

A Labkit Listing

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module labkit (beep, audio_reset_b, ac97_sdata_out, ac97_sdata_in, ac97_synch,
ac97_bit_clock,

vga_out_red, vga_out_green, vga_out_blue, vga_out_sync_b,
vga_out_blank_b, vga_out_pixel_clock, vga_out_hsync,
vga_out_vsync,

tv_out_ycrcb, tv_out_reset_b, tv_out_clock, tv_out_i2c_clock,
tv_out_i2c_data, tv_out_pal_ntsc, tv_out_hsync_b,
tv_out_vsync_b, tv_out_blank_b, tv_out_subcar_reset,

tv_in_ycrcb, tv_in_data_valid, tv_in_line_clock1,
tv_in_line_clock2, tv_in_aef, tv_in_hff, tv_in_aff,
tv_in_i2c_clock, tv_in_i2c_data, tv_in_fifo_read,
tv_in_fifo_clock, tv_in_iso, tv_in_reset_b, tv_in_clock,

ram0_data, ram0_address, ram0_adv_ld, ram0_clk, ram0_cen_b,
ram0_ce_b, ram0_oe_b, ram0_we_b, ram0_bwe_b,

ram1_data, ram1_address, ram1_adv_ld, ram1_clk, ram1_cen_b,
ram1_ce_b, ram1_oe_b, ram1_we_b, ram1_bwe_b,

clock_feedback_out, clock_feedback_in,

flash_data, flash_address, flash_ce_b, flash_oe_b, flash_we_b,
flash_reset_b, flash_sts, flash_byte_b,

rs232_txd, rs232_rxd, rs232_rts, rs232_cts,

mouse_clock, mouse_data, keyboard_clock, keyboard_data,
clock_27mhz, clock1, clock2,

disp_blank, disp_data_out, disp_clock, disp_rs, disp_ce_b,
disp_reset_b, disp_data_in,

button0, button1, button2, button3, button_enter, button_right,
button_left, button_down, button_up,

switch,

led,

user1, user2, user3, user4,
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daughtercard,

systemace_data, systemace_address, systemace_ce_b,
systemace_we_b, systemace_oe_b, systemace_irq, systemace_mpbrdy,

analyzer1_data, analyzer1_clock,
analyzer2_data, analyzer2_clock,
analyzer3_data, analyzer3_clock,
analyzer4_data, analyzer4_clock);

output beep, audio_reset_b, ac97_synch, ac97_sdata_out;
input ac97_bit_clock, ac97_sdata_in;

output [7:0] vga_out_red, vga_out_green, vga_out_blue;
output vga_out_sync_b, vga_out_blank_b, vga_out_pixel_clock,
vga_out_hsync, vga_out_vsync;

output [9:0] tv_out_ycrcb;
output tv_out_reset_b, tv_out_clock, tv_out_i2c_clock, tv_out_i2c_data,
tv_out_pal_ntsc, tv_out_hsync_b, tv_out_vsync_b, tv_out_blank_b,
tv_out_subcar_reset;

input [19:0] tv_in_ycrcb;
input tv_in_data_valid, tv_in_line_clock1, tv_in_line_clock2, tv_in_aef,
tv_in_hff, tv_in_aff;
output tv_in_i2c_clock, tv_in_fifo_read, tv_in_fifo_clock, tv_in_iso,
tv_in_reset_b, tv_in_clock;
inout tv_in_i2c_data;

inout [35:0] ram0_data;
output [18:0] ram0_address;
output ram0_adv_ld, ram0_clk, ram0_cen_b, ram0_ce_b, ram0_oe_b, ram0_we_b;
output [3:0] ram0_bwe_b;

inout [35:0] ram1_data;
output [18:0] ram1_address;
output ram1_adv_ld, ram1_clk, ram1_cen_b, ram1_ce_b, ram1_oe_b, ram1_we_b;
output [3:0] ram1_bwe_b;

input clock_feedback_in;
output clock_feedback_out;

inout [15:0] flash_data;

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output [23:0] flash_address;
output flash_ce_b, flash_oe_b, flash_we_b, flash_reset_b, flash_byte_b;
input  flash_sts;

output rs232_txd, rs232_rts;
input  rs232_rxd, rs232_cts;

input  mouse_clock, mouse_data, keyboard_clock, keyboard_data;

input  clock_27mhz, clock1, clock2;

output disp_blank, disp_clock, disp_rs, disp_ce_b, disp_reset_b;
input  disp_data_in;
output disp_data_out;

input  button0, button1, button2, button3, button_enter, button_right,
button_left, button_down, button_up;
input  [7:0] switch;
output [7:0] led;

inout [31:0] user1, user2, user3, user4;

inout [43:0] daughtercard;

inout [15:0] systemace_data;
output [6:0] systemace_address;
output systemace_ce_b, systemace_we_b, systemace_oe_b;
input  systemace_irq, systemace_mpbrdy;

output [15:0] analyzer1_data, analyzer2_data, analyzer3_data,
analyzer4_data;
output analyzer1_clock, analyzer2_clock, analyzer3_clock, analyzer4_clock;

///////////////////////////////
// I/O Assignments
///////////////////////////////

// Audio Input and Output
assign beep= 1'b0;
assign audio_reset_b = 1'b0;
assign ac97_synch = 1'b0;
assign ac97_sdata_out = 1'b0;

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// Video Output
assign tv_out_ycrcb = 10'h0;
assign tv_out_reset_b = 1'b0;
assign tv_out_clock = 1'b0;
assign tv_out_i2c_clock = 1'b0;
assign tv_out_i2c_data = 1'b0;
assign tv_out_pal_ntsc = 1'b0;
assign tv_out_hsync_b = 1'b1;
assign tv_out_vsync_b = 1'b1;
assign tv_out_blank_b = 1'b1;
assign tv_out_subcar_reset = 1'b0;

// Video Input
//assign tv_in_i2c_clock = 1'b0;
assign tv_in_fifo_read = 1'b1;
assign tv_in_fifo_clock = 1'b0;
assign tv_in_iso = 1'b1;
//assign tv_in_reset_b = 1'b0;
assign tv_in_clock = clock_27mhz;//1'b0;
//assign tv_in_i2c_data = 1'bZ;
// tv_in_ycrcb, tv_in_data_valid, tv_in_line_clock1, tv_in_line_clock2,
// tv_in_aef, tv_in_hff, and tv_in_aff are inputs

// SRAMs
assign ram0_data = 36'hZ;
assign ram0_address = 19'h0;
assign ram0_adv_ld = 1'b0;
assign ram0_clk = 1'b0;
assign ram0_cen_b = 1'b1;
assign ram0_ce_b = 1'b1;
assign ram0_oe_b = 1'b1;
assign ram0_we_b = 1'b1;
assign ram0_bwe_b = 4'hF;
assign ram1_data = 36'hZ;
assign ram1_address = 19'h0;
assign ram1_adv_ld = 1'b0;
assign ram1_clk = 1'b0;
assign ram1_cen_b = 1'b1;
assign ram1_ce_b = 1'b1;
assign ram1_oe_b = 1'b1;
assign ram1_we_b = 1'b1;
assign ram1_bwe_b = 4'hF;
assign clock_feedback_out = 1'b0;

// Flash ROM

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assign flash_data = 16'hZ;
assign flash_address = 24'h0;
assign flash_ce_b = 1'b1;
assign flash_oe_b = 1'b1;
assign flash_we_b = 1'b1;
assign flash_reset_b = 1'b0;
assign flash_byte_b = 1'b1;

// RS-232 Interface
assign rs232_txd = 1'b1;
assign rs232_rts = 1'b1;

// LED Displays
//assign disp_blank = 1'b1;
//assign disp_clock = 1'b0;
//assign disp_rs = 1'b0;
//assign disp_ce_b = 1'b1;
//assign disp_reset_b = 1'b0;
//assign disp_data_out = 1'b0;

// Buttons, Switches, and Individual LEDs
assign led = 8'hFF;

// User I/Os
assign user1 = 32'hZ;
assign user2 = 32'hZ;
assign user3 = 32'hZ;
assign user4 = 32'hZ;

// Daughtercard Connectors
assign daughtercard = 44'hZ;

// SystemACE Microprocessor Port
assign systemace_data = 16'hZ;
assign systemace_address = 7'h0;
assign systemace_ce_b = 1'b1;
assign systemace_we_b = 1'b1;
assign systemace_oe_b = 1'b1;

// Logic Analyzer
//assign analyzer1_data = 16'h0;
assign analyzer1_clock = 1'b1;
//assign analyzer2_data = 16'h0;
//assign analyzer2_clock = clock_64mhz;
//assign analyzer3_data = 16'h0;

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assign analyzer3_clock = 1'b1;
//assign analyzer4_data = 16'h0;
assign analyzer4_clock = 1'b1;

///////////////////////////////
// Fingerprint ID
///////////////////////////////

// use FPGA's digital clock manager to produce a
// 31.5 MHz pixel clock from clock_27mhz           // 15, 14
wire clock_32mhz_unbuf,clock_32mhz;
DCM pxl_clk_dcm (.CLKIN(clock_27mhz), .CLKFX(clock_32mhz_unbuf));
// synthesis attribute CLKFX_DIVIDE of pxl_clk_dcm is 15
// synthesis attribute CLKFX_MULTIPLY of pxl_clk_dcm is 14
// synthesis attribute CLK_FEEDBACK of pxl_clk_dcm  is "NONE"
// synthesis attribute CLKIN_PERIOD of pxl_clk_dcm  is 37
BUFG pxl_clk_buf (.O(clock_32mhz), .I(clock_32mhz_unbuf));
wire pxl_clk = clock_32mhz;

// use FPGA's digital clock manager to produce a
// 65MHz clock (actually 64.8MHz)
wire clock_65mhz_unbuf,clock_65mhz;
DCM video_clk_dcm (.CLKIN(clock_27mhz), .CLKFX(clock_65mhz_unbuf));
// synthesis attribute CLKFX_DIVIDE of video_clk_dcm is 10
// synthesis attribute CLKFX_MULTIPLY of video_clk_dcm is 24
// synthesis attribute CLK_FEEDBACK of video_clk_dcm is NONE
// synthesis attribute CLKIN_PERIOD of video_clk_dcm is 37
BUFG video_clk_buf (.O(clock_65mhz),.I(clock_65mhz_unbuf));
wire video_clk = clock_65mhz;

// main clock
wire clk = clock_65mhz;

// power-on reset generation
wire power_on_reset;    // remain high for first 16 clocks
SRL16 reset_sr (.D(1'b0), .CLK(clk), .Q(power_on_reset),
.A0(1'b1), .A1(1'b1), .A2(1'b1), .A3(1'b1));
defparam reset_sr.INIT = 16'hFFFF;

// button0 is reset
wire reset,user_reset;
debounce db1(user_reset, clk, ~button0, user_reset);
assign reset = user_reset | power_on_reset;

// generate basic VGA video signals

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// delay for memory delay shift
wire hs_out, vs_out, bb_out;
reg hs, hs1, hs2, hs3, hs4;
reg vs, vs1, vs2, vs3, vs4;
reg bb, bb1, bb2, bb3, bb4;
always @ (posedge pxl_clk) begin
    hs <= hs4; /*hs1 <= hs2; hs2 <= hs3; hs3 <= hs4;*/ hs4 <= hs_out;
    vs <= vs4; /*vs1 <= vs2; vs2 <= vs3; vs3 <= vs4;*/ vs4 <= vs_out;
    bb <= bb4; /*bb1 <= bb2; bb2 <= bb3; bb3 <= bb4;*/ bb4 <= bb_out;
end
assign vga_out_hsync = hs;
assign vga_out_vsync = vs;
assign vga_out_blank_b = bb;
// Inverting the clock to the DAC provides half a clock period for signals
// to propagate from the FPGA to the DAC.
assign vga_out_pixel_clock = ~pxl_clk;
wire [9:0] h_cnt, v_cnt;
wire hsync,vsync,blank;
vga vga1(reset,hs_out,vs_out,vga_out_sync_b,bb_out,h_cnt,v_cnt,pxl_clk);

