in_b, in_c, in_a, in_rgb};
380     else
381         out_triangle = {in_c, in_a, in_b, in_rgb};
382
383 // assing noop output
384 assign out_noop = 1'b0;
385 endmodule
386
387 module rotation_block(
388     in_triangle, in_normal,
389     out_triangle, out_normal, out_noop,
390     rotation_matrix);
391
392     input [`TRIANGLE_BITS-1:0] in_triangle;
393     input [`NORMAL_BITS-1:0] in_normal;
394
395 // outgoing triangles
396     output [`TRIANGLE_BITS-1:0] out_triangle;
397     output [`NORMAL_BITS-1:0] out_normal;
398     output out_noop;
399
400     input [9*`TRIG_OUT_BITS-1:0] rotation_matrix;
401
402 // split up inputs and outputs
403     wire [9*`COORD_BITS-1:0] in_m, out_m;
404     wire [9*(`COORD_BITS+`TRIG_OUT_BITS+2)-1:0] temp_m;
405     wire [3*(`COORD_BITS+`TRIG_OUT_BITS+2)-1:0] temp_normal;
406     wire [`COLOR_BITS-1:0] in_rgb, out_rgb;
407
408     assign {in_m, in_rgb} = in_triangle;
409     assign out_triangle = {out_m, out_rgb};
410     assign out_rgb = in_rgb;
411
412     matrix_product #(`COORD_BITS, `TRIG_OUT_BITS)
413         mp (in_m, rotation_matrix, temp_m);
414     matrix_trim #(`COORD_BITS+`TRIG_OUT_BITS+2, `COORD_BITS, `TRIG_OUT_BITS-2)
415         mt (temp_m, out_m, out_noop);
416
417     vector_matrix_product #(`COORD_BITS, `TRIG_OUT_BITS)
418         vmp (in_normal, rotation_matrix, temp_normal);
419     vector_trim #(`COORD_BITS+`TRIG_OUT_BITS+2, `COORD_BITS, `TRIG_OUT_BITS-2)
420         vt (temp_normal, out_normal);
421 endmodule
422
423 module translation_block(
424     in_triangle, out_triangle, out_noop, translation_vector);
425     input [`TRIANGLE_BITS-1:0] in_triangle;
426
427 // outgoing triangles
428     output [`TRIANGLE_BITS-1:0] out_triangle;
429     output out_noop;
430
431     input [3*`COORD_BITS-1:0] translation_vector;
432
433 // split up inputs and outputs
434     wire [9*`COORD_BITS-1:0] in_m, out_m;
435     wire [9*(`COORD_BITS+1)-1:0] temp_m;
436     wire [`COLOR_BITS-1:0] in_rgb, out_rgb;
437
438     assign {in_m, in_rgb} = in_triangle;
439     assign out_triangle = {out_m, out_rgb};
440     assign out_rgb = in_rgb;

```

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```

triangle_pipeline.v
_____
441
442     matrix_subtract #(`COORD_BITS)
443         ms (in_m, {3{translation_vector}}, temp_m);
444     matrix_trim #(`COORD_BITS+1, `COORD_BITS)
445         mt (temp_m, out_m, out_noop);
446 endmodule
447
448 module zoom_block(in_triangle, out_triangle, out_noop, zoom);
449     input [`TRIANGLE_BITS-1:0] in_triangle;
450     input [ `COORD_BITS-1:0] zoom;
451
452     localparam TEMP_MAX = 2*`COORD_BITS-2;
453     localparam TEMP_MIN = `COORD_BITS-2;
454
455 // outgoing triangles
456     output [`TRIANGLE_BITS-1:0] out_triangle;
457     output out_noop;
458
459 // split up inputs
460     wire [ `POINT_BITS-1:0] in_a, in_b, in_c;
461     wire [ `COORD_BITS-1:0] in_a_x, in_a_y, in_a_z,
462         in_b_x, in_b_y, in_b_z,
463         in_c_x, in_c_y, in_c_z;
464     wire [ `COLOR_BITS-1:0] in_rgb;
465
466     assign {in_a, in_b, in_c, in_rgb} = in_triangle;
467     assign {in_a_x, in_a_y, in_a_z} = in_a;
468     assign {in_b_x, in_b_y, in_b_z} = in_b;
469     assign {in_c_x, in_c_y, in_c_z} = in_c;
470
471     wire [ `POINT_BITS-1:0] out_a, out_b, out_c;
472     wire [ `COORD_BITS-1:0] out_a_x, out_a_y, out_a_z,
473         out_b_x, out_b_y, out_b_z,
474         out_c_x, out_c_y, out_c_z;
475     wire [ `COLOR_BITS-1:0] out_rgb;
476
477     assign out_a = {out_a_x, out_a_y, out_a_z};
478     assign out_b = {out_b_x, out_b_y, out_b_z};
479     assign out_c = {out_c_x, out_c_y, out_c_z};
480     assign out_triangle = {out_a, out_b, out_c, out_rgb};
481
482     assign out_rgb = in_rgb;
483     assign out_noop = 0;
484
485     wire [2*`COORD_BITS-1:0] temp_a_x, temp_a_y, temp_a_z,
486         temp_b_x, temp_b_y, temp_b_z,
487         temp_c_x, temp_c_y, temp_c_z;
488
489     signed_multiply #(`COORD_BITS, `COORD_BITS)
490         sm_a_x (in_a_x, zoom, temp_a_x);
491     signed_multiply #(`COORD_BITS, `COORD_BITS)
492         sm_a_y (in_a_y, zoom, temp_a_y);
493     signed_multiply #(`COORD_BITS, `COORD_BITS)
494         sm_a_z (in_a_z, zoom, temp_a_z);
495
496     signed_multiply #(`COORD_BITS, `COORD_BITS)
497         sm_b_x (in_b_x, zoom, temp_b_x);
498     signed_multiply #(`COORD_BITS, `COORD_BITS)
499         sm_b_y (in_b_y, zoom, temp_b_y);
500     signed_multiply #(`COORD_BITS, `COORD_BITS)
501         sm_b_z (in_b_z, zoom, temp_b_z);
502
503     signed_multiply #(`COORD_BITS, `COORD_BITS)

```

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triangle_pipeline.v

```

504     sm_c_x (in_c_x, zoom, temp_c_x);
505     signed_multiply #(`COORD_BITS, `COORD_BITS)
506         sm_c_y (in_c_y, zoom, temp_c_y);
507     signed_multiply #(`COORD_BITS, `COORD_BITS)
508         sm_c_z (in_c_z, zoom, temp_c_z);
509
510     assign out_a_x = temp_a_x[TEMP_MAX:TEMP_MIN];
511     assign out_a_y = temp_a_y[TEMP_MAX:TEMP_MIN];
512     assign out_a_z = temp_a_z[TEMP_MAX:TEMP_MIN];
513
514     assign out_b_x = temp_b_x[TEMP_MAX:TEMP_MIN];
515     assign out_b_y = temp_b_y[TEMP_MAX:TEMP_MIN];
516     assign out_b_z = temp_b_z[TEMP_MAX:TEMP_MIN];
517
518     assign out_c_x = temp_c_x[TEMP_MAX:TEMP_MIN];
519     assign out_c_y = temp_c_y[TEMP_MAX:TEMP_MIN];
520     assign out_c_z = temp_c_z[TEMP_MAX:TEMP_MIN];
521
522 endmodule

```

triangle_source.v

```

`timescale 1ns / 1ps
`include "defines.v"
module triangle_source(
    reset, clock, model_select, triangle_data,
    triangle_empty, triangle_noop, next, next_frame);
parameter ADDRESS_BITS = 12;
input reset;
input clock;
output [`TRIANGLE_BITS + `NORMAL_BITS - 1:0] triangle_data;
output triangle_empty;
output triangle_noop;
input next;
input next_frame;
input [3:0] model_select;
wire [ADDRESS_BITS-1:0] address0, address1;
wire [`TRIANGLE_BITS + `NORMAL_BITS - 1:0] triangle_data0, triangle_data1;
wire triangle_empty0, triangle_empty1,
    triangle_noop0, triangle_noop1;
assign {triangle_data, triangle_empty, triangle_noop} = model_select[0] ?
    {triangle_data0, triangle_empty0, triangle_noop0} :
    {triangle_data1, triangle_empty1, triangle_noop1};
rom_data_source #(`TRIANGLE_BITS + `NORMAL_BITS, ADDRESS_BITS) rds0 (
    .clock(clock),
    .reset(reset),
    .next_address(address0),
    .data(triangle_data0),
    .empty(triangle_empty0),
    .noop(triangle_noop0),
    .next(next),
    .next_frame(next_frame)
);
triangle_data tdo (.addr(address0), .clk(clock), .dout(triangle_data0));
rom_data_source #(`TRIANGLE_BITS + `NORMAL_BITS, ADDRESS_BITS) rds1 (
    .clock(clock),
    .reset(reset),
    .next_address(address1),
    .data(triangle_data1),
    .empty(triangle_empty1),
    .noop(triangle_noop1),
    .next(next),
    .next_frame(next_frame)
);
triangle_data tdi (.addr(address1), .clk(clock), .dout(triangle_data1));
endmodule
module rom_data_source(
    reset, clock, next_address, data,
    empty, noop, next, next_frame);
parameter DATA_BITS = 60;
parameter ADDRESS_BITS = 10;
input reset;
input clock;
output [ADDRESS_BITS-1:0] next_address;
    // save a cycle by outputting next/address
input [DATA_BITS-1:0] data;

```

```

triangle_source.v

64    output empty;
65    output noop;
66    input next;
67    input next_frame;
68
69 //output [ADDRESS_BITS-1:0] max_address;
70
71
72 // register output
73 reg empty;
74 reg noop;
75 reg [ADDRESS_BITS-1:0] address;
76 reg [ADDRESS_BITS-1:0] max_address;
77
78 // wiring
79 wire next_empty;
80 wire next_noop;
81 wire [ADDRESS_BITS-1:0] next_address;
82 wire [ADDRESS_BITS-1:0] next_max_address;
83
84
85 always @ (posedge clock)
86   if (reset) begin
87     address <= 0;
88     empty <= 1'b0;
89     noop <= 1'b1;
90     max_address <= -1;
91   end else if (next_frame) begin
92     address <= 1;
93     empty <= 0;
94     noop <= 1;
95     max_address <= max_address;
96   end else begin
97     address <= next_address;
98     empty <= next_empty;
99     noop <= next_noop;
100    max_address <= next_max_address;
101  end
102
103 assign next_address =
104   ((address <= max_address) && next && !reset) ? address + 1: address;
105 assign next_empty =
106   next_address > max_address;
107 assign next_noop =
108   next_address == 0 || next_empty;
109 assign next_max_address =
110   (address == 0) ? data[ADDRESS_BITS-1:0] : max_address;
111
112 endmodule

```

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```

orienter.v

1 `timescale 1ns / 1ps
2 `include "defines.v"
3 module orienter(reset, clock,
4   mouse0_clock, mouse0_data,
5   mouse1_clock, mouse1_data, buttons,
6   enable, switch_buffer,
7   paddle_y, ball_x, ball_y,
8   translation_vector,
9   rotation_matrix,
10  light_vector,
11  zoom,
12  rotor_matrix,
13  ball_vector,
14  paddle_vector);
15
16 input reset;
17 input clock;
18
19 input mouse0_clock;
20 input mouse0_data;
21 input mouse1_clock;
22 input mouse1_data;
23 input [`NUM_BUTTONS-1:0] buttons;
24
25 input enable;
26 input switch_buffer;
27
28 input [9:0] paddle_y, ball_x, ball_y;
29
30 localparam MAX = {2'b01, {(`COORD_BITS-2){1'b0}}};
31 localparam ZERO = {(`COORD_BITS){1'b0}};
32
33 output [3*`COORD_BITS-1:0] translation_vector, ball_vector,
34   paddle_vector, light_vector;
35 output [9*`TRIG_OUT_BITS-1:0] rotation_matrix, rotor_matrix;
36 output [ `COORD_BITS-1:0] zoom;
37
38 // calculate ball/paddle positions
39 wire [10:0] neg_paddle_y, neg_ball_x, neg_ball_y;
40 signed_subtract #(11) snpy (8, {1'b0, paddle_y}, neg_paddle_y);
41 signed_subtract #(11) snbx ((28+8+16), {1'b0, ball_x}, neg_ball_x);
42 signed_subtract #(11) snby (8, {1'b0, ball_y}, neg_ball_y);
43
44 wire [3*`COORD_BITS-1:0] next_ball_vector, next_paddle_vector;
45 assign next_paddle_vector =
46   {ZERO, {neg_paddle_y[10:0], 1'b0}, ZERO};
47 assign next_ball_vector =
48   {{neg_ball_x[10:0], 1'b0}, {neg_ball_y[10:0], 1'b0}, ZERO};
49
50 assign light_vector = {ZERO, {2'b11, {(`COORD_BITS-2){1'b0}}}, ZERO};
51 // maintain zoom
52 wire [ `COORD_BITS-1:0] temp_zoom;
53 reg [ `COORD_BITS-1:0] zoom;
54 slider #(`COORD_BITS, 1, MAX, MAX/2, 1) sl_zoom
55   (reset, clock, enable,
56    buttons[6]&&buttons[8], buttons[7]&&buttons[8], temp_zoom);
57
58 // maintain transpose
59 wire [ `COORD_BITS-1:0] t_x, t_y, t_z;
60 wire [3*`COORD_BITS-1:0] temp_translation_vector;
61 reg [3*`COORD_BITS-1:0] translation_vector, paddle_vector, ball_vector;
62 assign temp_translation_vector = {t_x, t_y, t_z};
63 assign t_z = 0;

```

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orienter.v

