ChessAl

Play against a computer IRL

The Chess Board

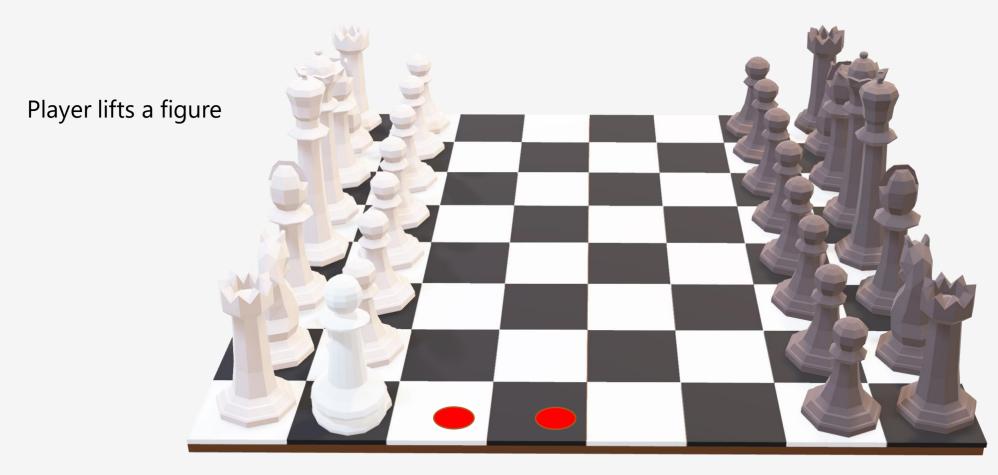
What's so special about it?

- Detects the positions of the figures
- Shows legal moves
- Shows opponent's moves



You can play a chess game against a computer without seeing or knowing how to use a computer.

The Chess Board

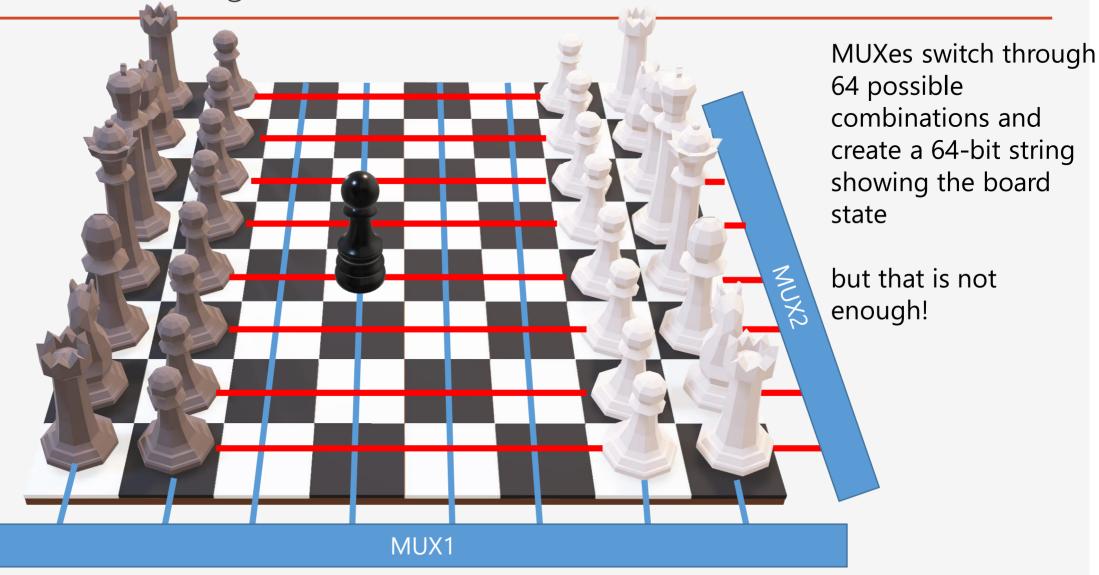


LEDs indicate legal positions

The Chess Board



The Chess Board – Figure detection



Chess Game FSM (Example binary)

Board_state [63:0] example progression





10111111



Chess Game FSM (Example decision tree)

Board States [63:0] example progression







- 1. There are exactly 32 pieces
- 2. All pieces occupy ranks 1,2,7,8
- Orientation is white on top
- Every piece type is now set (Queens on their respective colors)
- 3. from_to [11:0] should alternate between f3 and h3

- Knight location updated
- Send move to PC over UART

Chess Game FSM

Inputs:

- Clk_in Standard 100mhz clock
- [63:0] board_state cleaned bitmask showing current state
 (piece / no piece) of each square
- Board_state_ready goes high when previous modules finish reading + cleaning