// ADV7185 NTSC decoder interface code
// adv7185 initialization module
adv7185init adv7185(.reset(reset), .clock_27mhz(clock_27mhz),
    .source(1'b0), .tv_in_reset_b(tv_in_reset_b),
    .tv_in_i2c_clock(tv_in_i2c_clock),
    .tv_in_i2c_data(tv_in_i2c_data));

wire [29:0] ycrcb; // video data (luminance, chrominance)
wire [2:0] fvh; // sync for field, vertical, horizontal
wire dv; // data valid
ntsc_decode decode (.clk(tv_in_line_clock1), .reset(reset),
    .tv_in_ycrcb(tv_in_ycrcb[19:10]),
    .ycrcb(ycrcb), .f(fvh[2]),
    .v(fvh[1]), .h(fvh[0]), .data_valid(dv));

// code to write NTSC data to video memory
wire [13:0] bram_addr;
wire [7:0] bram_data;
wire bram_we, frame_clk;
ntsc_to_bram n2ram (tv_in_line_clock1,fvh,dv,ycrcb[29:22],
    bram_addr, bram_data, bram_we, frame_clk,
    video_clk, reset);

// START is button_enter

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wire start, start_sync;
debounce db2(power_on_reset, clk, ~button_enter, start_sync);
pulse pls1(power_on_reset, clk, start_sync, start, 4'b0);

//wire add_user_in;
//debounce db3(power_on_reset, clk, switch[7], add_user_in);

// USER ID is switch[2:0]
// ADD_USER is switch[7]
// controller
wire [2:0] state;
wire acquire;
wire [2:0] user_id;
wire add_user;
wire process_start, process_busy,
      validate_start, validate_busy,
      validate_result;
wire [2:0] match_id;
controller control( .start(start),
                     .disp_state(state),
                     .add_user( switch[7] ),
                     .add_user_latched(add_user),
                     .user_id( switch[2:0] ),
                     .user_id_latched(user_id),
                     .acquire(acquire),
                     .process_start( process_start ),
                     .validate_start( validate_start ),
                     .validate_result( validate_result ),
                     .busy( process_busy | validate_busy ),
                     .clock( clk ),
                     .reset(reset) );

// ~30 Hz frame clock
//wire frame_clk;
//divider mk_frame_clk(frame_clk, 4'd3, clk, reset);

// display with video memory
wire proc_disp_cycle, proc_disp_we;
wire [13:0] proc_disp_addr;
wire [7:0] proc_disp_pxl;
reg disp_cycle_source, disp_we;
reg [13:0] disp_addr;
reg [7:0] disp_pxl_in;
always @ (posedge clk) begin

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    disp_cycle_source <= acquire ? frame_clk : proc_disp_cycle;
    disp_addr <= acquire ? bram_addr : proc_disp_addr;
    disp_pxl_in <= acquire ? bram_data : proc_disp_pxl ;
    disp_we <= acquire ? bram_we : proc_disp_we;
end
DisplayField display(
/* Memory Access */
.cycle_source( disp_cycle_source ),
    .addr( disp_addr ),
    .pxl_in( disp_pxl_in ),
    .we( disp_we ),
/* Normal VGA Interface */
.pixel(h_cnt), .line(v_cnt),
    .red(vga_out_red), .green(vga_out_green), .blue(vga_out_blue),
    .clock( clk ), .reset( reset )
);

// Original Image Storage
reg scan_img_we;
reg [7:0] scan_img_write_pxl;
reg [13:0] scan_img_addr;
always @ (posedge clk) begin
    scan_img_we <= bram_we & acquire;
    scan_img_write_pxl <= bram_data;
    scan_img_addr <= bram_addr;
end
wire scan_img_re;
wire [7:0] scan_img_read_pxl;
wire scan_img_rst_pxl;
wire scan_img_en_seq;
img_buffer scanned_img(
    .we( scan_img_we ), .write_pxl( scan_img_write_pxl ), .addr( scan_img_addr ),
    .re( scan_img_re ), .read_pxl( scan_img_read_pxl ),
    .reset_pxl_pos( scan_img_rst_pxl ), .enable_seq_access( scan_img_en_seq ),
.en(1'b1), .reset(reset), .clock(clk)
);

// And we're off!
wire we_row_coeff, fft_row_dv,
      we_col_coeff, fft_col_dv;
wire [31:0] row_coeff, col_coeff;
process_image process( process_start, process_busy,
    scan_img_rst_pxl, scan_img_re, scan_img_read_pxl, scan_img_en_seq,
    proc_disp_cycle, proc_disp_addr, proc_disp_pxl, proc_disp_we,
    we_row_coeff, fft_row_dv, row_coeff,

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we_col_coeff, fft_col_dv, col_coeff,
reset, clk,
sel_data_begin, sel_data_in, sel_row_data_out, sel_col_data_out, sel_row_we, sel_col_we ]]

assign analyzer2_data = { 6'b0,
                        we_row_coeff,
                        fft_row_dv,
                        we_col_coeff,
                        fft_col_dv,
                        sel_row_we,
                        sel_col_we,
                        sel_data_begin,
                        sel_data_in,
                        sel_row_data_out,
                        sel_col_data_out};

assign analyzer1_data = row_coeff[15:0];
assign analyzer3_data = col_coeff[15:0];
assign analyzer2_clock = clk;

// Multiplexer for database storage
wire [31:0] rowA_data, rowB_data, colA_data, colB_data;
wire rowA_we, rowB_we, colA_we, colB_we;
wire [3:0] rowA_addr, colA_addr;
wire [6:0] rowB_addr, colB_addr;
fft_coeff_mux row_mux( .clock(clk), .reset(reset),
    // Selection Criterion
    .add_user(add_user), .user_id(user_id),
    // Input Signals
    .in_we( we_row_coeff ), .in_rst( fft_row_dv ), .in_data( row_coeff ),
    // Routed Signals (Output)
    .bufA_data( rowA_data ), .bufA_we( rowA_we ), .bufA_addr( rowA_addr ),
    .bufB_data( rowB_data ), .bufB_we( rowB_we ), .bufB_addr( rowB_addr ) );
fft_coeff_mux col_mux( .clock(clk), .reset(reset),
    // Selection Criterion
    .add_user(add_user), .user_id(user_id),
    // Input Signals
    .in_we( we_col_coeff ), .in_rst( fft_col_dv ), .in_data( col_coeff ),
    // Routed Signals (Output)
    .bufA_data( colA_data ), .bufA_we( colA_we ), .bufA_addr( colA_addr ),
    .bufB_data( colB_data ), .bufB_we( colB_we ), .bufB_addr( colB_addr ) );

assign analyzer4_data = {2'b0, process_busy, add_user,
                        rowA_we, rowB_we, colA_we, colB_we,

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        rowA_addr,
        colA_addr };

// THRESHOLD up is button_up
// THRESHOLD down is button_down
// THRESHOLD shift left is button_left
// THRESHOLD shift right is button_right
// VIEW THRESHOLD is switch[6]
wire threshold_up, threshold_down, threshold_sl, threshold_sr,
      t_up_sync, t_down_sync, t_sl_sync, t_sr_sync;
wire disp_threshold = switch[6];
debounce db_tup(reset, clk, ~button_up, t_up_sync);
pulse pls_tup(reset, clk, t_up_sync, threshold_up, 4'd5);
debounce db_tdown(reset, clk, ~button_down, t_down_sync);
pulse pls_tdown(reset, clk, t_down_sync, threshold_down, 4'd5);
debounce db_ts1(reset, clk, ~button_left, t_sl_sync);
pulse pls_ts1(reset, clk, t_sl_sync, threshold_sl, 4'd10);
debounce db_ts2(reset, clk, ~button_right, t_sr_sync);
pulse pls_ts2(reset, clk, t_sr_sync, threshold_sr, 4'd10);

reg [63:0] threshold;
always @ (posedge clk)
  if (reset) threshold <= 20000;
  else if (threshold_up) threshold <= threshold + 1;
  else if (threshold_down) threshold <= threshold - 1;
  else if (threshold_sl) threshold <= threshold + 1;
  else if (threshold_sr) threshold <= threshold - 1;
  else threshold <= threshold;

// Validation Unit with Database
validation validate(.clock(clk), .reset(reset),
  .compare(validate_start), .busy(validate_busy),
  .match(validate_result), .img_num(match_id),
  .din_row_A(rowA_data), .din_row_B(rowB_data),
  .we_row_A(rowA_we), .we_row_B(rowB_we),
  .row_addr_A(rowA_addr), .row_addr_B(rowB_addr),
  .din_col_A(colA_data), .din_col_B(colB_data),
  .we_col_A(colA_we), .we_col_B(colB_we),
  .col_addr_A(colA_addr), .col_addr_B(colB_addr),
  .threshold(threshold), .add_user(add_user & process_start), .user_id(user_id));
//assign validate_result = switch[6];
//assign match_id = switch[5:3];

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// Alphanumeric Display
// clock_27mhz, ascii, bits, dots
wire [639:0] dots1, dots2;
display_state led_matrix1(state,(state == 4)?match_id:user_id,clock_27mhz,dots1);
display_threshold led_matrix2( threshold, clock_27mhz, dots2 );
alphanumeric_displays led_matrix_driver(clock_27mhz, reset,
    disp_test, disp_blank, disp_clock, disp_rs, disp_ce_b,
    disp_reset_b, disp_data_out, disp_threshold ? dots2 : dots1);

endmodule

```

B Controller Module

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*****
* CONTROLLER MODULE
*
* This is the main module of the system. It functions as
* a major FSM.
*
* Its main functions are:
*   - User interaction
*   - Data flow
*   - System output
*
* MODES of OPERATION
*
*   - Idle (waiting for user stimulus)
*
*****

```

```

module controller( // User Interface
    start,
    disp_state,
    add_user,
    add_user_latched,
    acquire,
    user_id,
    user_id_latched,
    // Processing
    process_start,
    // Validation
    validate_start,
    validate_result,
    // System

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```

        busy,
clock,
reset );

///////////////////////////////
// Interface Pins
/////////////////////////////
// User Interaction
input start;           // pulsed input
input add_user;         // mode: 0 - validate, 1 - add user
output add_user_latched; // output
output [2:0] disp_state; // for display
output acquire;         // enable movie mode during acquire
input [2:0] user_id;    // input
output [2:0] user_id_latched; // output
// Process
output process_start;   // start processing
// Validation
output validate_start; // start validation
input validate_result; // 0 - no match, 1 - match found
// System
input busy;             // something is busy (input)
input clock;
input reset;

/////////////////////////////
// Registers
/////////////////////////////
// REGISTERED OUTPUTS
reg [2:0] disp_state;
reg acquire,
      process_start,
      validate_start;
reg [2:0] user_id_latched;
// INTERNAL REGS
reg [2:0] state, next, waitnext;
reg add_user_latched;
reg [31:0] disp_result_pause;

/////////////////////////////
// Parameters
/////////////////////////////
// STATE
parameter ACQUIRE = 0;    // IDLE
parameter SYS_RESET = 1;

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parameter WAIT = 2;
parameter PROCESS = 3;
parameter VALIDATE = 4;
parameter DISP_RESULT = 5;

///////////////////////////////
// Code
/////////////////////////////
always @ (posedge clock) begin

    if (reset) state <= ACQUIRE;
    else state <= next;

    acquire      <= (next == ACQUIRE);
    process_start <= (next == PROCESS);
    validate_start <= (next == VALIDATE);
    add_user_latched <= (next == ACQUIRE) ? (add_user) : add_user_latched;
    disp_result_pause <= (next == ACQUIRE) ? 0 :
                                         (next == DISP_RESULT) ? disp_result_pause + 1 :
                                         disp_result_pause;
    user_id_latched <= (next == ACQUIRE) ? user_id : user_id_latched;
    case (state)
        ACQUIRE: if (~add_user) disp_state <= 0; // 'identify' '
                  else disp_state <= 1;           // 'add user #''
        SYS_RESET: disp_state <= 7;             // (blank)
        WAIT: disp_state <= 2;                 // 'processing' '
        PROCESS: disp_state <= 2;              // 'processing' '
        VALIDATE: disp_state <= 2;            // 'processing' '
        DISP_RESULT:
            if (add_user_latched) disp_state <= 3;     // 'added user #''
            else if (validate_result) disp_state <= 4; // 'matched user #''
            else disp_state <= 5;                      // 'no match' ''
    endcase
    case (state)
        WAIT: waitnext <= waitnext;
        PROCESS: waitnext <= (add_user ? DISP_RESULT : VALIDATE);
        VALIDATE: waitnext <= DISP_RESULT;
        default: waitnext <= waitnext;
    endcase
end

always @ (state or start or busy or disp_result_pause)
case (state)
    ACQUIRE:

```

```

        if (start) next = PROCESS;
        else next = ACQUIRE;
SYS_RESET:
        next = ACQUIRE;
WAIT:
        if (busy) next = WAIT;
        else next = waitnext;
PROCESS:
        next = WAIT;
VALIDATE:
        next = WAIT;
DISP_RESULT:
        if (disp_result_pause > 32'h4FFFFFF) next = ACQUIRE;
        else next = DISP_RESULT;
default:
        next = ACQUIRE;
endcase
endmodule

```

C Image Capture

```

'timescale 1ns / 1ps

*****  

* NTSC to Block RAM (128x128x8)  

*  

*  

*  

*  

*  

*****  

  

module ntsc_to_bram( vclk,
                     fvh,
                     dv,
                     din,  

  

                     bram_addr,
                     bram_data,
                     bram_we,
                     frame_clk,  

  

                     clk,
                     reset );

```

```

// System
input clk;
input reset;
// Video Input
input vclk; // video clock from camera
input [2:0] fvh;
input dv;
input [7:0] din;
// Block RAM Output
output [13:0] bram_addr;
output [7:0] bram_data;
output bram_we;
output frame_clk;

///////////////////////////////
// Create Intermediate Output Signals (Unsyncronized)
///////////////////////////////

parameter COL_START = 0;
parameter ROW_START = 0;

reg [9:0] col = 0, row = 0;    // intermediate address
reg [7:0] vdata = 0;           // data
reg vwe;                      // write enable
reg old_dv;
reg old_frame; // frames are even / odd interlaced
reg even_odd; // decode interlaced frame to this wire
reg frame_clk; // update display per frame clock

wire frame = fvh[2];
wire frame_edge = frame & ~old_frame;

always @ (posedge vclk) begin
old_dv <= dv;
vwe <= dv && !fvh[2] & ~old_dv; // if data valid, write it
old_frame <= frame;
even_odd = frame_edge ? ~even_odd : even_odd;
frame_clk <= frame_edge;
if (!fvh[2]) begin
    // if horizontal blank, reset col count
    // else if not a vertical blank and data is valid and col < 720, increment col
    // else col <= col
    col <= fvh[0] ? COL_START :
        (!fvh[1] && dv && (col < 720)) ? col + 1 :

```

```

        col;
// if vertical blank, reset row count
// else if horizontal blank and row < 525, increment row
// else row <= row
row <= fvh[1] ? ROW_START :
(!fvh[2] && fvh[0] && (row < 525)) ? row + 1 :
row;
// if data valid and not new frame, update vdata
// else vdata
vdata <= (dv && !fvh[2]) ? din : vdata;
end
end

///////////////////////////////
// synchronize with system clock
/////////////////////////////
reg [9:0] x[1:0],y[1:0];
reg [7:0] data[1:0];
reg      we[1:0];
reg      eo[1:0];

// buffer the signals
always @(posedge clk) begin
{x[1],x[0]} <= {x[0],col};
{y[1],y[0]} <= {y[0],row};
{data[1],data[0]} <= {data[0],vdata};
{we[1],we[0]} <= {we[0],vwe};
{eo[1],eo[0]} <= {eo[0],even_odd};
end

// we only write the data in the buffer
// if the vwe was enabled, meaning the
// data was valid.
// edge detection on write enable signal
reg old_we;
wire we_edge = we[1] & ~old_we;
always @(posedge clk) old_we <= we[1];

parameter V_OFFSET = 24;
wire [6:0] addr_row = (y[1][6:0]-V_OFFSET);
wire [6:0] addr_col = x[1][7:1]-4;
reg [13:0] bram_addr;
reg [7:0]  bram_data;
reg bram_we;

```

```

    always @(posedge clk) begin
        // sample every other pixel by dropping
        // LSB from y and x.
        bram_addr <= {addr_row, addr_col};
        bram_data <= data[1];
        bram_we = we_edge &
                    (x[1] > 2) & (x[1] < 258) &
                    (y[1] < 128+V_OFFSET) & (y[1] > V_OFFSET);
    end

```

endmodule

D VGA Display

```

'timescale 1ns / 1ps

module DisplayField( /* INPUTS */ pixel, line,
                     cycle_source,
                     addr, pzl_in, we,
/* OUTPUT */ red, green, blue,
/* SYSTEM */ clock, reset );

parameter PXL_WIDTH = 8-1;
parameter NUM_PIXELS = 16384-1;
parameter ADDR_WIDTH = 14-1;
parameter ROWS = 128;
parameter ROW_WIDTH = 7-1;

input [9:0] pixel, line;
input [ADDR_WIDTH:0] addr;
input [PXL_WIDTH:0] pzl_in;
input we;
input cycle_source;
output [7:0] red, green, blue;
input clock, reset;

// Registered Outputs
reg [7:0] red, green, blue;

// Internal
wire [PXL_WIDTH:0] color;

// Screen Diameters

```

```

parameter WIDTH = 640;
parameter HEIGHT = 480;

// Double Buffered Data Source
double_buffer source (
.re( 1'b0 ),
.we( we ),
.read_addr( {line[ROW_WIDTH:0], pixel[ROW_WIDTH:0]} ),
.write_addr( addr ),
.write_pxl( pzl_in ),
.read_pxl( color ),
.en_seq_read( 1'b0 ),
.en_seq_write( 1'b0 ),
.reset_write_pos( 1'b0 ),
.reset_read_pos( 1'b0 ),
.swap( cycle_source ),
.en( 1'b1 ),
.reset(reset),
.clock(clock)
);
defparam source.PXL_WIDTH = PXL_WIDTH;
defparam source.NUM_PIXELS = NUM_PIXELS;
defparam source.ADDR_WIDTH = ADDR_WIDTH;

always @ (pixel or line) begin
    if (pixel == 255 + 63 && line == 127 + 63)
        {red, green, blue} = {255, 0, 255};
    else if (255 < pixel && pixel < 383 &&
              127 < line && line < 255)
        if (color)
            {red, green, blue} = {color,color,color};
        else
            {red, green, blue} = {0, 0, 0};
    else
        {red, green, blue} = {0, 0, 0};
end

endmodule

```

E LED Display

E.1 Display State

```
'timescale 1ns / 1ps

module display_state( state,
                      userID,
                      clock,
                      dots );

  input [2:0] state;
  input [2:0] userID;
  input clock;
  output [639:0] dots;

  // state          display
  // -----
  // 0              'Identify      '
  // 1              'Add user      #'
  // 2              'Processing    '
  // 3              'added user   #'
  // 4              'matched      #'
  // 5              'no match     '
  // 6              (not used)
  // 7              ,           , (blank)

  wire [7:0] char15 = (state == 0) ? 8'h49 :           // I
                      (state == 1) ? 8'h41 :           // A
                      (state == 2) ? 8'h50 :           // P
                      (state == 3) ? 8'h41 :           // A
                      (state == 4) ? 8'h4D :           // M
                      (state == 5) ? 8'h4E :           // N
                      (state == 6) ? 8'h00 :           // -
                      8'h00;
  wire [7:0] char14 = (state == 0) ? 8'h64 :           // d
                      (state == 1) ? 8'h64 :           // D
                      (state == 2) ? 8'h72 :           // r
                      (state == 3) ? 8'h64 :           // d
                      (state == 4) ? 8'h61 :           // a
                      (state == 5) ? 8'h6F :           // o
                      (state == 6) ? 8'h00 :           // -
                      8'h00;
  wire [7:0] char13 = (state == 0) ? 8'h65 :           // e
                      (state == 1) ? 8'h64 :           // D
```

```

        (state == 2) ? 8'h6F :           //      o
        (state == 3) ? 8'h64 :           //      d
        (state == 4) ? 8'h74 :           //      t
        (state == 5) ? 8'h00 :           //      -
        (state == 6) ? 8'h00 :           //      -
8'h00;
wire [7:0] char12 = (state == 0) ? 8'h6E :           // n
        (state == 1) ? 8'h00 :           //      -
        (state == 2) ? 8'h63 :           //      c
        (state == 3) ? 8'h65 :           //      e
        (state == 4) ? 8'h63 :           //      c
        (state == 5) ? 8'h4D :           //      M
        (state == 6) ? 8'h00 :           //      -
8'h00;
wire [7:0] char11 = (state == 0) ? 8'h74 :           // t
        (state == 1) ? 8'h55 :           //      U
        (state == 2) ? 8'h65 :           //      e
        (state == 3) ? 8'h64 :           //      d
        (state == 4) ? 8'h68 :           //      h
        (state == 5) ? 8'h61 :           //      a
        (state == 6) ? 8'h00 :           //      -
8'h00;
wire [7:0] char10 = (state == 0) ? 8'h69 :           // i
        (state == 1) ? 8'h73 :           //      S
        (state == 2) ? 8'h73 :           //      s
        (state == 3) ? 8'h00 :           //      -
        (state == 4) ? 8'h65 :           //      e
        (state == 5) ? 8'h74 :           //      t
        (state == 6) ? 8'h00 :           //      -
8'h00;
wire [7:0] char09 = (state == 0) ? 8'h66 :           // f
        (state == 1) ? 8'h65 :           //      e
        (state == 2) ? 8'h73 :           //      s
        (state == 3) ? 8'h55 :           //      U
        (state == 4) ? 8'h64 :           //      d
        (state == 5) ? 8'h63 :           //      c
        (state == 6) ? 8'h00 :           //      -
8'h00;
wire [7:0] char08 = (state == 0) ? 8'h79 :           // y
        (state == 1) ? 8'h72 :           //      R
        (state == 2) ? 8'h69 :           //      i
        (state == 3) ? 8'h73 :           //      s
        (state == 4) ? 8'h00 :           //      -
        (state == 5) ? 8'h68 :           //      h
        (state == 6) ? 8'h00 :           //      -