```

64
65     slider #(`COORD_BITS, -13'd1000, 13'd1000, 0, 12'b1) slx
66         (reset, clock, enable, buttons[1]&&buttons[8],
67          buttons[0]&&buttons[8], t_x);
68     slider #(`COORD_BITS, -13'd1000, 13'd1000, 0, 12'b1) sly
69         (reset, clock, enable, buttons[2]&&buttons[8],
70          buttons[3]&&buttons[8], t_y);
71
72
73 // maintain rotation
74 wire [`TRIG_IN_BITS-1:0] theta_x, theta_y, theta_z, theta_rotor;
75 slider #(`TRIG_IN_BITS, -128, 127, 0, 1, 1) sl_theta_x
76     (reset, clock, enable, buttons[1]&&(!buttons[8]),
77      buttons[0]&&(!buttons[8]), theta_x);
78 slider #(`TRIG_IN_BITS, -128, 127, -128, 1, 1) sl_theta_y
79     (reset, clock, enable, buttons[2]&&(!buttons[8]),
80      buttons[3]&&(!buttons[8]), theta_y);
81 slider #(`TRIG_IN_BITS, -128, 127, -128, 1, 1) sl_theta_z
82     (reset, clock, enable, buttons[6]&&(!buttons[8]),
83      buttons[7]&&(!buttons[8]), theta_z);
84 slider #(`TRIG_IN_BITS, -128, 127, 0, 3, 1) sl_theta_rotor
85     (reset, clock, enable, 1'b0, 1'b1, theta_rotor);
86
87 wire [9*`TRIG_OUT_BITS-1:0] temp_rotation_matrix, tempRotor_matrix;
88 reg [9*`TRIG_OUT_BITS-1:0] rotation_matrix, rotor_matrix;
89 thetas_to_matrix ttm
90     (reset, clock, enable, theta_x, theta_y, theta_z,
91      theta_rotor, temp_rotation_matrix, tempRotor_matrix);
92
93 always @ (posedge clock)
94     if (reset) begin
95         rotation_matrix <= { (9*`TRIG_OUT_BITS){1'b0} };
96         rotor_matrix <= { (9*`TRIG_OUT_BITS){1'b0} };
97         translation_vector <= { (3*`COORD_BITS){1'b0} };
98         paddle_vector <= { (3*`COORD_BITS){1'b0} };
99         ball_vector <= { (3*`COORD_BITS){1'b0} };
100        zoom <= MAX/2;
101    end else if (switch_buffer) begin
102        zoom <= temp_zoom;
103        rotation_matrix <= temp_rotation_matrix;
104        rotor_matrix <= tempRotor_matrix;
105        translation_vector <= temp_translation_vector;
106        paddle_vector <= next_paddle_vector;
107        ball_vector <= next_ball_vector;
108    end
109 endmodule
110
111 module slider(reset, clock, enable, up, down, value);
112     parameter WIDTH = 12;
113     parameter MIN_VALUE = -100;
114     parameter MAX_VALUE = 100;
115     parameter START_VALUE = 0;
116     parameter DELTA = 1;
117     parameter WRAP = 0;
118
119     input reset;
120     input clock;
121     input enable;
122     input up;
123     input down;
124     output [WIDTH-1:0] value;
125
126 // registered state

```

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orienter.v

```

127
128     reg [WIDTH-1:0] value;
129
130 // next holders
131     reg [WIDTH-1:0] next_value;
132
133     wire [WIDTH:0] sum, diff;
134     wire max_lt_sum, diff_lt_min;
135
136
137     always @ (posedge clock)
138         if (reset)
139             value <= START_VALUE;
140         else
141             value <= next_value;
142
143     always @ (up or down or value or sum or diff or
144       enable or max_lt_sum or diff_lt_min)
145         begin
146             // by default, don't change state
147             next_value = value;
148             if (enable && (up ^ down)) begin
149                 if (up)
150                     if (!max_lt_sum)
151                         next_value = sum[WIDTH-1:0];
152                     else
153                         next_value = WRAP ? MIN_VALUE : MAX_VALUE;
154                 else
155                     if (!diff_lt_min)
156                         next_value = diff[WIDTH-1:0];
157                     else
158                         next_value = WRAP ? MAX_VALUE : MIN_VALUE;
159             end
160         end
161
162         signed_add #(WIDTH) sa (value, DELTA, sum);
163         signed_subtract #(WIDTH) ss (value, DELTA, diff);
164
165         signed_lt #(WIDTH+1)slt0 (MAX_VALUE, sum, max_lt_sum);
166         signed_lt #(WIDTH+1)slt1 (diff, MIN_VALUE, diff_lt_min);
167
168 endmodule

```

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```

game_fsm.v
1 `timescale 1ns / 1ps
2 module fsm (reset, clock, enable, speed, paddle_speed,
3               up_sync, down_sync, paddle_y, ball_x, ball_y);
4   input reset;
5   input clock;
6   input enable;
7   input [3:0] speed;
8   input [3:0] paddle_speed;
9   input up_sync;
10  input down_sync;
11  output [9:0] paddle_y;
12  output [9:0] ball_x;
13  output [9:0] ball_y;
14
15 // registered state
16 reg [0:0] state;
17 reg [6:0] speed_x;
18 reg [6:0] speed_y;
19 reg dir_x;
20 reg dir_y;
21
22 // Parameters
23 `include "params.v"
24 parameter SPEED_GRADIANT = 3;
25 parameter MAX_DIST = (PADDLE_HEIGHT + BALL_HEIGHT) / 2;
26
27 // States
28 parameter PLAYING = 0;
29 parameter GAME_OVER = 1;
30
31 // next state holders
32 reg [0:0] next_state;
33 reg [6:0] next_speed_x;
34 reg [6:0] next_speed_y;
35 reg next_dir_x;
36 reg next_dir_y;
37
38 // Minor FSMs (Used mainly for abstraction)
39 paddle_fsm paddle_fsm1
40   (clock, reset, enable, up_sync, down_sync, paddle_speed, paddle_y);
41 ball_fsm ball_fsm1
42   (reset, clock, enable, next_speed_x, next_speed_y,
43    next_dir_x, next_dir_y, ball_x, ball_y);
44
45 // state changes synchronously
46 always @ (posedge clock)
47   if (reset) begin
48     state <= PLAYING;
49     speed_x <= {4'b0, speed[1:0]};
50     speed_y <= {4'b0, speed[3:2]};
51     dir_x <= POS;
52     dir_y <= POS;
53   end else begin
54     state <= next_state;
55     speed_x <= next_speed_x;
56     speed_y <= next_speed_y;
57     dir_x <= next_dir_x;
58     dir_y <= next_dir_y;
59   end
60
61 // local wires used for calculation
62 wire [9:0] ball_center_y = ball_y + (BALL_HEIGHT / 2);
63 wire [9:0] paddle_center_y = paddle_y + (PADDLE_HEIGHT / 2);

```

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```

game_fsm.v
64   wire [9:0] dist = ball_center_y < paddle_center_y ?
65                           paddle_center_y - ball_center_y :
66                           ball_center_y - paddle_center_y;
67   wire [3:0] y_speed_change =
68     (SPEED_GRADIANT * dist) / (PADDLE_HEIGHT/2)/*MAX_DIST*/;
69   wire [3:0] x_speed_change = SPEED_GRADIANT - y_speed_change;
70   wire y_speed_change_dir =
71     ball_center_y < paddle_center_y ? NEG : POS;
72
73 // next state calculated asynchronously
74 always @ (enable or state or ball_x or ball_y or
75           speed_x or speed_y or dir_x or dir_y
76           or dist or x_speed_change or y_speed_change
77           or y_speed_change_dir) begin
78   // by default, keep old state
79   next_state = state;
80   next_speed_x = speed_x;
81   next_speed_y = speed_y;
82   next_dir_x = dir_x;
83   next_dir_y = dir_y;
84
85   case (state)
86     PLAYING:
87       if (enable) begin
88         if (dir_x == POS &&
89             ball_x + speed_x >=
90             DISPLAY_WIDTH - BORDER_WIDTH - BALL_WIDTH)
91             next_dir_x = NEG; // Right Wall
92
93         if (dir_y == POS &&
94             ball_y + speed_y >=
95             DISPLAY_HEIGHT - BORDER_HEIGHT - BALL_HEIGHT)
96             next_dir_y = NEG; // Bottom Wall
97
98         if (dir_y == NEG && ball_y <= BORDER_HEIGHT + speed_y)
99             next_dir_y = POS; // Top Wall
100
101        // see if we hit the paddle
102        // (ignoring speed_y, but compensating for speed_x)
103        if (dir_x == NEG
104            && ball_x <= PADDLE_X + PADDLE_WIDTH + speed_x
105            && ball_x + BALL_WIDTH + speed_x >= PADDLE_X
106            && dist < MAX_DIST) begin
107
108          next_dir_x = POS;
109          next_speed_x = speed_x + x_speed_change;
110
111          // since we're using unsigned arithmetic,
112          // speed_y is tricky
113          if (dir_y == y_speed_change_dir)
114            next_speed_y = speed_y + y_speed_change;
115          else if (speed_y < y_speed_change) begin
116            next_speed_y = y_speed_change - speed_y;
117            next_dir_y = ~next_dir_y;
118          end else
119            next_speed_y = speed_y - y_speed_change;
120
121          // Make sure we don't get too close to overflow
122          if (next_speed_x > MAX_SPEED)
123            next_speed_x = MAX_SPEED;
124          if (next_speed_y > MAX_SPEED)
125            next_speed_y = MAX_SPEED;
126        end

```

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<pre> game_fsm.v 127 if (dir_x == NEG && ball_x <= speed_x) begin 128 // Hit left screen 129 next_state = GAME_OVER; 130 next_speed_x = 0; 131 next_speed_y = 0; 132 end 133 end 134 endcase 135 end 136 endmodule 147 module ball_fsm(reset, clock, enable, speed_x, 148 speed_y, dir_x, dir_y, ball_x, ball_y); 149 input reset; 150 input clock; 151 input enable; 152 input [6:0] speed_x; 153 input [6:0] speed_y; 154 input dir_x; 155 input dir_y; 156 output [9:0] ball_x; 157 output [9:0] ball_y; 158 159 // Parameters 160 `include "params.v" 161 162 // State 163 reg [9:0] ball_x; 164 reg [9:0] ball_y; 165 166 // Next State 167 wire [9:0] next_x; 168 wire [9:0] next_y; 169 170 always @ (posedge clock) 171 if (reset) begin 172 ball_x <= PADDLE_X + PADDLE_WIDTH; 173 ball_y <= DISPLAY_HEIGHT / 2; 174 end else begin 175 ball_x <= next_x; 176 ball_y <= next_y; 177 end 178 179 assign next_x = enable ? 180 (dir_x == POS ? ball_x + speed_x : ball_x - speed_x) : 181 ball_x; 182 assign next_y = enable ? 183 (dir_y == POS ? ball_y + speed_y : ball_y - speed_y) : 184 ball_y; 185 endmodule 186 187 module paddle_fsm(clock, reset, enable, up_sync, 188 down_sync, paddle_speed, paddle_y); 189 input clock; </pre>	<pre> game_fsm.v 190 input reset; 191 input enable; 192 input up_sync; 193 input down_sync; 194 input [3:0] paddle_speed; 195 output [9:0] paddle_y; 196 197 // parameters 198 `include "params.v" 199 parameter MIN_Y = BORDER_HEIGHT; 200 parameter MAX_Y = DISPLAY_HEIGHT - BORDER_HEIGHT - PADDLE_HEIGHT; 201 parameter START_Y = (MIN_Y + MAX_Y) / 2; 202 203 // registered state 204 reg [9:0] paddle_y; 205 206 // next holders 207 reg [9:0] next_y; 208 209 always @ (posedge clock) 210 if (reset) 211 paddle_y <= START_Y; 212 else 213 paddle_y <= next_y; 214 215 always @ (up_sync or down_sync or paddle_y or enable or paddle_speed) 216 begin 217 // by default, don't change state 218 next_y = paddle_y; 219 if (enable && (up_sync ^ down_sync)) begin 220 if (up_sync) 221 if (paddle_y > MIN_Y + paddle_speed) 222 next_y = paddle_y - paddle_speed; 223 else 224 next_y = MIN_Y; 225 else 226 if (paddle_y + paddle_speed < MAX_Y) 227 next_y = paddle_y + paddle_speed; 228 else 229 next_y = MAX_Y; 230 end 231 end 232 endmodule 233 </pre>
---	--

```

display_field.v

`timescale 1ns / 1ps
module display_field(reset, pixel_count, line_count,
                     paddle_y, ball_x, ball_y, in_rgb, out_rgb);
  input reset; // ignored, since display_field has no state
  input [9:0] pixel_count;
  input [9:0] line_count;
  input [9:0] paddle_y;
  input [9:0] ball_x;
  input [9:0] ball_y;
  input [23:0] in_rgb;
  output [23:0] out_rgb;

  // Internal Wring
  wire [23:0] rgb0, rgb1, rgb2, rgb3, rgb4, rgb5, rgb6,
             rgb7, rgb8, rgb9, rgb10, rgb11, rgb12;
  ...