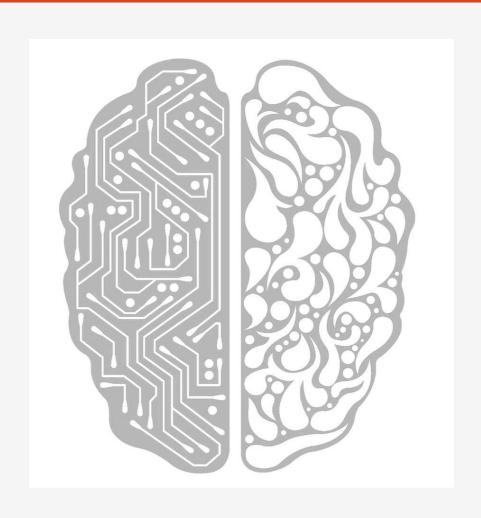
Outputs:

- Show_pos controls when to turn on LEDs
- [11:0] from_to Abstractly controls which LEDs to turn on

Chess Game FSM (Challenges)

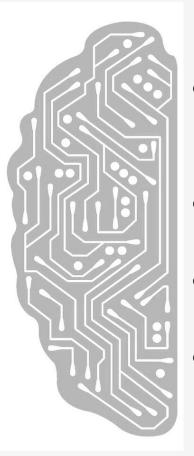
- Intricacies of move validation
- Evaluating possibility of capture when move order is broken
- Anything involving multiple pieces
 - a. Capture
 - b. Castling
 - c. Piece promotion

Chess Board FSM ------ Python Chess AI



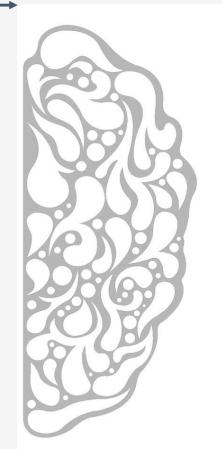
Communicating with python-chess

UART like Lab 2 ("g1f3")

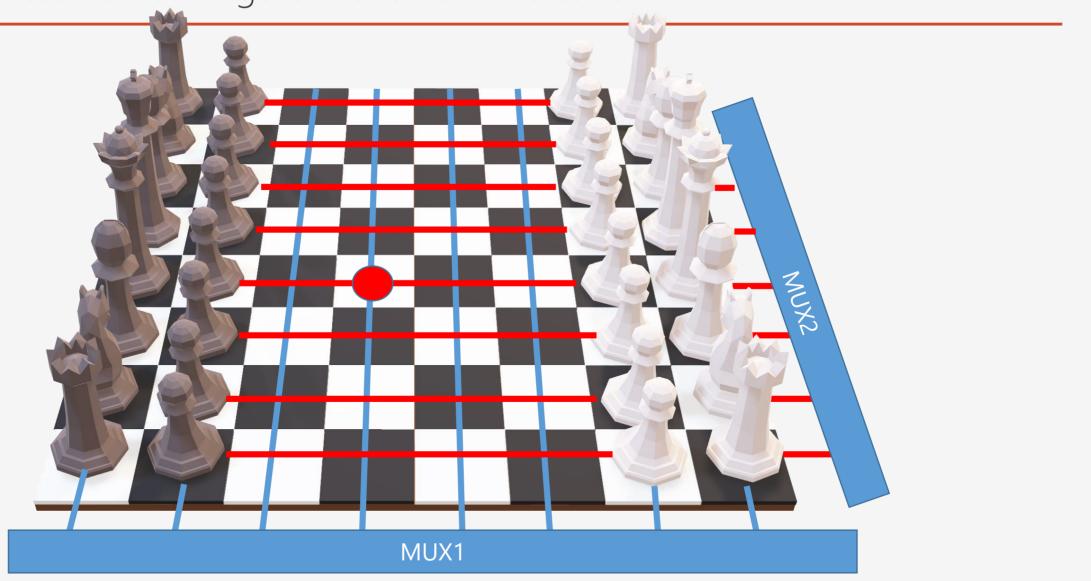


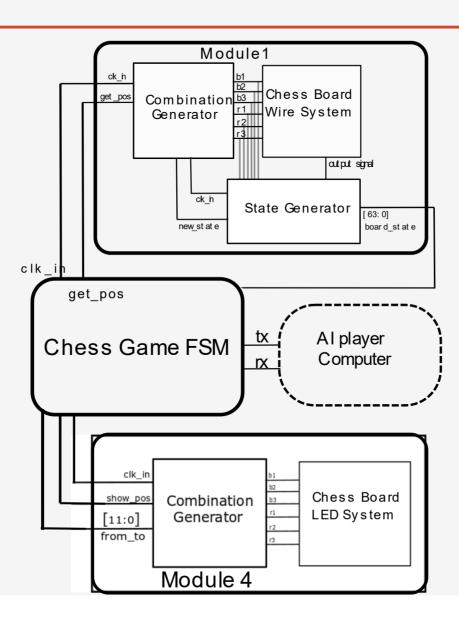
- A full piece movement has occurred
- Validity has been checked
- FSM has been updated
- Convert move to ascii ("q1f3")