```

```

8'h00;
wire [7:0] char07 = (state == 0) ? 8'h00 : // -
                      (state == 1) ? 8'h00 : // -
                      (state == 2) ? 8'h6E : //     n
                      (state == 3) ? 8'h65 : //     e
                      (state == 4) ? 8'h00 : //     -
                      (state == 5) ? 8'h00 : //     -
                      (state == 6) ? 8'h00 : //     -
                      8'h00;
wire [7:0] char06 = (state == 0) ? 8'h00 : // -
                      (state == 1) ? 8'h00 : // -
                      (state == 2) ? 8'h67 : //     g
                      (state == 3) ? 8'h72 : //     r
                      (state == 4) ? 8'h00 : //     -
                      (state == 5) ? 8'h00 : //     -
                      (state == 6) ? 8'h00 : //     -
                      8'h00;
wire [7:0] char05 = (state == 0) ? 8'h00 : 8'h00; //
wire [7:0] char04 = (state == 0) ? 8'h00 : 8'h00; //
wire [7:0] char03 = (state == 0) ? 8'h00 : 8'h00; //
wire [7:0] char02 = (state == 0) ? 8'h00 : 8'h00; //
wire [7:0] char01 = (state == 0) ? 8'h00 : 8'h00; //
wire [7:0] char00 = (state == 1 ||
                     state == 3 ||
                     state == 4 ) ? {5'b0,userID} : 8'h00; // [user ID]

alpha_display af15(clock, 1'b1, char15, dots[639:600]);
alpha_display af14(clock, 1'b1, char14, dots[599:560]);
alpha_display af13(clock, 1'b1, char13, dots[559:520]);
alpha_display af12(clock, 1'b1, char12, dots[519:480]);
alpha_display af11(clock, 1'b1, char11, dots[479:440]);
alpha_display af10(clock, 1'b1, char10, dots[439:400]);
alpha_display af09(clock, 1'b1, char09, dots[399:360]);
alpha_display af08(clock, 1'b1, char08, dots[359:320]);
alpha_display af07(clock, 1'b1, char07, dots[319:280]);
alpha_display af06(clock, 1'b1, char06, dots[279:240]);
alpha_display af05(clock, 1'b1, char05, dots[239:200]);
alpha_display af04(clock, 1'b1, char04, dots[199:160]);
alpha_display af03(clock, 1'b1, char03, dots[159:120]);
alpha_display af02(clock, 1'b1, char02, dots[119:080]);
alpha_display af01(clock, 1'b1, char01, dots[079:040]);
alpha_display af00(clock,
                  ~(state == 1 || state == 3 || state == 4),
                  char00, dots[039:000]);

```

```
endmodule
```

E.2 Display Threshold

```
'timescale 1ns / 1ps

module display_threshold( threshold,
                          clock,
                          dots );
    input [63:0] threshold;
    input clock;
    output [639:0] dots;

    alpha_display af15(clock, 1'b0, threshold[63:60], dots[639:600]);
    alpha_display af14(clock, 1'b0, threshold[59:56], dots[599:560]);
    alpha_display af13(clock, 1'b0, threshold[55:52], dots[559:520]);
    alpha_display af12(clock, 1'b0, threshold[51:48], dots[519:480]);
    alpha_display af11(clock, 1'b0, threshold[47:44], dots[479:440]);
    alpha_display af10(clock, 1'b0, threshold[43:40], dots[439:400]);
    alpha_display af09(clock, 1'b0, threshold[39:36], dots[399:360]);
    alpha_display af08(clock, 1'b0, threshold[35:32], dots[359:320]);
    alpha_display af07(clock, 1'b0, threshold[31:28], dots[319:280]);
    alpha_display af06(clock, 1'b0, threshold[27:24], dots[279:240]);
    alpha_display af05(clock, 1'b0, threshold[23:20], dots[239:200]);
    alpha_display af04(clock, 1'b0, threshold[19:16], dots[199:160]);
    alpha_display af03(clock, 1'b0, threshold[15:12], dots[159:120]);
    alpha_display af02(clock, 1'b0, threshold[11: 8], dots[119:080]);
    alpha_display af01(clock, 1'b0, threshold[ 7: 4], dots[079:040]);
    alpha_display af00(clock, 1'b0, threshold[ 3: 0], dots[039:000]);

endmodule
```

F Memory Buffer Modules

F.1 Image Buffer

```
'timescale 1ns / 1ps

/******************
 * Image Buffer (128 x 128 pixels, 8 bit / pxl)
 * David Friend, friend@mit.edu
 *
```

```

* Buffer stores 128 by 128 grayscale image in a
* register array. Access is random.
*
* DELAYS
*
* - Read delay: 2 (non-critical)
* - Write delay: 1 (non-critical)
*
*      -- -- -- --
*      _|_|_||_|_||_|_
*      0     1     2     3
*
* A read at 0 will become valid at 2.
* Inputs at 1 and 2 will not affect the data
* becoming valid at 2.
*
* A write at 0 will actually occur at 1. Once
* the data has latched at 0, it will be written,
* regardless of changes in input.
*
* If you reset the pxl position, this
* takes a clock cycle!
*
***** */

module img_buffer( /* Standard */
    en,
    we,
    write_pxl,
    read_pxl,
    addr,
    /* Sequencial Access */
    re,
    reset_pxl_pos,
    enable_seq_access,
    /* System */
    reset,
    clock );

parameter PXL_WIDTH  = 8-1;
parameter NUM_PIXELS = 16384-1;
parameter ADDR_WIDTH = 14-1;

///////////////////////////////
// Inputs
/////////////////////////////

```

```

// Standard Interface
input en;
input we;
input [ADDR_WIDTH:0] addr;

// Sequential Access Interface
input re;
input reset_pxl_pos;
input enable_seq_access;

// Data Lines
input [PXL_WIDTH:0] write_pxl;
output [PXL_WIDTH:0] read_pxl;

// System
input reset;
input clock;

///////////////////////////////
// Registers
///////////////////////////////
// internal storage
reg [ADDR_WIDTH:0] pxl_pos;
reg [14:0] buf_addr;
reg [8:0] buf_din;
wire [8:0] buf_dout;
reg buf_we;

///////////////////////////////
// Buffer
/////////////////////////////
buffer_128x128x8 img_buffer(
    .addr( buf_addr[13:0] ),
    .clk( clock ),
    .din( buf_din[7:0] ),
    .dout( buf_dout[7:0] ),
    .en( en ),
    .we( buf_we )
);

///////////////////////////////
// Code
/////////////////////////////

assign read_pxl = buf_dout[PXL_WIDTH:0];

```

```

always @ (posedge clock)
  if (en) begin
    buf_addr[ADDR_WIDTH:0] <= (enable_seq_access ? pxl_pos : addr);
    buf_addr[14:ADDR_WIDTH+1] <= 14'b0;
    buf_din[PXL_WIDTH:0] <= write_pxl;
    buf_din[8:PXL_WIDTH+1] <= 8'b0;
    buf_we <= we;

    if (reset | reset_pxl_pos) pxl_pos <= 0;
    else if (enable_seq_access & (we | re))
      pxl_pos <= pxl_pos + 1;
    else pxl_pos <= pxl_pos;
  end

endmodule

```

F.2 Double Buffer

```

'timescale 1ns / 1ps

/*****
 * Double Buffer Module
 * David Friend, friend@mit.edu
 *
 * For the proccessing of digital images,
 * it is very convenient to use a double
 * buffered design. We can read from the
 * first buffer and write changes to the
 * second. We can then switch the read and
 * write buffers and perform the next
 * filtering.
 *
 * Sequencial access, employing two
 * pointers, one for the read buffer
 * and one for the write buffer.
 *
 * DELAYS
 *
 * - Read delay: 3 (critical)
 * - Write delay: 2 (non-critical)
 *
 *   -- -- -- --
 *   _|_|_||_|_||_|_
 *   0   1   2   3
 *
 * If a read_addr or re is valid at 0,

```

```

* read_pxl will be valid at 3. Swap
* should not be asserted between 0 and
* 3, or the data will never become valid.
*
* If a we is asserted at 0, the data
* is actually written at 2. Data are
* written to the buffer that is the
* write buffer at 0, regardless of input
* changes between 0 and 2. For instance, if
* swap is high at 1, the data will still
* be written, and then be available
* through a read (after the swap).
*
***** */

module double_buffer( re,
                      we,
                      read_addr,
                      write_addr,
                      write_pxl,
                      read_pxl,
                      en_seq_read,
                      en_seq_write,
                      reset_write_pos,
                      reset_read_pos,
                      swap,
                      en,
                      reset,
                      clock );

parameter PXL_WIDTH = 8-1;
parameter NUM_PIXELS = 16384-1;
parameter ADDR_WIDTH = 14-1;

///////////////////////////////
// Pins
///////////////////////////////

// Standard Interface
input en;
input we;
input [ADDR_WIDTH:0] read_addr;
input [ADDR_WIDTH:0] write_addr;
input swap;

```

```

// Sequencial Access
input re;
input en_seq_read;
input en_seq_write;
input reset_write_pos;
input reset_read_pos;

// Data Lines
input [PXL_WIDTH:0] write_pxl;
output [PXL_WIDTH:0] read_pxl;

// System
input reset;
input clock;

///////////////
// Registers
///////////////
// registered outputs
//reg [PXL_WIDTH:0] read_pxl;
// state
reg read_buffer; // indicates which
                  // buffer (0 or 1)
                  // is the read buffer

reg buf0_we;
reg [PXL_WIDTH:0] buf0_write_pxl;
wire [PXL_WIDTH:0] buf0_read_pxl;
reg [ADDR_WIDTH:0] buf0_addr;
reg buf0_re, buf0_reset_pxl_pos,
     buf0_en_seq;

reg buf1_we;
reg [PXL_WIDTH:0] buf1_write_pxl;
wire [PXL_WIDTH:0] buf1_read_pxl;
reg [ADDR_WIDTH:0] buf1_addr;
reg buf1_re, buf1_reset_pxl_pos,
     buf1_en_seq;

///////////////
// Buffers
///////////////

img_buffer buf0(
    .en(en),

```

```

.we(buf0_we),
.write_pxl(buf0_write_pxl),
.read_pxl(buf0_read_pxl),
.addr(buf0_addr),
.re(buf0_re),
.reset_pxl_pos(buf0_reset_pxl_pos),
.enable_seq_access(buf0_en_seq),
.reset(reset),
.clock(clock)
);

defparam buf0.PXL_WIDTH = PXL_WIDTH;
defparam buf0.NUM_PIXELS = NUM_PIXELS;
defparam buf0.ADDR_WIDTH = ADDR_WIDTH;

img_buffer buf1(
    .en(en),
.we(buf1_we),
.write_pxl(buf1_write_pxl),
.read_pxl(buf1_read_pxl),
.addr(buf1_addr),
.re(buf1_re),
.reset_pxl_pos(buf1_reset_pxl_pos),
.enable_seq_access(buf1_en_seq),
.reset(reset),
.clock(clock)
);

defparam buf1.PXL_WIDTH = PXL_WIDTH;
defparam buf1.NUM_PIXELS = NUM_PIXELS;
defparam buf1.ADDR_WIDTH = ADDR_WIDTH;

/////////////////////////////
// Code
////////////////////////////

// read_pxl is only signal that isn't
// buffered against a change in read_buffer
// Don't swap the buffers while you're
// waiting for read_pxl to become valid!
assign read_pxl = (read_buffer) ? buf1_read_pxl : buf0_read_pxl;

always @ (posedge clock) begin

    if (reset) read_buffer <= 0;

```

```

else if (swap) read_buffer <= ~read_buffer;

buf1_we          <= ( read_buffer) ? 0 : we;
buf1_write_pxl   <= ( read_buffer) ? 0 : write_pxl;
buf1_re           <= ( read_buffer) ? re : 0;
buf1_addr         <= ( read_buffer) ? read_addr : write_addr;
buf1_en_seq       <= ( read_buffer) ? en_seq_read : en_seq_write;
buf1_reset_pxl_pos <= ( read_buffer) ? reset_read_pos : reset_write_pos;

buf0_we          <= (!read_buffer) ? 0 : we;
buf0_write_pxl   <= (!read_buffer) ? 0 : write_pxl;
buf0_re           <= (!read_buffer) ? re : 0;
buf0_addr         <= (!read_buffer) ? read_addr : write_addr;
buf0_en_seq       <= (!read_buffer) ? en_seq_read : en_seq_write;
buf0_reset_pxl_pos <= (!read_buffer) ? reset_read_pos : reset_write_pos;

end

endmodule