  // Global Parameters
  `include "params.v"

  // Borders
  parameter BGROND = 0;
  parameter BREGROND = -1;
  assign rgb0 = in_rgb; //BGROND;

  box border1(pixel_count, line_count, 10'b0, 10'b0, rgb0, rgbl);
  defparam border1.RGB = BREGROND ;
  defparam border1.WDTH = DISPLAYWDTH ;
  defparam border1.HIGH = BORDER_HIGH ;

  box border2(pixel_count, line_count,
              DISPLAYWDTH - BORDER_WDTH , 10'b0, rgbl, rgb2);
  defparam border2.RGB = BREGROND ;
  defparam border2.WDTH = BORDER_WDTH ;
  defparam border2.HIGH = DISPLAYHIGH ;

  box border3(pixel_count, line_count, 10'b0,
              DISPLAYHIGH - BORDER_HIGH , rgb2, rgb3);
  defparam border3.RGB = BREGROND ;
  defparam border3.WDTH = DISPLAYWDTH ;
  defparam border3.HIGH = BORDER_HIGH ;

  // Logo
  parameter MIT_RED = {8'b0101_1111, 8'b0001_1111, 8'b0001_1111};
  parameter MIT_GRAY = {8'b0100_1111, 8'b0100_1111, 8'b0011_1111};
  parameter LOGO_WDTH = 10'd39;
  parameter LOGO_HIGH = 10'd195;
  parameter LOGO_X = 10'd133;
  parameter LOGO_Y = 10'd134;
  parameter LOGO_DX = LOGO_WDTH + 10'd25;

  box m1(pixel_count, line_count, LOGO_X, LOGO_Y, rgb3, rgb4);
  defparam m1.RGB = MIT_RED;
  defparam m1.WDTH = LOGO_WDTH ;
  defparam m1.HIGH = LOGO_HIGH ;

  box m2(pixel_count, line_count, LOGO_X + LOGO_DX, LOGO_Y, rgb4, rgb5);
  defparam m2.RGB = MIT_RED;
  defparam m2.WDTH = LOGO_WDTH ;
  defparam m2.HIGH = 137;

  box m3(pixel_count, line_count,
         (LOGO_X + 2'd2*LOGO_DX), LOGO_Y, rgb5, rgb6);
  defparam m3.RGB = MIT_RED;

```

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```

display_field.v

defparam m3.WDTH = LOGO_WDTH ;
defparam m3.HIGH = LOGO_HIGH ;

box il(pixel_count, line_count,
       (LOGO_X + 2'd3*LOGO_DX), LOGO_Y, rgb6, rgb7);
defparam il.RGB = MIT_RED;
defparam il.WDTH = LOGO_WDTH ;
defparam il.HIGH = LOGO_WDTH ;

box i2(pixel_count, line_count,
       (LOGO_X + 2'd3*LOGO_WDTH ), LOGO_Y + 2'd2*LOGO_WDTH , rgb7, rgb8);
defparam i2.RGB = MIT_GRAY;
defparam i2.WDTH = LOGO_WDTH ;
defparam i2.HIGH = LOGO_HIGH - 2*LOGO_WDTH ;

box t1(pixel_count, line_count,
       (LOGO_X + 3'd4*LOGO_DX), LOGO_Y, rgb8, rgb9);
defparam t1.RGB = MIT_RED;
defparam t1.WDTH = LOGO_HIGH - 2*LOGO_WDTH ;
defparam t1.HIGH = LOGO_WDTH ;

box t2(pixel_count, line_count,
       (LOGO_X + 3'd4*LOGO_DX),
       (LOGO_Y + 2'd2*LOGO_WDTH ), rgb9, rgb10);
defparam t2.RGB = MIT_RED;
defparam t2.WDTH = LOGO_WDTH ;
defparam t2.HIGH = LOGO_HIGH - 2*LOGO_WDTH ;

// paddle
box paddle(pixel_count, line_count,
            PADDLE_X, paddle_y, rgbl0, rgbl1);
defparam paddle.RGB = BREGROND ;
defparam paddle.WDTH = PADDLE_WDTH ;
defparam paddle.HIGH = PADDLE_HIGH ;

// ball
box ball(pixel_count, line_count, ball_x, ball_y, rgbl1, rgbl2);
defparam ball.RGB = BREGROND ;
defparam ball.WDTH = BALL_WDTH ;
defparam ball.HIGH = BALL_HIGH ;

assign out_rgb = rgbl2;

endmodule

module box(pixel_count, line_count, x, y, rgb_in, rgb_out);
  input [9:0] pixel_count;
  input [9:0] line_count;
  input [9:0] x;
  input [9:0] y;
  input [23:0] rgb_in;
  output [23:0] rgb_out;

  parameter WDTH = 1;
  parameter HIGH = 1;
  parameter RGB = 24'b0;

  assign rgb_out =
    ((pixel_count >= x && pixel_count < x + WDTH )
     && (line_count >= y && line_count < y + HIGH ))
    ? RGB : rgb_in;
endmodule

```

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```

signed.v
1 module signed_add(a, b, c);
2   parameter WIDTH = 12;
3
4   input signed [WIDTH-1:0] a, b;
5   output signed [WIDTH:0] c;
6
7   assign c = a + b;
8 endmodule
9
10 module signed_add3(a, b, c, sum);
11   parameter WIDTH = 12;
12   localparam C_WIDTH = WIDTH + 2;
13
14   input signed [WIDTH-1:0] a, b, c;
15   output signed [C_WIDTH-1:0] sum;
16
17   assign sum = a + b + c;
18 endmodule
19
20 module signed_inc(a, c);
21   parameter WIDTH = 12;
22
23   input signed [WIDTH-1:0] a;
24   output signed [WIDTH:0] c;
25
26   assign c = a + 1;
27 endmodule
28
29 module signed_lt(a, b, c);
30   parameter WIDTH = 12;
31
32   input signed [WIDTH-1:0] a, b;
33   output c;
34
35   assign c = a < b;
36 endmodule
37
38 module signed_bound(a, b);
39   parameter WIDTH = 12;
40   parameter MAX = 100;
41   parameter MIN = -100;
42
43   input signed [WIDTH-1:0] a;
44   output signed [WIDTH-1:0] b;
45   assign b = a < MIN ? MIN : (a > MAX ? MAX : a);
46 endmodule
47
48 module signed_multiply(a, b, c);
49   parameter A_WIDTH = 12;
50   parameter B_WIDTH = 12;
51   localparam C_WIDTH = A_WIDTH + B_WIDTH;
52
53   input signed [A_WIDTH-1:0] a;
54   input signed [B_WIDTH-1:0] b;
55   output signed [C_WIDTH-1:0] c;
56
57   assign c = a * b;
58 endmodule
59
60 module signed_negate(a, b);
61   parameter WIDTH = 12;
62
63   input signed [WIDTH-1:0] a;

```

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```

signed.v
64   output signed [WIDTH:0] b;
65
66   assign b = -a;
67 endmodule
68
69 module signed_outer3(a, b, c, min, max);
70   parameter WIDTH = 12;
71
72   input signed [WIDTH-1:0] a, b, c;
73   output signed [WIDTH-1:0] min, max;
74
75   assign min = a < b ?
76     (a < c ? a : c):
77     (b < c ? b : c);
78
79   assign max = a > b ?
80     (a > c ? a : c):
81     (b > c ? b : c);
82 endmodule
83
84 module signed_subtract(a, b, c);
85   parameter WIDTH = 12;
86
87   input signed [WIDTH-1:0] a, b;
88   output signed [WIDTH:0] c;
89
90   assign c = a - b;
91 endmodule
92
93 module signed_to_unsigned(in_a, next_a);
94   parameter WIDTH = 10;
95   parameter ZERO = 320;
96   input [WIDTH-1:0] in_a;
97   output [WIDTH-1:0] next_a;
98
99   wire [WIDTH:0] temp;
100
101  signed_add #(WIDTH) sal (in_a, ZERO, temp);
102  assign next_a = temp[WIDTH-1:0];
103 endmodule
104
105 module signed_trim(in_a, next_a, next_noop);
106   parameter IN_WIDTH = 13;
107   parameter OUT_WIDTH = 12;
108   parameter SKIP_WIDTH = 0;
109
110   input [IN_WIDTH-1:0] in_a;
111   output [OUT_WIDTH-1:0] next_a;
112   output next_noop;
113
114   wire [OUT_WIDTH-1:0] next_a;
115   wire [IN_WIDTH-1:OUT_WIDTH-1] trimmed;
116   wire next_noop;
117
118   assign next_a = in_a[OUT_WIDTH-1+SKIP_WIDTH:0+SKIP_WIDTH];
119   assign trimmed = in_a[IN_WIDTH-1:OUT_WIDTH-1+SKIP_WIDTH];
120   assign next_noop =
121     !(trimmed == {((IN_WIDTH-OUT_WIDTH-SKIP_WIDTH){1'b0}) ||
122     ((IN_WIDTH-OUT_WIDTH-SKIP_WIDTH){1'b1})});
123
124 endmodule