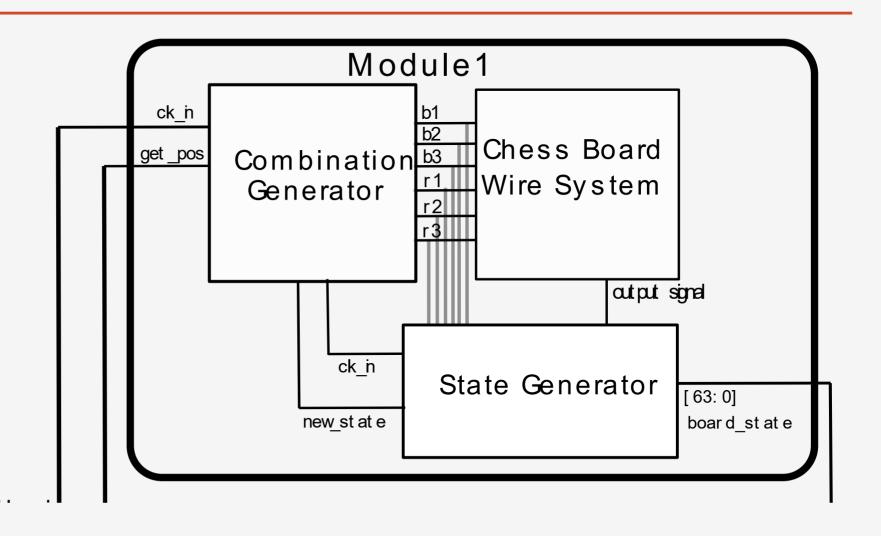
- Receive piece movement
- board.push(chess.
 Move.from_uci(
 "g1f3"))
- result =
 engine.play(board,
 chess.engine.Limit(tim
 e=0.1))
- Send back piece movement

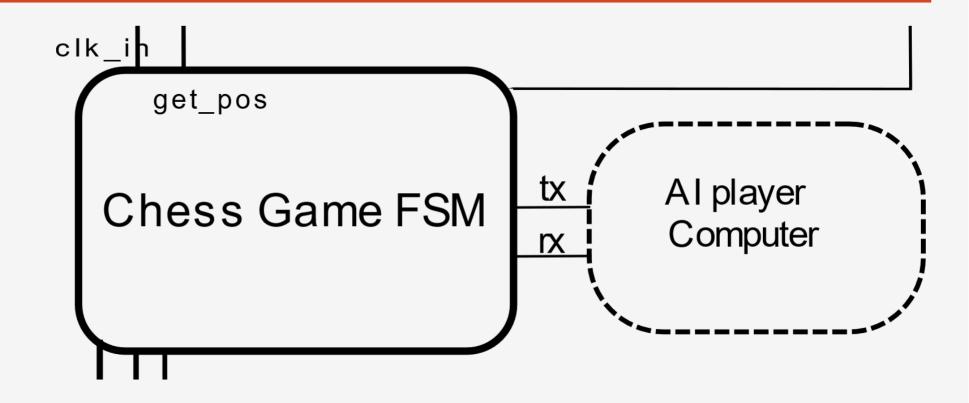


The Chess Board – Figure Movement Indication

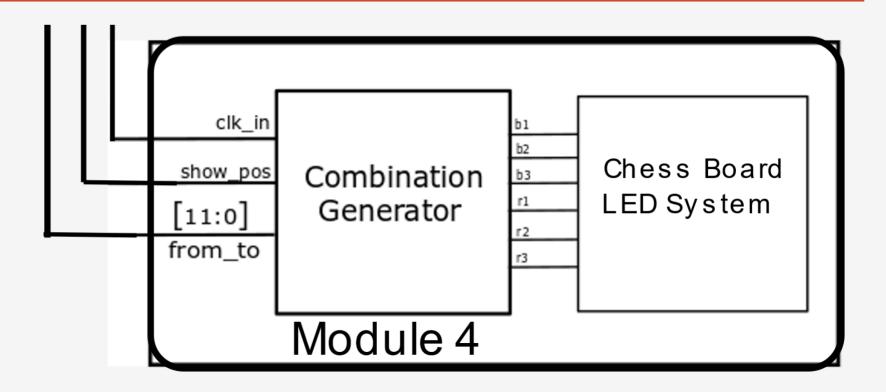








Block Diagram



Project Timeline and Workload		
Week of	Bahrudin	Grayson
Nov 4	 Prepare the chess board hardware (LEDs, wire grid, mux connections) 	Design the initial FSM functionalities
Nov 11	 Finish the hardware. Work on Module 1 – detection of figures 	 Implement an FSM that tracks figures given the occupied squares of the board.
Nov 18	 Work on Module 4 – Displaying of the movements of the opponent. UART communication 	 Add constraints to the movements to the FSM. Convert the movements to appropriate encodings that will be sent to the computer.
Nov 25	Integration of the UART communication, Modules 1 and 4 and the game FSM	
Dec 2	Test the board, game logic, edge cases. Add on screen game state. (Add VGA output of the game progress)	