```

F.3 Line Buffer

```

'timescale 1ns / 1ps

/*****
 * Line Buffer (1x128 Pixels, 1 bit / pxl)
 * David Friend, friend@mit.edu
 *
 * Buffer stores 1 by 128 binary image in a
 * register array. Access is random.
 *
 * DELAYS
 *
 * - Read delay: 2 (non-critical)
 * - Write delay: 1 (non-critical)
 *
 *    -- -- -- --
 *    _|_ |__|_|__|_|__|
 *    0   1   2   3
 *
 * A read at 0 will become valid at 2.
 * Inputs at 1 and 2 will not affect the data
 * becoming valid at 2.
 *
 * A write at 0 will actually occur at 1. Once
 * the data has latched at 0, it will be written,

```

```

* regardless of changes in input.
*
* If you reset the pxl position, this
* takes a clock cycle!
*
***** */

module line_buffer( /* Standard */
    en,
    we,
    write_pxl,
    read_pxl,
    addr,
    /* Sequencial Access */
    re,
    reset_pxl_pos,
    enable_seq_access,
    /* System */
    reset,
    clock );

parameter PXL_WIDTH  = 1-1;
parameter NUM_PIXELS = 128-1;
parameter ADDR_WIDTH = 7-1;

///////////////////////////////
// Inputs
/////////////////////////////
// Standard Interface
input en;
input we;
input [ADDR_WIDTH:0] addr;

// Sequencial Access Interface
input re;
input reset_pxl_pos;
input enable_seq_access;

// Data Lines
input [PXL_WIDTH:0] write_pxl;
output [PXL_WIDTH:0] read_pxl;

// System
input reset;
input clock;

```

```

///////////
// Registers
///////////
// internal storage
reg [ADDR_WIDTH:0] pxl_pos;
reg [ADDR_WIDTH:0] buf_addr;
reg [PXL_WIDTH:0] buf_din;
wire [PXL_WIDTH:0] buf_dout;
reg buf_we;

///////////
// Buffer
///////////
buffer_1x128x1 line_buf(
.addr( buf_addr ),
.clk( clock ),
.din( buf_din ),
.dout( buf_dout ),
.en( en ),
.we( buf_we )
);

///////////
// Code
///////////

assign read_pxl = buf_dout;

always @ (posedge clock)
if (en) begin
    buf_addr <= (enable_seq_access ? pxl_pos : addr);
    buf_din <= write_pxl;
    buf_we <= we;
    if (reset | reset_pxl_pos) pxl_pos <= 0;
    else if (enable_seq_access & (we | re))
        pxl_pos <= pxl_pos + 1;
    else pxl_pos <= pxl_pos;
end

endmodule

```

G Processing

G.1 Processing Controller

```
'timescale 1ns / 1ps

module process_image( /* Interface */
                      start,
                      busy,
                      /* Image Input */
                      scanned_img_reset_pxl_pos,
                      scanned_img_request_pxl,
                      scanned_img_pxl_in,
                      scanned_img_en_seq_access,
                      /* Display Output */
                      cycle_display,
                      disp_addr, disp_pxl_out,
                      disp_we,
                      /* Fourier Coefficients */
                      we_row_coeff, fft_row_dv, row_coeff,
                      we_col_coeff, fft_col_dv, col_coeff,
                      /* System */
                      reset,
                      clock,
                      sel_data_begin, sel_data_in, sel_row_data_out, sel_col_data_out,
                      sel_row_we, sel_col_we );

// Debug:
output sel_data_begin;
output sel_data_in;
output sel_row_data_out;
output sel_col_data_out;
output sel_col_we, sel_row_we;

/* Process Image Interface */
input start;
output busy;

/* Original Image Memory Interface */
output scanned_img_reset_pxl_pos;
output scanned_img_request_pxl;
input [7:0] scanned_img_pxl_in;
output scanned_img_en_seq_access;

/* Output */
```

```

output cycle_display;
output [13:0] disp_addr;
output [7:0] disp_pxl_out;
output disp_we;
output we_row_coeff, fft_row_dv,
      we_col_coeff, fft_col_dv;
output [31:0] row_coeff, col_coeff;

/* System */
input reset;
input clock;

///////////////
// Registers
///////////////
// registered outputs
reg busy;
reg scanned_img_en_seq_access = 0;
// FSM
reg [2:0] state, next, waitnext;
// other
reg buf_swap;
reg ds_start, disp_start;
reg sel_start, fft_row_start, fft_col_start;

///////////////
// Parameters
/////////////
// FSM state identifiers
parameter IDLE = 0;
parameter SYS_RESET = 1;
parameter WAIT = 2;
parameter DOWNSAMPLE = 3;
parameter ROW_COL_SEL = 4;
parameter FOURIER = 5;
parameter UPDATE_DISP = 6;

///////////////
// Modules
// (Processing Units)
/////////////
// Double Buffer
/////////////
wire buf_re, buf_we,

```

```

buf_write_pxl, buf_read_pxl,
buf_RST_WRITE, buf_RST_READ;

double_buffer buffers(
    .RE( buf_re ),
    .WE( buf_we ),
    .read_addr( 14'b0 ),
    .write_addr( 14'b0 ),
    .read_pxl( buf_read_pxl ),
    .write_pxl( buf_write_pxl ),
    .en_seq_read( 1'b1 ),
    .en_seq_write( 1'b1 ),
    .reset_write_pos( buf_RST_WRITE ),
    .reset_read_pos( buf_RST_READ ),
    .swap( buf_swap ),
    .en( 1'b1 ),
    .reset( reset ),
    .clock( clock )
);

defparam buffers.PXL_WIDTH = 0;
defparam buffers.NUM_PIXELS = 16383;
defparam buffers.ADDR_WIDTH = 13;

///////////////////////////////
// Downsample Module
///////////////////////////////

wire ds_busy;
wire ds_we, ds_write_pxl;
wire ds_RST_WRITE;

downsample ds(
    .in_reset_pxl_pos( scanned_img_reset_pxl_pos ),
    .in_re( scanned_img_request_pxl ),
    .in_pxl( scanned_img_pxl_in ),
    .out_reset_pxl_pos( ds_RST_WRITE ) ,
    .out_we( ds_we ),
    .out_pxl( ds_write_pxl ),
    .start( ds_start ),
    .busy( ds_busy ),
    .clock( clock ),
    .reset( reset )
);

```

```

///////////
// Update Display Module
///////////
wire disp_busy;
wire disp_re, disp_RST_read;

update_display disp(
    .start( disp_start ),
    .busy( disp_busy ),
    .re( disp_re ),
    .we( disp_we ),
    .addr( disp_addr ),
    .reset_input( disp_RST_read ),
    .cycle_display( cycle_display ),
    .read_pxl( buf_read_pxl ),
    .write_pxl( disp_pxl_out ),
    .clock(clock),
    .reset(reset)
);

///////////
// Select Row Column
///////////

wire sel_busy;
wire sel_re, sel_RST_read;
wire row_we, row_write_pxl, row_read_pxl;
wire row_re, row_RST, row_en_seq;
wire col_we, col_write_pxl, col_read_pxl;
wire col_re, col_RST, col_en_seq;
wire sel_row_RST, sel_col_RST;

row_col_selector selector(.clock(clock), .reset(reset),
    .row_select(7'd64), .col_select(7'd64), // input row and column numbers
    .start( sel_start ), .busy( sel_busy ),
    // INPUT from img buffer
    .data_in( buf_read_pxl ), .re( sel_re ), .reset_pxl_pos_data_in( sel_RST_read ),
    // OUTPUT to line buffers
    .reset_pxl_pos_row( sel_row_RST ), .we_row( row_we ), .data_out_row( row_write_pxl ),
    .reset_pxl_pos_col( sel_col_RST ), .we_col( col_we ), .data_out_col( col_write_pxl ) );

line_buffer row_buffer( .en( 1'b1 ), .reset(reset), .clock(clock),
    .we( row_we ), .write_pxl( row_write_pxl ), .addr( 7'b0 ),
    .read_pxl( row_read_pxl ), .re( row_re ), .reset_pxl_pos( row_RST ),
```

```

.enable_seq_access( 1'b1 ));

line_buffer col_buffer( .en( 1'b1 ), .reset(reset), .clock(clock),
    .we( col_we ), .write_pxl( col_write_pxl ), .addr( 7'b0 ),
    .read_pxl( col_read_pxl ), .re( col_re ), .reset_pxl_pos( col_RST ),
    .enable_seq_access( 1'b1 ));

// debugging wires
assign sel_data_begin = sel_start;
assign sel_data_in = buf_read_pxl;
assign sel_row_data_out = row_read_pxl;
assign sel_col_data_out = col_read_pxl;
assign sel_row_we = row_re;
assign sel_col_we = col_re;

///////////////////////////////
// FFT
/////////////////////////////
wire fft_row_busy;
wire fft_col_busy;
// outputs
// we_row_coeff, rst_row_coeff, row_coeff,
// we_col_coeff, rst_col_coeff, col_coeff,

wire fft_row_RST, fft_row_re, fft_col_RST, fft_col_re;

fft fft_row(.clock(clock), .reset(reset),
    .start( fft_row_start ), .busy( fft_row_busy ),
    .reset_pxl_pos_in( fft_row_RST ), .re_in( fft_row_re ), .data_in( row_read_pxl ),
    .we_out( we_row_coeff ),
    .M_sum_sq( row_coeff ), .fft_dv( fft_row_dv ) );
fft fft_col(.clock(clock), .reset(reset),
    .start( fft_col_start ), .busy( fft_col_busy ),
    .reset_pxl_pos_in( fft_col_RST ), .re_in( fft_col_re ), .data_in( col_read_pxl ),
    .we_out( we_col_coeff ),
    .M_sum_sq( col_coeff ), .fft_dv( fft_col_dv ) );

assign row_RST = fft_row_RST | sel_row_RST;
assign row_re = fft_row_re ;
assign col_RST = fft_col_RST | sel_col_RST ;
assign col_re = fft_col_re ;

assign buf_re = disp_re | sel_re ;
assign buf_we = ds_we ;

```

```

assign buf_RST_WRITE = DS_RST_WRITE;
assign buf_RST_READ = DISP_RST_READ | SEL_RST_READ;
assign buf_WRITE_PXL = DS_WRITE_PXL;

always @ (posedge clock) begin
    if (reset) state <= SYS_RESET;
    else state <= next;

    busy <= (next != IDLE);
    scanned_img_en_seq_access <= (next != IDLE);

    DS_start <= (next == DOWNSAMPLE);
    DISP_start <= (next == UPDATE_DISP);
    SEL_start <= (next == ROW_COL_SEL);
    FFT_ROW_start <= (next == FOURIER);
    FFT_COL_start <= (next == FOURIER);

    // this is a bit cryptic, but it means
    // swap the buffers on the exit of Downsample
    buf_swap <= (state == WAIT &&
                  next == waitnext &&
                  next == UPDATE_DISP);

    case (state)
        WAIT: waitnext <= waitnext;
        DOWNSAMPLE: waitnext <= UPDATE_DISP;
        UPDATE_DISP: waitnext <= ROW_COL_SEL;
        ROW_COL_SEL: waitnext <= FOURIER;
        FOURIER: waitnext <= IDLE;
        default: waitnext <= waitnext;
    endcase
end

wire internal_busy = DS_BUSY |
                     DISP_BUSY |
                     SEL_BUSY |
                     FFT_ROW_BUSY |
                     FFT_COL_BUSY;

always @ (state or start or internal_busy )
    case (state)
        IDLE:
            if (start) next = DOWNSAMPLE;
            else if (next == DOWNSAMPLE);
            else next = IDLE;

```

```

SYS_RESET:
    next = IDLE;
WAIT:
    if ( internal_busy ) next = WAIT;
    else next = waitnext;
DOWNSAMPLE:
    next = WAIT;
UPDATE_DISP:
    next = WAIT;
ROW_COL_SEL:
    next = WAIT;
FOURIER:
    next = WAIT;
default:
    next = IDLE;
endcase

endmodule