```

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```

vector.v

1 module vector_subtract(a, b, c);
2   parameter WIDTH = 12;
3
4   input [3*WIDTH-1:0] a, b;
5   output [3*(WIDTH+1)-1:0] c;
6
7   wire [WIDTH-1:0] a_x, a_y, a_z;
8   wire [WIDTH-1:0] b_x, b_y, b_z;
9   wire [WIDTH:0] c_x, c_y, c_z;
10
11  assign {a_x, a_y, a_z} = a;
12  assign {b_x, b_y, b_z} = b;
13  assign c = {c_x, c_y, c_z};
14
15  signed_subtract #(WIDTH) ss_x (a_x, b_x, c_x);
16  signed_subtract #(WIDTH) ss_y (a_y, b_y, c_y);
17  signed_subtract #(WIDTH) ss_z (a_z, b_z, c_z);
18 endmodule
19
20 module vector_matrix_product(a, b, c);
21   parameter A_WIDTH = 12;
22   parameter B_WIDTH = 12;
23   localparam C_WIDTH = A_WIDTH + B_WIDTH + 2;
24
25   input [3*A_WIDTH-1:0] a; /vector
26   input [9*B_WIDTH-1:0] b; /matrix
27   output [3*C_WIDTH-1:0] c;
28
29   wire [3*B_WIDTH-1:0] b1, b2, b3;
30   wire [B_WIDTH-1:0] b1_x, b1_y, b1_z,
31                     b2_x, b2_y, b2_z,
32                     b3_x, b3_y, b3_z;
33   wire [C_WIDTH-1:0] c_x, c_y, c_z;
34
35   assign {b1, b2, b3} = b;
36   assign {b1_x, b1_y, b1_z} = b1;
37   assign {b2_x, b2_y, b2_z} = b2;
38   assign {b3_x, b3_y, b3_z} = b3;
39
40   assign c = {c_x, c_y, c_z};
41
42   dot_product #(A_WIDTH, B_WIDTH) dp1 (a, {b1_x, b2_x, b3_x}, c_x);
43   dot_product #(A_WIDTH, B_WIDTH) dp2 (a, {b1_y, b2_y, b3_y}, c_y);
44   dot_product #(A_WIDTH, B_WIDTH) dp3 (a, {b1_z, b2_z, b3_z}, c_z);
45 endmodule
46
47 module vector_trim(in_v, next_v, next_noop);
48   parameter IN_WIDTH = 12;
49   parameter OUT_WIDTH = 11;
50   parameter SKIP_WIDTH = 0;
51
52   input [3*IN_WIDTH-1:0] in_v;
53   output [3*OUT_WIDTH-1:0] next_v;
54   output next_noop;
55
56   wire [IN_WIDTH-1:0] in_x, in_y, in_z;
57   wire [OUT_WIDTH-1:0] next_x, next_y, next_z;
58   wire x_noop, y_noop, znooop ;
59
60   assign {in_x, in_y, in_z} = in_v;
61   assign next_v = {next_x, next_y, next_z};
62   assign next_noop = x_noop|y_noop|znooop ;
63

```

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```

vector.v

64   signed_trim #(IN_WIDTH, OUT_WIDTH, SKIP_WIDTH) st_x (in_x, next_x, x_noop);
65   signed_trim #(IN_WIDTH, OUT_WIDTH, SKIP_WIDTH) st_y (in_y, next_y, y_noop);
66   signed_trim #(IN_WIDTH, OUT_WIDTH, SKIP_WIDTH) st_z (in_z, next_z, znooop );
67 endmodule
68
69 module dot_product(a, b, c);
70   parameter A_WIDTH = 12;
71   parameter B_WIDTH = 12;
72   localparam C_WIDTH = A_WIDTH + B_WIDTH + 2;
73
74   input [3*A_WIDTH-1:0] a;
75   input [3*B_WIDTH-1:0] b;
76   output [C_WIDTH-1:0] c;
77
78   wire [A_WIDTH-1:0] a_x, a_y, a_z;
79   wire [B_WIDTH-1:0] b_x, b_y, b_z;
80   wire [(A_WIDTH+B_WIDTH)-1:0] c_x, c_y, c_z;
81
82   assign {a_x, a_y, a_z} = a;
83   assign {b_x, b_y, b_z} = b;
84
85   signed_multiply #(A_WIDTH, B_WIDTH) sm_x (a_x, b_x, c_x);
86   signed_multiply #(A_WIDTH, B_WIDTH) sm_y (a_y, b_y, c_y);
87   signed_multiply #(A_WIDTH, B_WIDTH) sm_z (a_z, b_z, c_z);
88
89   signed_add3 #(A_WIDTH+B_WIDTH) sa(c_x, c_y, c_z, c);
90 endmodule
91
92 module cross_product(a, b, c);
93   parameter A_WIDTH = 12;
94   parameter B_WIDTH = 12;
95
96   input [3*A_WIDTH-1:0] a;
97   input [3*B_WIDTH-1:0] b;
98   output [3*(A_WIDTH+B_WIDTH+1)-1:0] c;
99
100  wire [A_WIDTH-1:0] a_x, a_y, a_z;
101  wire [B_WIDTH-1:0] b_x, b_y, b_z;
102  wire [A_WIDTH+B_WIDTH-1:0] c_x1, c_y1, c_z1 , c_x2, c_y2, c_z2 ;
103
104  assign {a_x, a_y, a_z} = a;
105  assign {b_x, b_y, b_z} = b;
106
107  signed_multiply #(A_WIDTH, B_WIDTH) sm_x1 (a_y, b_z, c_x1);
108  signed_multiply #(A_WIDTH, B_WIDTH) sm_x2 (a_z, b_y, c_x2);
109
110  signed_multiply #(A_WIDTH, B_WIDTH) sm_y1 (a_z, b_x, c_y1);
111  signed_multiply #(A_WIDTH, B_WIDTH) sm_y2 (a_x, b_z, c_y2);
112
113  signed_multiply #(A_WIDTH, B_WIDTH) sm_z1 (a_x, b_y, c_z1 );
114  signed_multiply #(A_WIDTH, B_WIDTH) sm_z2 (a_y, b_x, c_z2 );
115
116  vector_subtract #(A_WIDTH + B_WIDTH) vs ({c_x1, c_y1, c_z1 }, {c_x2, c_y2, c_z2 }, c);
117
118 endmodule

```

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```

matrix.v

1 module matrix_product(a, b, c);
2   parameter A_WIDTH = 12;
3   parameter B_WIDTH = 12;
4   localparam C_WIDTH = A_WIDTH+B_WIDTH+2;
5
6   input [9*A_WIDTH-1:0] a; // matrix
7   input [9*B_WIDTH-1:0] b; // matrix
8   output [9*C_WIDTH-1:0] c; // matrix
9
10  wire [3*B_WIDTH-1:0] b1, b2, b3;
11  wire [B_WIDTH-1:0] b1_x, b1_y, b1_z,
12    b2_x, b2_y, b2_z,
13    b3_x, b3_y, b3_z;
14
15  assign {b1, b2, b3} = b;
16  assign {b1_x, b1_y, b1_z} = b1;
17  assign {b2_x, b2_y, b2_z} = b2;
18  assign {b3_x, b3_y, b3_z} = b3;
19
20  wire [3*C_WIDTH-1:0] c1, c2, c3;
21  wire [C_WIDTH-1:0] c1_x, c1_y, c1_z,
22    c2_x, c2_y, c2_z,
23    c3_x, c3_y, c3_z;
24
25  assign c = {c1, c2, c3};
26  assign c1 = {c1_x, c1_y, c1_z};
27  assign c2 = {c2_x, c2_y, c2_z};
28  assign c3 = {c3_x, c3_y, c3_z};
29
30  matrix_vector_product #(A_WIDTH, B_WIDTH) mvpx
31  (a, {b1_x, b2_x, b3_x}, {c1_x, c2_x, c3_x});
32  matrix_vector_product #(A_WIDTH, B_WIDTH) mvpy
33  (a, {b1_y, b2_y, b3_y}, {c1_y, c2_y, c3_y});
34  matrix_vector_product #(A_WIDTH, B_WIDTH) mvpz
35  (a, {b1_z, b2_z, b3_z}, {c1_z, c2_z, c3_z});
36 endmodule
37
38 module matrix_subtract(a, b, c);
39   parameter WIDTH = 12;
40
41   input [9*WIDTH-1:0] a, b;
42   output [9*(WIDTH+1)-1:0] c;
43
44   wire [3*WIDTH-1:0] a1, a2, a3, b1, b2, b3;
45   wire [3*(WIDTH+1)-1:0] c1, c2, c3;
46
47   assign {a1, a2, a3} = a;
48   assign {b1, b2, b3} = b;
49   assign c = {c1, c2, c3};
50
51   vector_subtract #(WIDTH) vs_1 (a1, b1, c1);
52   vector_subtract #(WIDTH) vs_2 (a2, b2, c2);
53   vector_subtract #(WIDTH) vs_3 (a3, b3, c3);
54 endmodule
55
56 module matrix_trim(in_m, next_m, next_noop);
57   parameter IN_WIDTH = 12;
58   parameter OUT_WIDTH = 11;
59   parameter SKIP_WIDTH = 0;
60
61   input [9*IN_WIDTH-1:0] in_m;
62   output [9*OUT_WIDTH-1:0] next_m;
63   output next_noop;

```

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```

matrix.v

64
65   wire [3*IN_WIDTH-1:0] in_a, in_b, in_c;
66   wire [3*OUT_WIDTH-1:0] next_a, next_b, next_c;
67   wire a_noop, b_noop, c_noop;
68
69   assign {in_a, in_b, in_c} = in_m;
70   assign next_m = {next_a, next_b, next_c};
71   assign next_noop = a_noop||b_noop||c_noop;
72
73   vector_trim #(IN_WIDTH, OUT_WIDTH, SKIP_WIDTH) st_a (in_a, next_a, a_noop);
74   vector_trim #(IN_WIDTH, OUT_WIDTH, SKIP_WIDTH) st_b (in_b, next_b, b_noop);
75   vector_trim #(IN_WIDTH, OUT_WIDTH, SKIP_WIDTH) st_c (in_c, next_c, c_noop);
76 endmodule
77
78 module matrix_vector_product(a, b, c);
79   parameter A_WIDTH = 12;
80   parameter B_WIDTH = 12;
81   localparam C_WIDTH = A_WIDTH + B_WIDTH + 2;
82
83   input [9*A_WIDTH-1:0] a; // matrix
84   input [3*B_WIDTH-1:0] b; // vector
85   output [3*C_WIDTH-1:0] c;
86
87   wire [3*A_WIDTH-1:0] a1, a2, a3;
88   wire [C_WIDTH-1:0] c_x, c_y, c_z;
89
90   assign {a1, a2, a3} = a;
91   assign c = {c_x, c_y, c_z};
92
93   dot_product #(A_WIDTH, B_WIDTH) dp1 (a1, b, c_x);
94   dot_product #(A_WIDTH, B_WIDTH) dp2 (a2, b, c_y);
95   dot_product #(A_WIDTH, B_WIDTH) dp3 (a3, b, c_z);
96 endmodule
97