```

G.2 Downsample

```

'timescale 1ns / 1ps

*****
* Downsample Module
* David Friend, friend@mit.edu
*
* Input: 128 x 128 image, 8-bits per pxl
* Output: 128 x 128 image, 1-bit per pxl
*
* Computes the average pixel value of the 8-bit
* image and uses this as a threshold. If a pixel
* has a pixel value greater than the threshold,
* it is a '1'. Below or equal to the threshold
* is interpreted as a '0'.
*
* There are three steps:
*   1. Sum all 8-bit pixels
*   2. Compute threshold (average of sum
*      from step 1)
*   3. Output downsampled image
* These steps correspond to the states of
*
* SOURCE: img_buffer, sequencial
*
* Reading from img_buffer. Delay is 2

```

```

* clock cycles. Must have two initialization
* reads to account for delay. Also must
* reset buffer position before reading. This
* is a total of three initialization states.
*
* DESTINATION: double_buffer, sequencial
*
* Writing to a double_buffer. Delay is two
* clock cycles, but it is not critical in the
* sense that nothing can prevent the write
* from occurring once the data has been
* latched. Access is sequential. The position
* must be reset before writing. Care must be
* taken to start the write at the appropriate
* time relative to the read.
*
***** */

module downsample( in_reset_pxl_pos,
                    in_re,
                    in_pxl,
                    out_reset_pxl_pos,
                    out_we,
                    out_pxl,
                    start,
                    busy,
                    clock,
                    reset );

parameter PXL_WIDTH = 8-1;
parameter ADDR_WIDTH = 14-1;
parameter NUM_PIXELS = 16383-1;

// Input Memory Interface
output in_reset_pxl_pos;
output in_re;
input [PXL_WIDTH:0] in_pxl;

// Output Memory Interface
output out_reset_pxl_pos;
output out_we;
output out_pxl;

// Module Interface
input start;

```

```

output busy;

// System
input clock;
input reset;

///////////
// Parameters
///////////
// states
parameter IDLE          = 0;
parameter SYS_RESET      = 1;

// read to accumulate
parameter RST_PXL        = 2;
parameter INITREAD1       = 3;
parameter INITREAD2       = 4;
parameter READSUM         = 5;

// calculate
parameter THRESHOLD      = 6;

// read to write
parameter RST_PXL_2      = 7;
parameter INITREAD1_2     = 8;
parameter INITREAD2_2     = 9;
parameter INITREAD3_2     = 10; // to account for delay
parameter READWRITE        = 11; // or latch_read_compare

///////////
// Registers
///////////
// registered outputs
reg in_reset_pxl_pos;
reg in_re;
reg out_reset_pxl_pos;
reg out_we;
reg out_pxl;
reg busy;
// internal storage
reg [21:0] sum;
reg [PXL_WIDTH:0] threshold;
reg [3:0] state, next;

```

```

reg [ADDR_WIDTH:0] pxl_cnt;

///////////
// Code
///////////

always @ (posedge clock) begin

    if (reset) state <= SYS_RESET;
    else state <= next;

    busy <= (next != IDLE);

    sum <= ((next == IDLE) ? (22'b0) :
              ((next == READSUM) ? (sum + in_pxl) : (sum)));
    threshold <= ((next == IDLE) ? (127) :
                  ((next == THRESHOLD) ? (sum >> (ADDR_WIDTH + 1)) : (threshold)));

    // increment pxl_cnt on exit from readwrite states
    if (next == IDLE || 
        next == RST_PXL || 
        next == RST_PXL_2 ) pxl_cnt <= 0;
    else if ((next == READSUM && state == READSUM) ||
              (next == READWRITE && state == READWRITE))
        pxl_cnt <= pxl_cnt + 1;
    else
        pxl_cnt <= pxl_cnt;

    in_reset_pxl_pos <= (next == RST_PXL || next == RST_PXL_2);
    in_re <= (next == INITREAD1 ||
               next == INITREAD2 ||
               next == READSUM ||
               next == INITREAD1_2 ||
               next == INITREAD2_2 ||
               next == INITREAD3_2 ||
               next == READWRITE );

    out_reset_pxl_pos <= (next == RST_PXL_2);
    out_we <= (next == READWRITE);
    // delays out_pxl by one
    // from in_pxl becoming valid ---
    // hence three initial reads
    out_pxl <= (next == IDLE) ? 0 : (in_pxl > threshold);

```

```

end

always @ (state or start or pxl_cnt)
  case (state)
    IDLE:
      if (start) next = RST_PXL;
      else if (next == RST_PXL) next = RST_PXL;
      else next = IDLE;
    SYS_RESET:
      next = IDLE;
    RST_PXL:
      next = INITREAD1;
    INITREAD1:
      next = INITREAD2;
    INITREAD2:
      next = READSUM;
    READSUM:
      if (pxl_cnt == NUM_PIXELS) next = THRESHOLD;
      else next = READSUM;
    THRESHOLD:
      next = RST_PXL_2;
    RST_PXL_2:
      next = INITREAD1_2;
    INITREAD1_2:
      next = INITREAD2_2;
    INITREAD2_2:
      next = INITREAD3_2;
    INITREAD3_2:
      next = READWRITE;
    READWRITE:
      if (pxl_cnt == NUM_PIXELS) next = IDLE;
      else next = READWRITE;
    default:
      next = IDLE;
  endcase

endmodule

```

G.3 Display Processed Unit

```

'timescale 1ns / 1ps

*****
* Update Display from Processed Image

```

```

* David Friend, friend@mit.edu
*
* Reads data from the processed image buffer
* and writes into the Display. Finally it
* cycles the display buffers to put the img
* on the screen.
*
* SOURCE: double_buffer, sequencial
*
* Reading from a duble_buffer. Delay is
* 3 clock cycles. Must have three initialization
* reads to account for delay. But must
* reset buffer position before reading.
* This a total of four initialization
* states.
*
* DESTINATION: double_buffer, random
*
* Writing to a double_buffer. Delay is
* 2 clock cycles, but is not critical,
* in the sense that nothing can prevent
* the write from occurring once it has
* latched. Access is random; care must
* be taken to ensure that data is written
* to the proper location. Address should
* be incremented on exit from the WRITE
* state.
*
***** */

module update_display( start, busy,
                      re, we, addr,
                      reset_input, cycle_display,
                      read_pxl, write_pxl,
                      clock, reset);

parameter PXL_WIDTH = 8-1;
parameter ADDR_WIDTH = 14-1;
parameter NUM_PIXELS = 16384-1;

// Module Interface
input start;
output busy;

// Source Memory Interface

```

```

output re, reset_input;
input read_pxl;

// Display Memory Interface
output [ADDR_WIDTH:0] addr;
output we, cycle_display;
output [PXL_WIDTH:0] write_pxl;

// System
input clock;
input reset;

///////////////////////////////
// Parameters
///////////////////////////////
// state
parameter IDLE = 0;
parameter SYS_RESET = 1;
parameter RESET = 2;
parameter INITREAD1 = 3;
parameter INITREAD2 = 4;
parameter INITREAD3 = 5;
parameter READWRITE = 6;

///////////////////////////////
// Registers
///////////////////////////////
// registered outputs
reg re, reset_input;
reg we, cycle_display;
reg busy;
reg [ADDR_WIDTH:0] addr;
// internal
reg [2:0] state, next;

///////////////////////////////
// Code
///////////////////////////////

assign write_pxl = {read_pxl, read_pxl, read_pxl, read_pxl,
                    read_pxl, read_pxl, read_pxl, read_pxl};

always @ (posedge clock) begin
    if (reset) state <= SYS_RESET;
    else state <= next;

```

```

busy <= (next != IDLE);
reset_input <= (next == RESET);
re <= (next == INITREAD1 |
        next == INITREAD2 |
        next == INITREAD3 |
        next == READWRITE);
we <= (next == READWRITE);
cycle_display <= (next == IDLE && state == READWRITE);

// addr
if (reset | next == RESET)
    addr <= 0;
else if ( next == READWRITE &&
          state == READWRITE )
    addr <= addr + 1;
else
    addr <= addr;
end

always @ (state or start or addr)
case (state)
    IDLE:
        if (start) next = RESET;
        // if we don't include this condition:
        else if (next == RESET) next = RESET;
        // then this might be true on
        // negedge of start, and we
        // don't start at all
        else next = IDLE;
    SYS_RESET:
        next = IDLE;
    RESET:
        next = INITREAD1;
    INITREAD1:
        next = INITREAD2;
    INITREAD2:
        next = INITREAD3;
    INITREAD3:
        next = READWRITE;
    READWRITE:
        if (addr == NUM_PIXELS) next = IDLE;
        else next = READWRITE;
    default:

```

```

        next = IDLE;
    endcase

endmodule

```

G.4 Row and Column Selector

```

'timescale 1ns / 1ps
///////////////////////////////
//  Kevin Amendt  kamendt@mit.edu
//  6.111 Final Project: Fingerprint Identification
//
//  Create Date:  10:03:14 05/15/06
//  Design Name:
//  Module Name: my_row_your_cloumn
//  Project Name:
//  Target Device:
//  Tool versions:
//  Description: This module will write a specific row and column of a 128x128
//                Binary image.
//
//  Dependencies:
//
// Revision:
// Revision 0.01 - File Created
// Additional Comments:
//
/////////////////////////////
module row_col_selector(clock, reset, row_select, col_select,
                        start, data_in, busy, re,
                        reset_pxl_pos_data_in, reset_pxl_pos_row,
                        we_row, data_out_row, reset_pxl_pos_col,
                        we_col, data_out_col
);
    //  Inputs
    input      clock, reset;
    input [6:0] row_select, col_select;
    input      start;
    input      data_in;

    //  Outputs
    output     busy;
    output     re, reset_pxl_pos_data_in;
    output     reset_pxl_pos_row, we_row, data_out_row;
    output     reset_pxl_pos_col, we_col, data_out_col;

```

```

//      Registers
reg  [2:0]      state, next;
reg           busy;
reg           re, reset_pxl_pos_data_in;
reg           reset_pxl_pos_row, we_row;
reg           reset_pxl_pos_col, we_col;
reg  [14:0]     pxl_count;

//      Wires
wire [6:0]      row_val = pxl_count[13:7];
wire [6:0]      col_val = pxl_count[6:0];

//      FSM State Parameters
parameter      SYS_RESET = 0;
parameter      IDLE = 1;
parameter      RESET_PXL = 2;
parameter      WRITE_ROW_COL = 3;

//      Sequential Always Block
always @ (posedge clock)
    if(reset) begin
        state <= SYS_RESET;
        pxl_count <=0;
    end
    else begin
        state <= next;
        reset_pxl_pos_data_in <= (next == RESET_PXL);
        reset_pxl_pos_row <= (next == RESET_PXL);
        reset_pxl_pos_col <= (next == RESET_PXL);
        we_row <= ((next == WRITE_ROW_COL) & (row_val == row_select));
        we_col <= ((next == WRITE_ROW_COL) & (col_val == col_select + 1));
        re <= (next == WRITE_ROW_COL);
        busy <= ~(next == IDLE);
        if((next == WRITE_ROW_COL) && (state == WRITE_ROW_COL))
            pxl_count <= pxl_count + 1;
        else if(next == RESET_PXL)
            pxl_count <= 0;
    end

//      Combinational Always Block
always @ (state or start or pxl_count)
    case(state)
        SYS_RESET:
            next = IDLE;

```

```

IDLE:
    if(start)    next = RESET_PXL;
    else        next = IDLE;
RESET_PXL:
    next = WRITE_ROW_COL;
WRITE_ROW_COL:
    if(pxl_count == 16383) next = IDLE;
    else      next = WRITE_ROW_COL;
endcase

// Combinational Output Assignments
assign data_out_row = data_in;
assign data_out_col = data_in;

endmodule

```

G.5 Fourier Transform

G.5.1 FFT

```

'timescale 1ns / 1ps
///////////////////////////////
// Kevin Amendt kamendt@mit.edu
// 6.111 Final Project: Fingerprint Identification
//
//
// Create Date: 15:57:20 05/14/06
//
// Module Name: fft
//
// This module is to interface with the FFT coregen instance.
// It will read the values of the input out of memory, and
// supply them to the FFT at the correct timing. Streams them in
// every clock cycle.
//
// It will also square the real/img parts of the coefficients and
// write them to memory
//
// Revision:
// Revision 0.01 - File Created
// Additional Comments:
//
/////////////////////////////
module fft(clock, reset, data_in, start, sum_sq,
            reset_pxl_pos_in, re_in, we_out,
            enable_seq_access_out, reset_pxl_pos_out,

```

```

    busy,
    fft_xk_re, fft_xk_im
    ,fft_xn_index, fft_xk_index
    ,M_sum_sq
    ,fft_dv );

input      clock, reset;
input      data_in;
input      start;

output [16:0] sum_sq;
output [31:0] M_sum_sq;

output      reset_pxl_pos_in, re_in;
output      we_out, enable_seq_access_out, reset_pxl_pos_out;
output      busy;
output [15:0]fft_xk_re, fft_xk_im;
output [6:0] fft_xn_index, fft_xk_index;
output      fft_dv;

// Instance of FFT
reg  [7:0] fft_xn_re;                      // X (time) in real      INPUT
wire [7:0] fft_xn_im;                      // X (time) in imaginary INPUT
wire      fft_start;                        // start FFT             INPUT
wire      fft_fwd_inv;                     // Forward or Inverse FFT INPUT
wire      fft_fwd_inv_we;                  // Write Enable for fwd_inv INPUT
wire      fft_sclr;                        // System Reset: sets all values to default INPUT
wire      fft_ce;                          // clock enable           INPUT
wire      fft_clock;                      // clock, synchronous     INPUT
wire [15:0]fft_xk_re;                      // X (freq) out real     OUTPUT
wire [15:0]fft_xk_im;                      // X (freq) out imaginary OUTPUT
wire [6:0] fft_xn_index;                   // index number for X (time) in OUTPUT
wire [6:0] fft_xk_index;                   // index number for X (freq) out OUTPUT
wire      fft_rfd;                         // Ready For Data         OUTPUT
wire      fft_busy;                        // FFT is busy            OUTPUT
wire      fft_dv;                           // Data Valid             OUTPUT
wire      fft_edone;                      // Early done, high one clock cycle before done goes high OUTPUT
wire      fft_done;                        // FFT transform is done, streams out data   OUTPUT

fft_128x1 fft(
.xn_re(fft_xn_re),
.xn_im(fft_xn_im),
.start(fft_start),
.fwd_inv(fft_fwd_inv),
.fwd_inv_we(fft_fwd_inv_we),

```

```

.sclr(fft_sclr),
.ce(fft_ce),
.clk(fft_clock),
.xk_re(fft_xk_re),
.xk_im(fft_xk_im),
.xn_index(fft_xn_index),
.xk_index(fft_xk_index),
.rfd(fft_rfd),
.busy(fft_busy),
.dv(fft_dv),
.edone(fft_edone),
.done(fft_done)
);

// FFT initializer
reg [1:0] initclock;
always @ (posedge clock)begin
initclock <= reset ? 0 : ((initclock < 3) ? initclock + 1 : initclock);
fft_xn_re[0] <= data_in;
fft_xn_re[7:1] <= 7'b0;
//fft_xn_re[7:0] <= data_in[7:0];
end

// FFT port assignments
assign fft_fwd_inv_we = (initclock == 2'b01);
assign fft_fwd_inv = 1;
assign fft_ce = 1;
assign fft_xn_im[7:0] = 8'b0;
assign fft_sclr = 0;
assign fft_clock = clock;

// FFT_FSM to control the FFT instance

fft_FSM fft_FSM(
.clock(clock),
.reset(reset),
.start(start),
.reset_pxl_pos_in(reset_pxl_pos_in),
.re_in(re_in),
.we_out(we_out),
.enable_seq_access_out(enable_seq_access_out),

```

```

    .reset_pxl_pos_out(reset_pxl_pos_out),
    .fft_dv(fft_dv),
    .fft_start(fft_start),
    .busy(busy)
);

//      Sum_Square to compute the square of the magnitude (sum of square of Img and Real parts)

    sum_square uut (
        .clock(clock),
        .reset(reset),
        .re(fft_xk_re[15:0]),
        .im(fft_xk_im[15:0]),
        .sum_sq(sum_sq),
        .M_sum_sq(M_sum_sq)
);
endmodule

```

G.5.2 FFT FSM

```

'timescale 1ns / 1ps
///////////////////////////////
//      Kevin Amendt      kamendt@mit.edu
//      6.111 Final Project: Fingerprint Identification
//
// Create Date:      19:23:55 05/14/06
// Design Name:
// Module Name:     fft_FSM
// Project Name:
// Target Device:
// Tool versions:
// Description:
//
// Dependencies:
//
// Revision:
// Revision 0.01 - File Created
// Additional Comments:
//
/////////////////////////////
module fft_FSM(clock, reset, start,
                reset_pxl_pos_in, re_in,
                we_out, enable_seq_access_out,
                reset_pxl_pos_out
                ,fft_dv,fft_start,

```

```

    busy

);

// Inputs
input      clock, reset, start;
input      fft_dv;

// Outputs
output     reset_pxl_pos_in, re_in;
output     we_out, enable_seq_access_out, reset_pxl_pos_out;
output     fft_start;
output     busy;

// Registers
reg [2:0]   state, next;
reg [7:0]   read_count;
reg [7:0]   write_count;

reg      reset_pxl_pos_in, reset_pxl_pos_out, re_in, we_out, enable_seq_access_out, ff
reg      busy;

// State Parameters
parameter SYS_RESET = 0;
parameter IDLE = 1;
parameter STARTFFT = 2;
parameter READ_VALUES = 3;
parameter WAIT = 4;
parameter WRITE_COEF = 5;
parameter DISCARD_COEF = 6;

// Sequential Always Block
always @ (posedge clock or posedge reset)
  if(reset)
    state <= SYS_RESET;
  else begin
    state <= next;
    reset_pxl_pos_in <= (next == STARTFFT);
    reset_pxl_pos_out <= (next == STARTFFT);
    re_in <= (next == READ_VALUES);
    we_out <= (next == WRITE_COEF);
    enable_seq_access_out <= (next == WRITE_COEF);
    fft_start <= ((next == STARTFFT)) ;
    busy <= ~(next == IDLE);
    if(next == IDLE) begin
      read_count <= 0;

```

```

        write_count <= 0;
    end
    else if(next == READ_VALUES)
        read_count <= read_count + 1;
    else if(next == WRITE_COEF || next == DISCARD_COEF)
        write_count <= write_count + 1;
    end

//      Combinational Always Block
always @ (state or start or fft_dv or read_count or write_count)
case(state)
    SYS_RESET:
        next = IDLE;
    IDLE:
        if(start)    next = STARTFFT;
        else         next = IDLE;
    STARTFFT:
        next = READ_VALUES;
    READ_VALUES:
        if(read_count == 128)   next = WAIT;
        else                   next = READ_VALUES;
    WAIT:
        if(fft_dv)   next = WRITE_COEF;
        else         next = WAIT;
    WRITE_COEF:
        if(write_count == 16)   next = DISCARD_COEF;
        else                   next = WRITE_COEF;
    DISCARD_COEF:
        if(write_count == 200)  next = IDLE;
        else                   next = DISCARD_COEF;
endcase

//Combinational Output Assignment Block

endmodule

```

G.5.3 Squared Magnitude of Coefficients

```

'timescale ins / 1ps
///////////////////////////////
//  Kevin Amendt  kamendt@mit.edu
//  6.111 Final Project: Fingerprint Identification
//
//  Create Date:  17:51:48 05/14/06

```

```

//      Module Name:      multiply_test
//
//      This module takes in the real and imaginary parts from the FFT unit
//      and sums the square of each part.
//
//      Registers are used to ensure that timing requirements are met in the fft module
//
// Revision:
// Revision 0.01 - File Created
// Additional Comments:
//
///////////////////////////////
module sum_square(clock, reset, re, im, sum_sq, M_sum_sq);

    //      Inputs
    input          clock, reset;
    input [15:0]    re, im;

    //      Outputs
    output [16:0]   sum_sq;
    output [31:0]   M_sum_sq;
    //      Registers
    reg [31:0] M_sum_sq;

    //      Wires -- Switch from 2's complement to pos unsigned int
    wire [7:0]      re_unsigned = (re[7]) ? ({1'b0,~re[6:0]}+1) : ({1'b0, re[6:0]});
    wire [7:0]      im_unsigned = (im[7]) ? ({1'b0,~im[6:0]}+1) : ({1'b0, im[6:0]});

    //      Sequential Always Block
    always @ (posedge clock)
        if(reset)  M_sum_sq <= 0;
        else begin
            M_sum_sq <= re_unsigned*re_unsigned + im_unsigned*im_unsigned;
        end

    //      Assignments
    assign sum_sq[16:0] = M_sum_sq[16:0];           // discard upper 9 bits of M_sum_sq
                                                    // shouldn't ever break 8 bits

endmodule

```

H Buffer Selector

'timescale 1ns / 1ps

```

/***********************
 * FFT Coefficient Reverse Multiplexer
 *
 * Determines destination database for fourier coefficients
 * based on the add_user input and the user_id input.
 *
 * Runs synchronously with FFT module. in_RST is the start
 * signal.
 *
************************/

module fft_coeff_mux( // selector
                     add_user,
                     user_id,
                     // data in
                     in_we,
                     in_RST,
                     in_data,
                     // data out
                     bufA_data,
                     bufA_we,
                     bufA_addr,
                     bufB_data,
                     bufB_we,
                     bufB_addr,
                     // system
                     clock,
                     reset );

```

```

///////////////////////////////
// Data Pins
///////////////////////////////
// MUX Selector
input add_user;
input [2:0] user_id;

// Data In
input in_we;
input in_RST;
input [31:0] in_data;

// Data Out
output [31:0] bufA_data;

```

```

output bufA_we;
output [3:0] bufA_addr;
output [31:0] bufB_data;
output bufB_we;
output [6:0] bufB_addr;

// System
input clock;
input reset;

///////////////////////////////
// Parameters
/////////////////////////////
parameter IDLE = 0;
parameter SYS_RESET = 1;
parameter START = 2;
parameter WRITE_COEFF = 3;
parameter PAUSE = 4;

///////////////////////////////
// Registers
/////////////////////////////
reg [31:0] bufA_data;
reg bufA_we;
reg [3:0] bufA_addr_delay, Mid_bufA_addr;
reg [31:0] bufB_data;
reg bufB_we;
reg [6:0] bufB_addr_delay, Mid_bufB_addr;
reg [2:0] state, next;
reg [4:0] coeff_cnt;
reg add_user_save;

///////////////////////////////
// Code
/////////////////////////////

// Sequential Always block
always @ (posedge clock or posedge reset)
    if (reset) begin
        state <= SYS_RESET;
        coeff_cnt <= 0;
    end
    else begin