```

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```

1      thetas_to_matrix.v
2
3      `timescale 1ns / 1ps
4      `include "defines.v"
5      module thetas_to_matrix(
6          reset, clock, enable, theta_x, theta_y, theta_z,
7          theta_rotor, matrix, rotor_matrix);
8          input reset, clock, enable;
9          input [`TRIG_IN_BITS-1:0] theta_x, theta_y, theta_z, theta_rotor;
10         output [9*`TRIG_OUT_BITS-1:0] matrix, rotor_matrix;
11
12         localparam IDLE = 0;
13         localparam X_ROTATION = 1;
14         localparam YROTATION = 2;
15         localparam Z_ROTATION = 3;
16         localparam ROTOR = 4;
17         localparam FNAL = 5;
18
19         reg [2:0] state, next_state;
20         reg [`TRIG_IN_BITS-1:0] theta, next_theta;
21         reg [1:0] select, next_select;
22         reg [9*`TRIG_OUT_BITS-1:0] matrix, next_matrix,
23             rotor_matrix, next_rotor_matrix,
24             temp0, next_temp0,
25             templ, next_temp1;
26
27         wire [9*`TRIG_OUT_BITS-1:0] ttm_matrix, mt_matrix;
28         wire [9*(2*`TRIG_OUT_BITS+2)-1:0] mp_matrix;
29
30         theta_to_matrix ttm (theta, select, ttm_matrix);
31
32         matrix_product #(`TRIG_OUT_BITS, `TRIG_OUT_BITS)
33             mp (temp0, templ, mp_matrix);
34
35         matrix_trim
36             #(`TRIG_OUT_BITS+`TRIG_OUT_BITS+2, `TRIG_OUT_BITS, `TRIG_OUT_BITS-2)
37             mt (mp_matrix, mt_matrix, out_noop);
38
39         always @ (posedge clock)
40             if (reset) begin
41                 state <= IDLE;
42                 theta <= {(`TRIG_IN_BITS){1'b0}};
43                 select <= 2'b0;
44                 temp0 <= {(`TRIG_OUT_BITS){1'b0}};
45                 templ <= {(`TRIG_OUT_BITS){1'b0}};
46                 matrix <= {(`TRIG_OUT_BITS){1'b0}};
47                 rotor_matrix <= {(`TRIG_OUT_BITS){1'b0}};
48             end else begin
49                 state <= next_state;
50                 theta <= next_theta;
51                 select <= next_select;
52                 temp0 <= next_temp0;
53                 templ <= next_temp1;
54                 matrix <= next_matrix;
55                 rotor_matrix <= next_rotor_matrix;
56             end
57
58         wire timer;
59         divider #(5) div0 (reset, clock, timer);
60
61         always @ (state, theta, select, temp0, templ, matrix, enable,
62             theta_x, theta_y, ttm_matrix, theta_z, mt_matrix,
63             rotor_matrix, theta_rotor) begin
64             next_state = state;
65             next_theta = theta;
66
67             localparam MAX = {2'b01, {(`TRIG_OUT_BITS-2){1'b0}}};
68
69             reg [`TRIG_OUT_BITS-1:0]
70                 a_x, a_y, a_z, b_x, b_y, b_z, c_x, c_y, c_z;
71             assign matrix =
72                 {a_x, a_y, a_z, b_x, b_y, b_z, c_x, c_y, c_z};
73
74             wire [`TRIG_OUT_BITS-1:0] cos, sin, nsin;
75             wire [`TRIG_OUT_BITS:0] neg_sin;
76
77             trig t (theta, sin, cos);
78
79             next_select = select;
80             next_temp0 = temp0;
81             next_temp1 = templ;
82             next_matrix = matrix;
83             next_rotor_matrix = rotor_matrix;
84
85             if (timer || enable) begin
86                 case (state)
87                     IDLE:
88                         if (enable) begin
89                             next_state = X_ROTATION;
90                             next_theta = theta_x;
91                             next_select = 2'b0;
92                         end
93                     X_ROTATION:
94                         begin
95                             next_state = YROTATION ;
96                             next_theta = theta_y;
97                             next_select = 2'b1;
98                             next_temp0 = ttm_matrix;
99                         end
100                    YROTATION :
101                        begin
102                            next_temp1 = ttm_matrix;
103                            next_state = Z_ROTATION;
104                            next_theta = theta_z;
105                            next_select = 2'b10;
106                        end
107                    Z_ROTATION:
108                        begin
109                            next_temp0 = mt_matrix;
110                            next_temp1 = ttm_matrix;
111                            next_theta = theta_rotor;
112                            next_select = 2'b10;
113                            next_state = FNAL ;
114                        end
115                    FNAL :
116                        begin
117                            next_matrix = mt_matrix;
118                            next_rotor_matrix = ttm_matrix;
119                            next_state = IDLE;
120                        end
121                endcase
122            end
123        endmodule
124
125        module theta_to_matrix(theta, select, matrix);
126
127            input [`TRIG_IN_BITS-1:0] theta;
128            input [1:0] select;
129            output [9*`TRIG_OUT_BITS-1:0] matrix;
130
131            localparam MAX = {2'b01, {(`TRIG_OUT_BITS-2){1'b0}}};
132
133            reg [`TRIG_OUT_BITS-1:0]
134                a_x, a_y, a_z, b_x, b_y, b_z, c_x, c_y, c_z;
135            assign matrix =
136                {a_x, a_y, a_z, b_x, b_y, b_z, c_x, c_y, c_z};
137
138            wire [`TRIG_OUT_BITS-1:0] cos, sin, nsin;
139            wire [`TRIG_OUT_BITS:0] neg_sin;
140
141            trig t (theta, sin, cos);
142
143            next_select = select;
144            next_temp0 = temp0;
145            next_temp1 = templ;
146            next_matrix = matrix;
147            next_rotor_matrix = rotor_matrix;
148
149            if (timer || enable) begin
150                case (state)
151                    IDLE:
152                        if (enable) begin
153                            next_state = X_ROTATION;
154                            next_theta = theta_x;
155                            next_select = 2'b0;
156                        end
157                    X_ROTATION:
158                        begin
159                            next_state = YROTATION ;
160                            next_theta = theta_y;
161                            next_select = 2'b1;
162                            next_temp0 = ttm_matrix;
163                        end
164                    YROTATION :
165                        begin
166                            next_temp1 = ttm_matrix;
167                            next_state = Z_ROTATION;
168                            next_theta = theta_z;
169                            next_select = 2'b10;
170                        end
171                    Z_ROTATION:
172                        begin
173                            next_temp0 = mt_matrix;
174                            next_temp1 = ttm_matrix;
175                            next_theta = theta_rotor;
176                            next_select = 2'b10;
177                            next_state = FNAL ;
178                        end
179                    FNAL :
180                        begin
181                            next_matrix = mt_matrix;
182                            next_rotor_matrix = ttm_matrix;
183                            next_state = IDLE;
184                        end
185                endcase
186            end
187        endmodule
188
189        module matrix_product(theta, select, matrix);
190
191            input [`TRIG_IN_BITS-1:0] theta;
192            input [1:0] select;
193            output [9*`TRIG_OUT_BITS-1:0] matrix;
194
195            localparam MAX = {2'b01, {(`TRIG_OUT_BITS-2){1'b0}}};
196
197            reg [`TRIG_OUT_BITS-1:0]
198                a_x, a_y, a_z, b_x, b_y, b_z, c_x, c_y, c_z;
199            assign matrix =
200                {a_x, a_y, a_z, b_x, b_y, b_z, c_x, c_y, c_z};
201
202            wire [`TRIG_OUT_BITS-1:0] cos, sin, nsin;
203            wire [`TRIG_OUT_BITS:0] neg_sin;
204
205            trig t (theta, sin, cos);
206
207            next_select = select;
208            next_temp0 = temp0;
209            next_temp1 = templ;
210            next_matrix = matrix;
211
212            if (timer || enable) begin
213                case (state)
214                    IDLE:
215                        if (enable) begin
216                            next_state = X_ROTATION;
217                            next_theta = theta_x;
218                            next_select = 2'b0;
219                        end
220                    X_ROTATION:
221                        begin
222                            next_state = YROTATION ;
223                            next_theta = theta_y;
224                            next_select = 2'b1;
225                            next_temp0 = ttm_matrix;
226                        end
227                    YROTATION :
228                        begin
229                            next_temp1 = ttm_matrix;
230                            next_state = Z_ROTATION;
231                            next_theta = theta_z;
232                            next_select = 2'b10;
233                        end
234                    Z_ROTATION:
235                        begin
236                            next_temp0 = mt_matrix;
237                            next_temp1 = ttm_matrix;
238                            next_theta = theta_rotor;
239                            next_select = 2'b10;
240                            next_state = FNAL ;
241                        end
242                    FNAL :
243                        begin
244                            next_matrix = mt_matrix;
245                            next_rotor_matrix = ttm_matrix;
246                            next_state = IDLE;
247                        end
248                endcase
249            end
250        endmodule
251
252        module matrix_trim(theta, select, matrix);
253
254            input [`TRIG_IN_BITS-1:0] theta;
255            input [1:0] select;
256            output [9*`TRIG_OUT_BITS-1:0] matrix;
257
258            localparam MAX = {2'b01, {(`TRIG_OUT_BITS-2){1'b0}}};
259
260            reg [`TRIG_OUT_BITS-1:0]
261                a_x, a_y, a_z, b_x, b_y, b_z, c_x, c_y, c_z;
262            assign matrix =
263                {a_x, a_y, a_z, b_x, b_y, b_z, c_x, c_y, c_z};
264
265            wire [`TRIG_OUT_BITS-1:0] cos, sin, nsin;
266            wire [`TRIG_OUTBITS:0] neg_sin;
267
268            trig t (theta, sin, cos);
269
270            next_select = select;
271            next_temp0 = temp0;
272            next_temp1 = templ;
273            next_matrix = matrix;
274
275            if (timer || enable) begin
276                case (state)
277                    IDLE:
278                        if (enable) begin
279                            next_state = X_ROTATION;
280                            next_theta = theta_x;
281                            next_select = 2'b0;
282                        end
283                    X_ROTATION:
284                        begin
285                            next_state = YROTATION ;
286                            next_theta = theta_y;
287                            next_select = 2'b1;
288                            next_temp0 = ttm_matrix;
289                        end
290                    YROTATION :
291                        begin
292                            next_temp1 = ttm_matrix;
293                            next_state = Z_ROTATION;
294                            next_theta = theta_z;
295                            next_select = 2'b10;
296                        end
297                    Z_ROTATION:
298                        begin
299                            next_temp0 = mt_matrix;
300                            next_temp1 = ttm_matrix;
301                            next_theta = theta_rotor;
302                            next_select = 2'b10;
303                            next_state = FNAL ;
304                        end
305                    FNAL :
306                        begin
307                            next_matrix = mt_matrix;
308                            next_rotor_matrix = ttm_matrix;
309                            next_state = IDLE;
310                        end
311                endcase
312            end
313        endmodule
314
315        module timer();
316
317            output [1:0] timer;
318
319            reg [1:0] count;
320
321            initial
322                begin
323                    count = 0;
324                end
325
326            always
327                begin
328                    if (count == 5)
329                        count = 0;
330                    else
331                        count = count + 1;
332
333                    if (count == 5)
334                        timer = 2'b1;
335                    else
336                        timer = 2'b0;
337                end
338
339        endmodule
340
341        module divider(divider);
342
343            output [1:0] div0;
344
345            reg [1:0] count;
346
347            initial
348                begin
349                    count = 0;
350                end
351
352            always
353                begin
354                    if (count == 5)
355                        count = 0;
356                    else
357                        count = count + 1;
358
359                    if (count == 5)
360                        div0 = 2'b1;
361                    else
362                        div0 = 2'b0;
363                end
364
365        endmodule
366
367        module trig(trig);
368
369            input [1:0] theta;
370            input [1:0] sin;
371            input [1:0] cos;
372
373            output [9*`TRIG_OUTBITS-1:0] matrix;
374
375            localparam MAX = {2'b01, {(`TRIG_OUTBITS-2){1'b0}}};
376
377            reg [`TRIG_OUTBITS-1:0]
378                a_x, a_y, a_z, b_x, b_y, b_z, c_x, c_y, c_z;
379            assign matrix =
380                {a_x, a_y, a_z, b_x, b_y, b_z, c_x, c_y, c_z};
381
382            wire [9*`TRIG_OUTBITS-1:0] neg_sin;
383
384            trig t (theta, sin, cos);
385
386            next_select = select;
387            next_temp0 = temp0;
388            next_temp1 = templ;
389            next_matrix = matrix;
390
391            if (timer || enable) begin
392                case (state)
393                    IDLE:
394                        if (enable) begin
395                            next_state = X_ROTATION;
396                            next_theta = theta_x;
397                            next_select = 2'b0;
398                        end
399                    X_ROTATION:
400                        begin
401                            next_state = YROTATION ;
402                            next_theta = theta_y;
403                            next_select = 2'b1;
404                            next_temp0 = ttm_matrix;
405                        end
406                    YROTATION :
407                        begin
408                            next_temp1 = ttm_matrix;
409                            next_state = Z_ROTATION;
410                            next_theta = theta_z;
411                            next_select = 2'b10;
412                        end
413                    Z_ROTATION:
414                        begin
415                            next_temp0 = mt_matrix;
416                            next_temp1 = ttm_matrix;
417                            next_theta = theta_rotor;
418                            next_select = 2'b10;
419                            next_state = FNAL ;
420                        end
421                    FNAL :
422                        begin
423                            next_matrix = mt_matrix;
424                            next_rotor_matrix = ttm_matrix;
425                            next_state = IDLE;
426                        end
427                endcase
428            end
429        endmodule
430
431        module assign(assign);
432
433            input [9*`TRIG_OUTBITS-1:0] matrix;
434
435            localparam MAX = {2'b01, {(`TRIG_OUTBITS-2){1'b0}}};
436
437            reg [9*`TRIG_OUTBITS-1:0]
438                a_x, a_y, a_z, b_x, b_y, b_z, c_x, c_y, c_z;
439            assign matrix =
440                {a_x, a_y, a_z, b_x, b_y, b_z, c_x, c_y, c_z};
441
442            wire [9*`TRIG_OUTBITS-1:0] neg_sin;
443
444            trig t (theta, sin, cos);
445
446            next_select = select;
447            next_temp0 = temp0;
448            next_temp1 = templ;
449            next_matrix = matrix;
450
451            if (timer || enable) begin
452                case (state)
453                    IDLE:
454                        if (enable) begin
455                            next_state = X_ROTATION;
456                            next_theta = theta_x;
457                            next_select = 2'b0;
458                        end
459                    X_ROTATION:
460                        begin
461                            next_state = YROTATION ;
462                            next_theta = theta_y;
463                            next_select = 2'b1;
464                            next_temp0 = ttm_matrix;
465                        end
466                    YROTATION :
467                        begin
468                            next_temp1 = ttm_matrix;
469                            next_state = Z_ROTATION;
470                            next_theta = theta_z;
471                            next_select = 2'b10;
472                        end
473                    Z_ROTATION:
474                        begin
475                            next_temp0 = mt_matrix;
476                            next_temp1 = ttm_matrix;
477                            next_theta = theta_rotor;
478                            next_select = 2'b10;
479                            next_state = FNAL ;
480                        end
481                    FNAL :
482                        begin
483                            next_matrix = mt_matrix;
484                            next_rotor_matrix = ttm_matrix;
485                            next_state = IDLE;
486                        end
487                endcase
488            end
489        endmodule
490
491        module wire(wire);
492
493            input [9*`TRIG_OUTBITS-1:0] matrix;
494
495            localparam MAX = {2'b01, {(`TRIG_OUTBITS-2){1'b0}}};
496
497            reg [9*`TRIG_OUTBITS-1:0]
498                a_x, a_y, a_z, b_x, b_y, b_z, c_x, c_y, c_z;
499            assign matrix =
500                {a_x, a_y, a_z, b_x, b_y, b_z, c_x, c_y, c_z};
501
502            wire [9*`TRIG_OUTBITS-1:0] neg_sin;
503
504            trig t (theta, sin, cos);
505
506            next_select = select;
507            next_temp0 = temp0;
508            next_temp1 = templ;
509            next_matrix = matrix;
510
511            if (timer || enable) begin
512                case (state)
513                    IDLE:
514                        if (enable) begin
515                            next_state = X_ROTATION;
516                            next_theta = theta_x;
517                            next_select = 2'b0;
518                        end
519                    X_ROTATION:
520                        begin
521                            next_state = YROTATION ;
522                            next_theta = theta_y;
523                            next_select = 2'b1;
524                            next_temp0 = ttm_matrix;
525                        end
526                    YROTATION :
527                        begin
528                            next_temp1 = ttm_matrix;
529                            next_state = Z_ROTATION;
530                            next_theta = theta_z;
531                            next_select = 2'b10;
532                        end
533                    Z_ROTATION:
534                        begin
535                            next_temp0 = mt_matrix;
536                            next_temp1 = ttm_matrix;
537                            next_theta = theta_rotor;
538                            next_select = 2'b10;
539                            next_state = FNAL ;
540                        end
541                    FNAL :
542                        begin
543                            next_matrix = mt_matrix;
544                            next_rotor_matrix = ttm_matrix;
545                            next_state = IDLE;
546                        end
547                endcase
548            end
549        endmodule
550
551        module trig(trig);
552
553            input [1:0] theta;
554            input [1:0] sin;
555            input [1:0] cos;
556
557            output [9*`TRIG_OUTBITS-1:0] matrix;
558