```

```

state <= next;
bufA_data <= (coeff_cnt > 2) ? in_data : 0;
bufB_data <= (coeff_cnt > 2 ) ? in_data : 0;
Mid_bufA_addr <= bufA_addr_delay;
Mid_bufB_addr <= bufB_addr_delay;
if (next == START) begin
    add_user_save <= add_user;
    coeff_cnt <= 0;
    bufA_addr_delay <= 0;
    bufB_addr_delay <= user_id << 4;
end
if (next == WRITE_COEFF) begin
    if (add_user_save) begin
        bufB_we <= in_we;
        bufA_we <= 0;
    end
    else begin
        bufA_we <= in_we;
        bufB_we <= 0;
    end
    bufA_addr_delay <= bufA_addr_delay + 1;
    bufB_addr_delay <= bufB_addr_delay + 1;
end
else begin
    bufB_we <= 0;
    bufA_we <= 0;
end
if (state == WRITE_COEFF)
coeff_cnt <= coeff_cnt + 1;
else
coeff_cnt <= 0;
end

// Combinational Always Block
always @ (state or in_rst or coeff_cnt)
case (state)
IDLE: if (in_rst) next = START;
      else next = IDLE;
SYS_RESET: next = IDLE;
START: next = /*PAUSE;
PAUSE: next = */WRITE_COEFF;
WRITE_COEFF: if (coeff_cnt == 15 ) next = IDLE;
             else next = WRITE_COEFF;
endcase

```

```

assign bufA_addr = (state == IDLE) ? (4'hz): (Mid_bufA_addr);
assign bufB_addr = (state == IDLE) ? (7'hz): (Mid_bufB_addr);

endmodule

```

I Validation Unit

I.1 Validation

```

'timescale 1ns / 1ps
///////////////////////////////
//    6.111 Fingerprint ID
//    Kevin Amendt    kamendt@mit.edu
//
// Top level instantiation of memory and sq_errors and comparator
// Processing block can write to the memory via the we & din inputs
//
///////////////////////////////

module validation(clock, reset, compare, match, din_row_A, din_row_B,
                  we_row_A, we_row_B, din_col_A, din_col_B, we_col_A,
                  we_col_B, row_addr_A, row_addr_B, col_addr_A, col_addr_B,
                  busy, img_num, threshold,
                  add_user,
                  user_id
                );

```

parameter ENABLED = 1;

```

//    Inputs
input      clock, reset, compare;
input [31:0] din_row_A, din_row_B, din_col_A, din_col_B;
input      we_row_A, we_row_B, we_col_A, we_col_B;
input [63:0] threshold;
input [2:0]  user_id;
input      add_user;

//    Outputs
output     match, busy;
output [3:0] img_num;

//    Inout
inout    [3:0] row_addr_A, col_addr_A;

```

```

inout  [6:0] row_addr_B, col_addr_B;

//    Wires
wire  [3:0]    row_addr_A, col_addr_A;
wire  [6:0]    row_addr_B, col_addr_B;
wire  [31:0]   row_in_A, row_in_B,col_in_A, col_in_B;
wire          row_done,  row_start;
wire  [15:0]   row_sq_error,col_sq_error;
wire          col_done, col_start;
// wire  [3:0]    img_num;

//    Instances

//    Instanstialtion of memory elements

buffer_1x16x32 row_mem_A(
    .addr(row_addr_A),
    .clk(clock),
    .din(din_row_A),
    .dout(row_in_A),
    .en(ENABLED),
    .we(we_row_A)
);

buffer_1x16x32 col_mem_A(
    .addr(col_addr_A),
    .clk(clock),
    .din(din_col_A),
    .dout(col_in_A),
    .en(ENABLED),
    .we(we_col_A)
);

buffer_8x16x32 row_mem_B(
    .addr(row_addr_B),
    .clk(clock),
    .din(din_row_B),
    .dout(row_in_B),
    .en(ENABLED),
    .we(we_row_B)
);

buffer_8x16x32 col_mem_B(
    .addr(col_addr_B),
    .clk(clock),

```

```

.din(din_col_B),
.dout(col_in_B),
.en(ENABLED),
.we(we_col_B)
);

// Instantiation of validation logic
comparator comparator (
.clock(clock),
.reset(reset),
.threshold(threshold),
.sq_error_row(row_sq_error),
.sq_error_col(col_sq_error),
.done_row(row_done),
.done_col(col_done),
.compare(compare),
.match(match),
.start_row(row_start),
.start_col(col_start),
.img_num(img_num),
.add_user(add_user),
.user_id(user_id),
.busy(busy)
);

```

```

    sq_error ROW_SQ_ERROR (
.clock(clock),
.reset(reset),
.start(row_start),
.Ain(row_in_A),
.Bin(row_in_B),
.img_num(img_num),
.addr_A(row_addr_A),
.addr_B(row_addr_B),
.sq_error(row_sq_error),
.done(row_done)
);

    sq_error COL_SQ_ERROR (
.clock(clock),
.reset(reset),
.start(col_start),
.Ain(col_in_A),
.Bin(col_in_B),
.img_num(img_num),

```

```

    .addr_A(col_addr_A),
    .addr_B(col_addr_B),
    .sq_error(col_sq_error),
    .done(col_done)
  );
}

endmodule

```

I.2 Comparator

```

'timescale 1ns / 1ps
///////////////////////////////
// 6.111 Fingerprint ID
// Kevin Amendt  kamendt@mit.edu
//
// Create Date: 22:32:37 05/11/06
// Design Name: Comparator
// Module Name: comparator
// Description: takes in the Fourier Series Coefficients of two different
//               signals and compares them by summing the error. If this error
//               is below a certain threshold, then it is considered a match.
//
// This module is the comparator. It takes in the squared error
// from the row and columns, sums them, and compares to a threshold
// Also responsible for start and img_num commands to the sq_error modules
//
// Dependencies:
//
// Revision:
// Revision 0.01 - File Created
// Additional Comments:
//
///////////////////////////////
module comparator(clock, reset,
                  sq_error_row, sq_error_col,
                  done_row, done_col,
                  compare, match,
                  start_row, start_col, img_num, busy, threshold,
                  add_user, user_id
);
  // Parameters
  parameter error_width = 64-1;           //bit width of sq_error from sq_error module
  //parameter threshold = 20;//64'd200000; // Threshold value for comparison

```

```

//      Inputs
input                           clock, reset;
input [error_width:0]          sq_error_row, sq_error_col;
input                           done_row, done_col, compare;
input [63:0] threshold;

input add_user;
input [2:0] user_id;
//      Registered Inputs

//      Outputs
output                          match, start_row, start_col, busy;
output [3:0]                     img_num;

//      Registered Outputs
reg                            match, start_row, start_col, busy;
reg [3:0]                      img_num;

//      Registers
reg [3:0]                      state, next;
reg [error_width:0]            sq_error;
reg [7:0]                       entry_exists = 8'b0;

//      State Parameters
parameter no_match_idle = 0;
parameter start_errors = 1;
parameter Wait = 2;
parameter sum = 3;
parameter test = 4;
parameter done_check = 5;
parameter match_idle = 6;
parameter reset_img_num = 7;
parameter inc_img_num = 8;

//      Sequential Always Block
always @ (posedge clock or posedge reset)
    if(reset) begin
        state <= no_match_idle;
        img_num <= 0;
        sq_error <= 0;
        entry_exists <= 8'b0;
    end
    else begin
        if (add_user) entry_exists[user_id] <= 1;
        state <= next;
    end

```

```

busy <= ~((next == match_idle) || (next == no_match_idle));
if(next == sum)
    if(sq_error_row > sq_error_col) sq_error <= sq_error_row;
    else sq_error <= sq_error_col;
else if(next == inc_img_num) img_num <= img_num + 1;
else if((next == no_match_idle) || (next == reset_img_num)) img_num <= 0;
match <= (next == match_idle);
start_row <= (next == start_errors);
start_col <= (next == start_errors);
end

// Combinational Always Block
always @ (state or compare or done_row or done_col or match or sq_error or img_num )
case(state)
    no_match_idle:
        if(compare) next = start_errors;
        else         next = no_match_idle;
    start_errors:
        next = Wait;
    Wait:
        if(done_row && done_col)   next = sum;
        else                         next = Wait;
    sum:
        next = test;
    test:
        if(sq_error < threshold &&
           entry_exists[img_num]) next = match_idle;
        else                      next = inc_img_num;
    inc_img_num:
        next = done_check;
    done_check:
        if(img_num < 8)   next = start_errors;
        else             next = no_match_idle;
    match_idle:
        if(compare)     next = reset_img_num;
        else             next = match_idle;
    reset_img_num:
        next = start_errors;
endcase

endmodule

```

I.3 Summed Squared Error

```

'timescale 1ns / 1ps
////////////////////////////

```

```

//      6.111 Fingerprint ID
//      Kevin Amendt      kamendt@mit.edu
//
//
//      Create Date:      22:45:05 05/11/06
//      Design Name:    Validation
//      Module Name:   sq_error
//
//      Description: takes in the Fourier Transform Coefficients of two different
//                     signals and compares them by summing the square of the error.
//                     This error is sent to a comparator to sum the col and row errors
//                     and compared that error with the threshold value. Memory A is the
//                     scanned image, memory B is the database. IMG_NUM refers to the image
//                     in memory B that is being fetched. Should come from the comparator module
//
//
//      Default values:
//      Calculating 16* FS coefficients
//      Can store 7 databased fingerprints
//      8 bits per coefficient (max magnitude = 255)
//
//
// Revision:
// Revision 0.01 - File Created
// Additional Comments:
//
///////////////////////////////
module sq_error(clock, reset, start, img_num, Ain, Bin, addr_A, addr_B, sq_error, done
               );
//
//      Parameters
parameter coef_width      = 32  -1;                                //# bits per coefficient
parameter coef_number       = 16  -1;                                //# coefficients per image
parameter error_width       = 64  -1;                                // width of error output data
parameter addr_width        = 4   -1;                                //bitlength of coef_number
//
//      Inputs
input                           clock, reset;
input                           start;
input [3:0]                      img_num;
input [coef_width:0]            Ain, Bin;
//
//      Registered Inputs
reg    [coef_width:0]          mid_Ain, mid_Bin;

```

```

//      Outputs
output  [addr_width:0]      addr_A;
output  [6:0]                addr_B;
output  [error_width:0]      sq_error;
output                           done;

//      Registered Outputs
reg     [2:0]                state, next;
reg     [addr_width:0]      M_addr_A;
reg     [6:0]                M_addr_B;
reg     [error_width:0]      sq_error;
reg                           done;

//      State Names
parameter IDLE = 0;
parameter set_sq_error = 1;
parameter read0 = 2;
parameter read1 = 3;
parameter read2 = 4;
parameter error = 5;
parameter error2 = 6;
parameter finished = 7;

//      Sequential Always Block
always @ (posedge clock or posedge reset)
  if(reset) begin
    state <= IDLE;
    done <=1;
    sq_error <= 0;
    M_addr_A <= 0;
    M_addr_B <= 0;
  end
  else begin
    state <= next;
    if((next == error) && (M_addr_A == (coef_number)))  done <= 1;
    else if(start)   done <= 0;
    if(next == read2) begin
      mid_Ain <= Ain;
      mid_Bin <= Bin;
    end
    if(next == set_sq_error) begin
      sq_error <= 0;
      M_addr_A <= 0;
      M_addr_B <= img_num << 4;
    end
  end
end

```

```

    end
    if(next == IDLE)
        sq_error <= sq_error;
    if(next == error) begin
        if(Ain>Bin) sq_error <= sq_error + (mid_Ain-mid_Bin)*(mid_Ain-mid_Bin);
        else         sq_error <= sq_error + (mid_Bin-mid_Ain)*(mid_Bin-mid_Ain);
        M_addr_A <= M_addr_A + 1;
        M_addr_B <= M_addr_B + 1;
    end
end

// Combinational Always Block
always @ (state or start or done)
case(state)
    IDLE:
        if(start) next = set_sq_error;
        else      next = IDLE;
    set_sq_error:
        next = read0;
    read0:
        next = read1;
    read1:
        next = read2;
    read2:
        next = error;
    error:
        if(~done) next = read0;
        else      next = finished;
    finished:
        next = IDLE;
endcase

// Combinational output assignment
assign addr_A = (state == IDLE) ? (4'hz):(M_addr_A);
assign addr_B = (state == IDLE) ? (7'hz):(M_addr_B);

endmodule

```