559            localparam MAX = {2'b01, {(`TRIG_OUTBITS-2){1'b0}}};
560
561            reg [`TRIG_OUTBITS-1:0]
562                a_x, a_y, a_z, b_x, b_y, b_z, c_x, c_y, c_z;
563            assign matrix =
564                {a_x, a_y, a_z, b_x, b_y, b_z, c_x, c_y, c_z};
565
566            wire [9*`TRIG_OUTBITS-1:0] neg_sin;
567
568            trig t (theta, sin, cos);
569
570            next_select = select;
571            next_temp0 = temp0;
572            next_temp1 = templ;
573            next_matrix = matrix;
574
575            if (timer || enable) begin
576                case (state)
577                    IDLE:
578                        if (enable) begin
579                            next_state = X_ROTATION;
580                            next_theta = theta_x;
581                            next_select = 2'b0;
582                        end
583                    X_ROTATION:
584                        begin
585                            next_state = YROTATION ;
586                            next_theta = theta_y;
587                            next_select = 2'b1;
588                            next_temp0 = ttm_matrix;
589                        end
590                    YROTATION :
591                        begin
592                            next_temp1 = ttm_matrix;
593                            next_state = Z_ROTATION;
594                            next_theta = theta_z;
595                            next_select = 2'b10;
596                        end
597                    Z_ROTATION:
598                        begin
599                            next_temp0 = mt_matrix;
600                            next_temp1 = ttm_matrix;
601                            next_theta = theta_rotor;
602                            next_select = 2'b10;
603                            next_state = FNAL ;
604                        end
605                    FNAL :
606                        begin
607                            next_matrix = mt_matrix;
608                            next_rotor_matrix = ttm_matrix;
609                            next_state = IDLE;
610                        end
611                endcase
612            end
613        endmodule
614
615        module assign(assign);
616
617            input [9*`TRIG_OUTBITS-1:0] matrix;
618
619            localparam MAX = {2'b01, {(`TRIG_OUTBITS-2){1'b0}}};
620
621            reg [9*`TRIG_OUTBITS-1:0]
622                a_x, a_y, a_z, b_x, b_y, b_z, c_x, c_y, c_z;
623            assign matrix =
624                {a_x, a_y, a_z, b_x, b_y, b_z, c_x, c_y, c_z};
625
626            wire [9*`TRIG_OUTBITS-1:0] neg_sin;
627
628            trig t (theta, sin, cos);
629
630            next_select = select;
631            next_temp0 = temp0;
632            next_temp1 = templ;
633            next_matrix = matrix;
634
635            if (timer || enable) begin
636                case (state)
637                    IDLE:
638                        if (enable) begin
639                            next_state = X_ROTATION;
640                            next_theta = theta_x;
641                            next_select = 2'b0;
642                        end
643                    X_ROTATION:
644                        begin
645                            next_state = YROTATION ;
646                            next_theta = theta_y;
647                            next_select = 2'b1;
648                            next_temp0 = ttm_matrix;
649                        end
650                    YROTATION :
651                        begin
652                            next_temp1 = ttm_matrix;
653                            next_state = Z_ROTATION;
654                            next_theta = theta_z;
655                            next_select = 2'b10;
656                        end
657                    Z_ROTATION:
658                        begin
659                            next_temp0 = mt_matrix;
660                            next_temp1 = ttm_matrix;
661                            next_theta = theta_rotor;
662                            next_select = 2'b10;
663                            next_state = FNAL ;
664                        end
665                    FNAL :
666                        begin
667                            next_matrix = mt_matrix;
668                            next_rotor_matrix = ttm_matrix;
669                            next_state = IDLE;
670                        end
671                endcase
672            end
673        endmodule
674
675        module wire(wire);
676
677            input [9*`TRIG_OUTBITS-1:0] matrix;
678
679            localparam MAX = {2'b01, {(`TRIG_OUTBITS-2){1'b0}}};
680
681            reg [9*`TRIG_OUTBITS-1:0]
682                a_x, a_y, a_z, b_x, b_y, b_z, c_x, c_y, c_z;
683            assign matrix =
684                {a_x, a_y, a_z, b_x, b_y, b_z, c_x, c_y, c_z};
685
686            wire [9*`TRIG_OUTBITS-1:0] neg_sin;
687
688            trig t (theta, sin, cos);
689
690            next_select = select;
691            next_temp0 = temp0;
692            next_temp1 = templ;
693            next_matrix = matrix;
694
695            if (timer || enable) begin
696                case (state)
697                    IDLE:
698                        if (enable) begin
699                            next_state = X_ROTATION;
700                            next_theta = theta_x;
701                            next_select = 2'b0;
702                        end
703                    X_ROTATION:
704                        begin
705                            next_state = YROTATION ;
706                            next_theta = theta_y;
707                            next_select = 2'b1;
708                            next_temp0 = ttm_matrix;
709                        end
710                    YROTATION :
711                        begin
712                            next_temp1 = ttm_matrix;
713                            next_state = Z_ROTATION;
714                            next_theta = theta_z;
715                            next_select = 2'b10;
716                        end
717                    Z_ROTATION:
718                        begin
719                            next_temp0 = mt_matrix;
720                            next_temp1 = ttm_matrix;
721                            next_theta = theta_rotor;
722                            next_select = 2'b10;
723                            next_state = FNAL ;
724                        end
725                    FNAL :
726                        begin
727                            next_matrix = mt_matrix;
728                            next_rotor_matrix = ttm_matrix;
729                            next_state = IDLE;
730                        end
731                endcase
732            end
733        endmodule
734
735        module trig(trig);
736
737            input [1:0] theta;
738            input [1:0] sin;
739            input [1:0] cos;
740
741            output [9*`TRIG_OUTBITS-1:0] matrix;
742
743            localparam MAX = {2'b01, {(`TRIG_OUTBITS-2){1'b0}}};
744
745            reg [`TRIG_OUTBITS-1:0]
746                a_x, a_y, a_z, b_x, b_y, b_z, c_x, c_y, c_z;
747            assign matrix =
748                {a_x, a_y, a_z, b_x, b_y, b_z, c_x, c_y, c_z};
749
750            wire [9*`TRIG_OUTBITS-1:0] neg_sin;
751
752            trig t (theta, sin, cos);
753
754            next_select = select;
755            next_temp0 = temp0;
756            next_temp1 = templ;
757            next_matrix = matrix;
758
759            if (timer || enable) begin
760                case (state)
761                    IDLE:
762                        if (enable) begin
763                            next_state = X_ROTATION;
764                            next_theta = theta_x;
765                            next_select = 2'b0;
766                        end
767                    X_ROTATION:
768                        begin
769                            next_state = YROTATION ;
770                            next_theta = theta_y;
771                            next_select = 2'b1;
772                            next_temp0 = ttm_matrix;
773                        end
774                    YROTATION :
775                        begin
776                            next_temp1 = ttm_matrix;
777                            next_state = Z_ROTATION;
778                            next_theta = theta_z;
779                            next_select = 2'b10;
780                        end
781                    Z_ROTATION:
782                        begin
783                            next_temp0 = mt_matrix;
784                            next_temp1 = ttm_matrix;
785                            next_theta = theta_rotor;
786                            next_select = 2'b10;
787                            next_state = FNAL ;
788                        end
789                    FNAL :
790                        begin
791                            next_matrix = mt_matrix;
792                            next_rotor_matrix = ttm_matrix;
793                            next_state = IDLE;
794                        end
795                endcase
796            end
797        endmodule
798
799        module assign(assign);
800
801            input [9*`TRIG_OUTBITS-1:0] matrix;
802
803            localparam MAX = {2'b01, {(`TRIG_OUTBITS-2){1'b0}}};
804
805            reg [9*`TRIG_OUTBITS-1:0]
806                a_x, a_y, a_z, b_x, b_y, b_z, c_x, c_y, c_z;
807            assign matrix =
808                {a_x, a_y, a_z, b_x, b_y, b_z, c_x, c_y, c_z};
809
810            wire [9*`TRIG_OUTBITS-1:0] neg_sin;
811
812            trig t (theta, sin, cos);
813
814            next_select = select;
815            next_temp0 = temp0;
816            next_temp1 = templ;
817            next_matrix = matrix;
818
819            if (timer || enable) begin
820                case (state)
821                    IDLE:
822                        if (enable) begin
823                            next_state = X_ROTATION;
824                            next_theta = theta_x;
825                            next_select = 2'b0;
826                        end
827                    X_ROTATION:
828                        begin
829                            next_state = YROTATION ;
830                            next_theta = theta_y;
831                            next_select = 2'b1;
832                            next_temp0 = ttm_matrix;
833                        end
834                    YROTATION :
835                        begin
836                            next_temp1 = ttm_matrix;
837                            next_state = Z_ROTATION;
838                            next_theta = theta_z;
839                            next_select = 2'b10;
840                        end
841                    Z_ROTATION:
842                        begin
843                            next_temp0 = mt_matrix;
844                            next_temp1 = ttm_matrix;
845                            next_theta = theta_rotor;
846                            next_select = 2'b10;
847                            next_state = FNAL ;
848                        end
849                    FNAL :
850                        begin
851                            next_matrix = mt_matrix;
852                            next_rotor_matrix = ttm_matrix;
853                            next_state = IDLE;
854                        end
855                endcase
856            end
857        endmodule
858
859        module wire(wire);
860
861            input [9*`TRIG_OUTBITS-1:0] matrix;
862
863            localparam MAX = {2'b01, {(`TRIG_OUTBITS-2){1'b0}}};
864
865            reg [9*`TRIG_OUTBITS-1:0]
866                a_x, a_y, a_z, b_x, b_y, b_z, c_x, c_y, c_z;
867            assign matrix =
868                {a_x, a_y, a_z, b_x, b_y, b_z, c_x, c_y, c_z};
869
870            wire [9*`TRIG_OUTBITS-1:0] neg_sin;
871
872            trig t (theta, sin, cos);
873
874            next_select = select;
875            next_temp0 = temp0;
876            next_temp1 = templ;
877            next_matrix = matrix;
878
879            if (timer || enable) begin
880                case (state)
881                    IDLE:
882                        if (enable) begin
883                            next_state = X_ROTATION;
884                            next_theta = theta_x;
885                            next_select = 2'b0;
886                        end
887                    X_ROTATION:
888                        begin
889                            next_state = YROTATION ;
890                            next_theta = theta_y;
891                            next_select = 2'b1;
892                            next_temp0 = ttm_matrix;
893                        end
894                    YROTATION :
895                        begin
896                            next_temp1 = ttm_matrix;
897                            next_state = Z_ROTATION;
898                            next_theta = theta_z;
899                            next_select = 2'b10;
900                        end
901                    Z_ROTATION:
902                        begin
903                            next_temp0 = mt_matrix;
904                            next_temp1 = ttm_matrix;
905                            next_theta = theta_rotor;
906                            next_select = 2'b10;
907                            next_state = FNAL ;
908                        end
909                    FNAL :
910                        begin
911                            next_matrix = mt_matrix;
912                            next_rotor_matrix = ttm_matrix;
913                            next_state = IDLE;
914                        end
915                endcase
916            end
917        endmodule
918
919        module trig(trig);
920
921            input [1:0] theta;
922            input [1:0] sin;
923            input [1:0] cos;
924
925            output [9*`TRIG_OUTBITS-1:0] matrix;
926
927            localparam MAX = {2'b01, {(`TRIG_OUTBITS-2){1'b0}}};
928
929            reg [`TRIG_OUTBITS-1:0]
930                a_x, a_y, a_z, b_x, b_y, b_z, c_x, c_y, c_z;
931            assign matrix =
932                {a_x, a_y, a_z, b_x, b_y, b_z, c_x, c_y, c_z};
933
934            wire [9*`TRIG_OUTBITS-1:0] neg_sin;
935
936            trig t (theta, sin, cos);
937
938            next_select = select;
939            next_temp0 = temp0;
940            next_temp1 = templ;
941            next_matrix = matrix;
942
943            if (timer || enable) begin
944                case (state)
945                    IDLE:
946                        if (enable) begin
947                            next_state = X_ROTATION;
948                            next_theta = theta_x;
949                            next_select = 2'b0;
950                        end
951                    X_ROTATION:
952                        begin
953                            next_state = YROTATION ;
954                            next_theta = theta_y;
955                            next_select = 2'b1;
956                            next_temp0 = ttm_matrix;
957                        end
958                    YROTATION :
959                        begin
960                            next_temp1 = ttm_matrix;
961                            next_state = Z_ROTATION;
962                            next_theta = theta_z;
963                            next_select = 2'b10;
964                        end
965                    Z_ROTATION:
966                        begin
967                            next_temp0 = mt_matrix;
968                            next_temp1 = ttm_matrix;
969                            next_theta = theta_rotor;
970                            next_select = 2'b10;
971                            next_state = FNAL ;
972                        end
973                    FNAL :
974                        begin
975                            next_matrix = mt_matrix;
976                            next_rotor_matrix = ttm_matrix;
977                            next_state = IDLE;
978                        end
979                endcase
980            end
981        endmodule
982
983        module assign(assign);
984
985            input [9*`TRIG_OUTBITS-1:0] matrix;
986
987            localparam MAX = {2'b01, {(`TRIG_OUTBITS-2){1'b0}}};
988
989            reg [9*`TRIG_OUTBITS-1:0]
990                a_x, a_y, a_z, b_x, b_y, b_z, c_x, c_y, c_z;
991            assign matrix =
992                {a_x, a_y, a_z, b_x, b_y, b_z, c_x, c_y, c_z};
993
994            wire [9*`TRIG_OUTBITS-1:0] neg_sin;
995
996            trig t (theta, sin, cos);
997
998            next_select = select;
999            next_temp0 = temp0;
1000           next_temp1 = templ;
1001          next_matrix = matrix;
1002
1003          if (timer || enable) begin
1004              case (state)
1005                  IDLE:
1006                      if (enable) begin
1007                          next_state = X_ROTATION;
1008                          next_theta = theta_x;
1009                          next_select = 2'b0;
1010                      end
1011                  X_ROTATION:
1012                      begin
1013                          next_state = YROTATION ;
1014                          next_theta = theta_y;
1015                          next_select = 2'b1;
1016                          next_temp0 = ttm_matrix;
1017                      end
1018                  YROTATION :
1019                      begin
1020                          next_temp1 = ttm_matrix;
1021                          next_state = Z_ROTATION;
1022                          next_theta = theta_z;
1023                          next_select = 2'b10;
1024                      end
1025                  Z_ROTATION:
1026                      begin
1027                          next_temp0 = mt_matrix;
1028                          next_temp1 = ttm_matrix;
1029                          next_theta = theta_rotor;
1030                          next_select = 2'b10;
1031                          next_state = FNAL ;
1032                      end
1033                  FNAL :
1034                      begin
1035                          next_matrix = mt_matrix;
1036                          next_rotor_matrix = ttm_matrix;
1037                          next_state = IDLE;
1038                      end
1039              endcase
1040          end
1041      endmodule
1042
1043      module wire(wire);
1044
1045          input [9*`TRIG_OUTBITS-1:0] matrix;
1046
1047          localparam MAX = {2'b01, {(`TRIG_OUTBITS-2){1'b0}}};
1048
1049          reg [9*`TRIG_OUTBITS-1:0]
1050              a_x, a_y, a_z, b_x, b_y, b_z, c_x, c_y, c_z;
1051          assign matrix =
1052              {a_x, a_y, a_z, b_x, b_y, b_z, c_x, c_y, c_z};
1053
1054          wire [9*`TRIG_OUTBITS-1:0] neg_sin;
1055
1056          trig t (theta, sin, cos);
1057
1058          next_select = select;
1059          next_temp0 = temp0;
1060          next_temp1 = templ;
1061          next_matrix = matrix;
1062
1063          if (timer || enable) begin
1064              case (state)
1065                  IDLE:
1066                      if (enable) begin
1067                          next_state = X_ROTATION;
1068                          next_theta = theta_x;
1069                          next_select = 2'b0;
1070                      end
1071                  X_ROTATION:
1072                      begin
1073                          next_state = YROTATION ;
1074                          next_theta = theta_y;
1075                          next_select = 2'b1;
1076                          next_temp0 = ttm_matrix;
1077                      end
1078                  YROTATION :
1079                      begin
1080                          next_temp1 = ttm_matrix;
1081                          next_state = Z_ROTATION;
1082                          next_theta = theta_z;
1083                          next_select = 2'b10;
1084                      end
1085                  Z_ROTATION:
1086                      begin
1087                          next_temp0 = mt_matrix;
1088                          next_temp1 = ttm_matrix;
1089                          next_theta = theta_rotor;
1090                          next_select = 2'b10;
1091                          next_state = FNAL ;
1092                      end
1093                  FNAL :
1094                      begin
1095                          next_matrix = mt_matrix;
1096                          next_rotor_matrix = ttm_matrix;
1097                          next_state = IDLE;
1098                      end
1099              endcase
1100          end
1101      endmodule
1102
1103      module trig(trig);
1104
1105          input [1
```

```

theta_to_matrix.v
_____
127 signed_negate #(`TRIG_OUT_BITS) sn (sin, neg_sin);
128
129 assign nsin = neg_sin[`TRIG_OUT_BITS-1:0];
130
131 always @ (theta, select, cos, sin, nsin) begin
132   {a_x, a_y, a_z, b_x, b_y, b_z, c_x, c_y, c_z} =
133     {(9*`TRIG_OUT_BITS){1'b0}};
134   case (select)
135     2'd0:
136       begin
137         a_x = MAX;
138         b_y = cos;
139         b_z = sin;
140         c_y = nsin;
141         c_z = cos;
142       end
143     2'd1:
144       begin
145         a_x = cos;
146         a_z = nsin;
147         b_y = MAX;
148         c_x = sin;
149         c_z = cos;
150       end
151     2'd2:
152       begin
153         a_x = cos;
154         a_y = sin;
155         b_x = nsin;
156         b_y = cos;
157         c_z = MAX;
158       end
159     endcase
160   end
161 endmodule
162
163 module divider(reset, clock, enable);
164   parameter COUNT = 10'd10;
165   input clock;
166   input reset;
167   output enable;
168
169   reg [9:0]counter;
170   reg enable;
171
172   always @(posedge clock)
173   begin
174     enable <= 1'b0;
175     if (reset)
176       counter <= 10'b0;
177     else if (counter == COUNT)
178       begin
179         counter <= 10'b0;
180         enable <= 1'b1;
181       end
182     else
183       counter <= counter + 1;
184   end
185 endmodule
186

```

Page: 3

```

labkit.v
_____
1 //////////////////////////////////////////////////////////////////
2 //
3 // 6.111 FPGA Labkit -- Template Toplevel Module for Lab 4 (Spring 2006)
4 //
5 //
6 // Created: March 13, 2006
7 // Author: Nathan Ickes
8 //
9 //////////////////////////////////////////////////////////////////
10
11 module labkit (beep, audio_reset_b, ac97_sdata_out, ac97_sdata_in, ac97_synth,
12   ac97_bit_clock,
13
14   vga_out_red, vga_out_green, vga_out_blue, vga_out_sync_b,
15   vga_out_blank_b, vga_out_pixel_clock, vga_out_hsync,
16   vga_out_vsync,
17
18   tv_out_ycrcb, tv_out_reset_b, tv_out_clock, tv_out_i2c_clock,
19   tv_out_i2c_data, tv_out_pal_ntsc, tv_out_hsync_b,
20   tv_out_vsync_b, tv_out_blank_b, tv_out_subcar_reset,
21
22   tv_in_ycrcb, tv_in_data_valid, tv_in_line_clock1,
23   tv_in_line_clock2, tv_in_aef, tv_in_hff, tv_in_aff,
24   tv_in_i2c_clock, tv_in_i2c_data, tv_in_fifo_read,
25   tv_in_fifo_clock, tv_in_iso, tv_in_reset_b, tv_in_clock,
26
27   ram0_data, ram0_address, ram0_adv_ld, ram0_clk, ram0_cen_b,
28   ram0_ce_b, ram0_oe_b, ram0_we_b, ram0_bwe_b,
29
30   raml_data, raml_address, raml_adv_ld, raml_clk, raml_cen_b,
31   raml_ce_b, raml_oe_b, raml_we_b, raml_bwe_b,
32
33   clock_feedback_out, clock_feedback_in,
34
35   flash_data, flash_address, flash_ce_b, flash_oe_b, flash_we_b,
36   flash_reset_b, flash_sts, flash_byte_b,
37
38   rs232_txd, rs232_rxd, rs232_rts, rs232_cts,
39
40   mouse_clock, mouse_data, keyboard_clock, keyboard_data,
41
42   clock_27mhz, clock1, clock2,
43
44   disp_blank, disp_data_out, disp_clock, disp_rs, disp_ce_b,
45   disp_reset_b, disp_data_in,
46
47   button0, button1, button2, button3, button_enter, button_right,
48   button_left, button_down, button_up,
49
50   switch,
51
52   led,
53
54   user1, user2, user3, user4,
55
56   daughtercard,
57
58   systemace_data, systemace_address, systemace_ce_b,
59   systemace_we_b, systemace_oe_b, systemace_irq, systemace_mpbrdy,
60
61   analyzer1_data, analyzer1_clock,
62   analyzer2_data, analyzer2_clock,
63   analyzer3_data, analyzer3_clock,

```

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```

64      analyzer4_data, analyzer4_clock);
65
66 output beep, audio_reset_b, ac97_synch, ac97_sdata_out;
67 input ac97_bit_clock, ac97_sdata_in;
68
69 output [7:0] vga_out_red, vga_out_green, vga_out_blue;
70 output vga_out_sync_b, vga_out_blank_b, vga_out_pixel_clock,
71   vga_out_hsync, vga_out_vsync;
72
73 output [9:0] tv_out_ycrcb;
74 output tv_out_reset_b, tv_out_clock, tv_out_i2c_clock, tv_out_i2c_data,
75   tv_out_pal_ntsc, tv_out_hsync_b, tv_out_vsync_b, tv_out_blank_b,
76   tv_out_subcar_reset;
77
78 input [19:0] tv_in_yrcrb;
79 input tv_in_data_valid, tv_in_line_clock1, tv_in_line_clock2, tv_in_aef,
80   tv_in_hff, tv_in_aff;
81 output tv_in_i2c_clock, tv_in_fifo_read, tv_in_fifo_clock, tv_in_iso,
82   tv_in_reset_b, tv_in_clock;
83 inout tv_in_i2c_data;
84
85 inout [35:0] ram0_data;
86 output [18:0] ram0_address;
87 output ram0_adv_ld, ram0_clk, ram0_cen_b, ram0_ce_b, ram0_oe_b, ram0_we_b;
88 output [3:0] ram0_bwe_b;
89
90 inout [35:0] ram1_data;
91 output [18:0] ram1_address;
92 output ram1_adv_ld, ram1_clk, ram1_cen_b, ram1_ce_b, ram1_oe_b, ram1_we_b;
93 output [3:0] ram1_bwe_b;
94
95 input clock_feedback_in;
96 output clock_feedback_out;
97
98 inout [15:0] flash_data;
99 output [23:0] flash_address;
100 output flash_ce_b, flash_oe_b, flash_we_b, flash_reset_b, flash_byte_b;
101 input flash_sts;
102
103 output rs232_txd, rs232_rts;
104 input rs232_rxd, rs232_cts;
105
106 input mouse_clock, mouse_data, keyboard_clock, keyboard_data;
107
108 input clock_27mhz, clock1, clock2;
109
110 output disp_blank, disp_clock, disp_rs, disp_ce_b, disp_reset_b;
111 input disp_data_in;
112 output disp_data_out;
113
114 input button0, button1, button2, button3, button_enter, button_right,
115   button_left, button_down, button_up;
116 input [7:0] switch;
117 output [7:0] led;
118
119 inout [31:0] user1, user2, user3, user4;
120
121 inout [43:0] daughtercard;
122
123 inout [15:0] systemace_data;
124 output [6:0] systemace_address;
125 output systemace_ce_b, systemace_we_b, systemace_oe_b;
126 input systemace_irq, systemace_mpbrdy;

```

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```

127
128 output [15:0] analyzer1_data, analyzer2_data, analyzer3_data,
129   analyzer4_data;
130 output analyzer1_clock, analyzer2_clock, analyzer3_clock, analyzer4_clock;
131
132 // I/O Assignments
133 //
134 // Audio Input and Output
135 assign beep = 1'b0;
136 assign audio_reset_b = 1'b0;
137 assign ac97_synch = 1'b0;
138 assign ac97_sdata_out = 1'b0;
139
140 // Video Output
141 assign tv_out_ycrcb = 10'h0;
142 assign tv_out_reset_b = 1'b0;
143 assign tv_out_clock = 1'b0;
144 assign tv_out_i2c_clock = 1'b0;
145 assign tv_out_i2c_data = 1'b0;
146 assign tv_out_pal_ntsc = 1'b0;
147 assign tv_out_hsync_b = 1'b1;
148 assign tv_out_vsync_b = 1'b1;
149 assign tv_out_blank_b = 1'b1;
150 assign tv_out_subcar_reset = 1'b0;
151
152 // Video Input
153 assign tv_in_i2c_clock = 1'b0;
154 assign tv_in_fifo_read = 1'b0;
155 assign tv_in_fifo_clock = 1'b0;
156 assign tv_in_iso = 1'b0;
157 assign tv_in_reset_b = 1'b0;
158 assign tv_in_clock = 1'b0;
159 assign tv_in_i2c_data = 1'bZ;
160
161 // Flash ROM
162 assign flash_data = 16'hZ;
163 assign flash_address = 24'h0;
164 assign flash_ce_b = 1'b1;
165 assign flash_oe_b = 1'b1;
166 assign flash_we_b = 1'b1;
167 assign flash_reset_b = 1'b0;
168 assign flash_byte_b = 1'b1;
169
170 // RS-232 Interface
171 assign rs232_txd = 1'b1;
172 assign rs232_rts = 1'b1;
173
174 // LED Displays
175 assign disp_blank = 1'b1;
176 assign disp_clock = 1'b0;
177 assign disp_rs = 1'b0;
178 assign disp_ce_b = 1'b1;
179 assign disp_oe_b = 1'b0;
180 assign disp_we_b = 1'b0;
181 assign disp_reset_b = 1'b0;
182 assign disp_data_out = 1'b0;
183
184 // Buttons, Switches, and Individual LEDs
185 assign led = 8'hFF;
186
187 // User I/Os
188
189

```

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labkit.v

```

190 assign user1 = 32'hz;
191 assign user2 = 32'hz;
192 assign user3 = 32'hz;
193 assign user4 = 32'hz;
194
195 // Daughtercard Connectors
196 assign daughtercard = 44'hz;
197
198 // SystemACE Microprocessor Port
199 assign systemace_data = 16'hz;
200 assign systemace_address = 7'ho;
201 assign systemace_ce_b = 1'b1;
202 assign systemace_we_b = 1'b1;
203 assign systemace_oe_b = 1'b1;
204
205 /////////////////////////////////
206 //
207 // Lab 4 Components
208 //
209 ///////////////////////////////
210
211 wire pclk, pixel_clock, locked;
212
213 assign pixel_clock = clock_27mhz;
214 assign ram0_clk = pixel_clock;
215 assign ram1_clk = pixel_clock;
216 assign clock_feedback_out = 1'b0;
217
218 DCM pixel_clock_dcml (.CLKIN(pixel_clock), .CLKFX(vga_out_pixel_clock));
219 // synthesis attribute CLKFX_DIVIDE of pixel_clock_dcml is 2
220 // synthesis attribute CLKFX_MULTIPLY of pixel_clock_dcml is 2
221 // synthesis attribute CLK_FEEDBACK of pixel_clock_dcml is "NONE"
222 // synthesis attribute CLKOUT_PHASE_SHIFT of pixel_clock_dcml is "NONE"
223 // synthesis attribute PHASE_SHIFT of pixel_clock_dcml is 0
224
225 // The composite sync signal is used to encode sync data in the green
226 // channel analog voltage for older monitors. It does not need to be
227 // implemented for the monitors in the 6.111 lab, and can be left at 1'b1.
228 assign vga_out_sync_b = 1'b1;
229
230 wire reset_sync, up_sync, down_sync;
231 wire [8:0] buttons;
232
233 debounce db1 (1'b0, pixel_clock, ~button0, reset_sync);
234 debounce db2 (1'b0, pixel_clock, ~button1, up_sync);
235 debounce db3 (1'b0, pixel_clock, ~button2, down_sync);
236 debounce db4 (1'b0, pixel_clock, ~button_right, buttons[0]);
237 debounce db5 (1'b0, pixel_clock, ~button_left, buttons[1]);
238 debounce db6 (1'b0, pixel_clock, ~button_down, buttons[2]);
239 debounce db7 (1'b0, pixel_clock, ~button_up, buttons[3]);
240 debounce db8 (1'b0, pixel_clock, ~button1, buttons[4]);
241 debounce db9 (1'b0, pixel_clock, ~button2, buttons[5]);
242 debounce db10 (1'b0, pixel_clock, ~button3, buttons[6]);
243 debounce db11 (1'b0, pixel_clock, ~button_enter, buttons[7]);
244
245 assign buttons[8] = switch[7];
246
247 internal internal(
248     .reset(reset_sync), .clock(pixel_clock),
249     .model_select({2'b0, switch[0], switch[6]}),
250     .paddle_up(up_sync),
251

```

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```

253     .paddle_down(down_sync),
254     .paddle_speed({switch[5:3], 1'b1}),
255     .ball_initial_speed({switch[2:0], 1'b1}), // game inputs
256
257     .ram0_data(ram0_data),
258     .ram0_address(ram0_address),
259     .ram0_we_b(ram0_we_b), // ram 0 buss
260     .ram1_data(ram1_data),
261     .ram1_address(ram1_address),
262     .ram1_we_b(ram1_we_b), // ram 1 buss
263
264     .mouse0_clock(mouse_clock),
265     .mouse0_data(mouse_data), // ps/2 0 buss
266     .mouse1_clock(keyboard_clock),
267     .mouse1_data(keyboard_data), // ps/2 1 buss
268
269     .buttons(buttons),
270
271     .vga_rgb({vga_out_red, vga_out_green, vga_out_blue}),
272     .vga_blank_b(vga_out_blank_b),
273     .vga_hsync(vga_out_hsync),
274     .vga_vsync(vga_out_vsync) // vga outputs
275 );
276
277 // SRAMs
278 assign ram0_adv_ld = 1'b0;
279 assign ram0_cen_b = 1'b0;
280 assign ram0_ce_b = 1'b0;
281 assign ram0_oe_b = 1'b0;
282 assign ram0_bwe_b = 4'h0;
283 assign ram1_adv_ld = 1'b0;
284 assign ram1_cen_b = 1'b0;
285 assign ram1_ce_b = 1'b0;
286 assign ram1_oe_b = 1'b0;
287 assign ram1_bwe_b = 4'h0;
288
289 // Logic Analyzer
290 assign analyzer1_data = 16'h0;
291 assign analyzer1_clock = 1'b1;
292 assign analyzer2_data = {ram0_we_b, ram0_address[14:0]};
293 assign analyzer2_clock = ram0_clk;
294 assign analyzer3_data = 16'h0;
295 assign analyzer3_clock = 1'b1;
296 assign analyzer4_data = {ram0_data[15:0]};
297 assign analyzer4_clock = ram0_clk;
298 endmodule
299
300 // Switch Debounce Module
301 // use your system clock for the clock input
302 // to produce a synchronous, debounced output
303 module debounce (reset, clock, noisy, clean);
304     parameter DELAY = 270000; // .01 sec with a 27Mhz clock
305     input reset, clock, noisy;
306     output clean;
307
308     reg [18:0] count;
309     reg new, clean;
310
311     always @(posedge clock)
312         if (reset)
313             begin
314                 count <= 0;
315                 new <= noisy;

```

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```

316     clean <= noisy;
317     end
318   else if (noisy != new)
319     begin
320       new <= noisy;
321       count <= 0;
322     end
323   else if (count == DELAY)
324     clean <= new;
325   else
326     count <= count+1;
327
328 endmodule
329

```

```

internal_tf.v
`timescale 1ns / 1ps
module internal_tf_v;
  // Inputs
  reg reset;
  reg clock;
  reg [3:0] model_select;
  reg paddle_up;
  reg paddle_down;
  reg [3:0] paddle_speed;
  reg [3:0] ball_initial_speed;
  reg mouse0_clock;
  reg mouse0_data;
  reg mouse1_clock;
  reg mouse1_data;
  reg [7:0] buttons;
  reg [35:0] write_data;
  reg tristate;

  // Outputs
  wire [18:0] ram0_address;
  wire ram0_we_b;
  wire [18:0] ram1_address;
  wire ram1_we_b;
  wire [23:0] vga_rgb;
  wire vga_blank_b;
  wire vga_hsync;
  wire vga_vsync;
  wire [35:0] ram0_data;
  wire [35:0] ram1_data;
  assign ram0_data = (tristate) ? {36{1'bZ}} : write_data;

  // Instantiate the Unit Under Test (UUT)
  internal uut (
    .reset(reset),
    .clock(clock),
    .model_select(model_select),
    .paddle_up(paddle_up),
    .paddle_down(paddle_down),
    .paddle_speed(paddle_speed),
    .ball_initial_speed(ball_initial_speed),
    .ram0_data(ram0_data),
    .ram0_address(ram0_address),
    .ram0_we_b(ram0_we_b),
    .ram1_data(ram1_data),
    .ram1_address(ram1_address),
    .ram1_we_b(ram1_we_b),
    .mouse0_clock(mouse0_clock),
    .mouse0_data(mouse0_data),
    .mouse1_clock(mouse1_clock),
    .mouse1_data(mouse1_data),
    .vga_rgb(vga_rgb),
    .vga_blank_b(vga_blank_b),
    .vga_hsync(vga_hsync),
    .vga_vsync(vga_vsync),
    .buttons(buttons)
  );
  always #5 clock <= ~clock;
  initial begin
    // Initialize Inputs

```

internal_tf.v

```

64      reset = 0;
65      clock = 0;
66      model_select = 0;
67      paddle_up = 0;
68      paddle_down = 0;
69      paddle_speed = 0;
70      ball_initial_speed = 0;
71      mouse0_clock = 0;
72      mouse0_data = 0;
73      mousel_clock = 0;
74      mousel_data = 0;
75      tristate = 1;
76      write_data = 0;
77      buttons = 0;
78      // Wait 100 ns for global reset to finish
79      #100;
80      reset = 1;
81      @(posedge clock);
82      @(posedge clock);
83      @(posedge clock);
84      reset = 0;
85      @(posedge clock);
86      @(posedge clock);
87      @(posedge clock);
88      tristate = 0;
89      @(posedge clock);
90      tristate = 1;
91      @(posedge clock);
92      tristate = 0;
93      @(posedge clock);
94      tristate = 1;
95      @(posedge clock);
96      tristate = 0;
97      @(posedge clock);
98      tristate = 1;
99      @(posedge clock);
100     tristate = 0;
101     @(posedge clock);
102     tristate = 1;
103     @(posedge clock);
104     tristate = 0;
105     @(posedge clock);
106     tristate = 1;
107   end
108 endmodule
109
110

```

defines.v

```

1  `define COORD_BITS (12)
2  `define COLOR_BITS (24)
3  `define POINT_BITS (3 * `COORD_BITS)
4  `define TRIANGLE_BITS ((3 * `POINT_BITS) + `COLOR_BITS)
5  `define NORMAL_BITS (3 * `COORD_BITS)
6
7  // For Trig Functions
8  `define TRIG_IN_BITS (8)
9  `define TRIG_OUT_BITS (13)
10
11 // SVGA Output
12 `define PIXEL_BITS (10*2+12+24)
13 `define SCREEN_WIDTH (640)
14 `define SCREEN_HEIGHT (480)
15
16 `define P2D_BITS (2 * `COORD_BITS)
17 `define LINE_BITS (2 * `P2D_BITS)
18 `define RHOMBUS_BITS (2 * `LINE_BITS + 5*`COORD_BITS)
19
20 `define NUM_BUTTONS (9)
21
22 `define ROTOR_COLOR (24'h3F3FB)
23 `define BALL_COLOR (24'hBEA33F)
24 `define PADDLE_COLOR (24'hBE3FB)
25
26
27 `define MIT_RED (24'h5B1F1F) //{{8'b0101_1111, 8'b0001_1111, 8'b0001_1111}}
28 `define MIT_GRAY ({8'b0100_1111, 8'b0100_1111, 8'b0011_1111})
29

```

```
params.v
1 // params.v
2 // Global Constants (Used in more than one module)
3 parameter DISPLAYWIDTH    = 10d640 ;
4 parameter DISPLAYHEIGHT   = 10d480 ;
5 parameter PADDE_WIDTH    = 10d16 ;
6 parameter PADDE_HEIGHT   = 10d128 ;
7 parameter PADDE_X        = 10d28 ;
8 parameter BALWIDTH       = 10d64 ;
9 parameter BALHEIGHT      = 10d64 ;
10 parameter BORDERWIDTH    = 10d8 ;
11 parameter BORDERHEIGHT   = 10d8 ;
12 parameter MAXSPEED      = 5bill1111 ;
13
14 parameter POS = 0;
15 parameter NEG = 1;
16
17
```