

Math 18.06, Spring 2013
Problem Set #Exam 3
May 14, 2013

Problem 1. In all of this problem, the 3 by 3 matrix A has eigenvalues $\lambda_1, \lambda_2, \lambda_3$ with independent eigenvectors x_1, x_2, x_3 .

a) What are the trace of A and the determinant of A ?

The trace of A is $\lambda_1 + \lambda_2 + \lambda_3$ and the determinant is $\lambda_1\lambda_2\lambda_3$.

b) Suppose: $\lambda_1 = \lambda_2$. Choose the true statement from 1, 2, 3:

1. A can be diagonalized.
2. A can not be diagonalized.
3. I need more information to decide.

(1) is the correct option, because we know that there exists a full set of independent eigenvectors.

c) From the eigenvalues and eigenvectors, how could you find the matrix A ? Give a formula for A and explain each part carefully.

We can recover A using $A = S\Lambda S^{-1}$, where S is a matrix whose columns are x_1, x_2, x_3 , and Λ is a diagonal matrix whose diagonal entries are $\lambda_1, \lambda_2, \lambda_3$.

d) Suppose $\lambda_1 = 2$ and $\lambda_2 = 5$ and $x_1 = (1, 1, 1)$ and $x_2 = (1, -2, 1)$. Choose λ_3 and x_3 so that A is symmetric positive semidefinite but not positive definite.

If we want A to be symmetric, the third eigenvector x_3 had better be orthogonal to the other two. The quick way to find a vector orthogonal to two given ones in \mathbb{R}^3 is via cross product: $x_3 = x_1 \times x_2 = (3, 0, -3)$.

Alternately, you can use elimination: x_3 should be in the nullspace of

$$A = \begin{bmatrix} 1 & 1 & 1 \\ 1 & -2 & 1 \end{bmatrix}$$

You could also just notice the first and last entries match and guess the answer from that. Either way, x_3 should be a multiple of $(1, 0, -1)$.

As for the eigenvalue, to get a matrix that's positive semidefinite but not positive definite, we need to use $\lambda_3 = 0$.

It doesn't actually ask you to compute A , but here's one that works:

$$A = \begin{bmatrix} 1 & 1 & 1 \\ 1 & -2 & 0 \\ 1 & 1 & -1 \end{bmatrix} \begin{bmatrix} 2 & 0 & 0 \\ 0 & 5 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} 1 & 1 & 1 \\ 1 & -2 & 0 \\ 1 & 1 & -1 \end{bmatrix}^{-1} = \frac{1}{2} \begin{bmatrix} 3 & -2 & 3 \\ -2 & 8 & -2 \\ 3 & -2 & 3 \end{bmatrix}$$

Problem 2. Suppose A has eigenvalues $1, 1/3, 1/2$ and its eigenvectors are the columns of S :

$$S = \begin{bmatrix} 1 & 0 & 0 \\ 3 & 1 & 0 \\ 1 & 1 & 1 \end{bmatrix} \quad \text{with} \quad S^{-1} = \begin{bmatrix} 1 & 0 & 0 \\ -3 & 1 & 0 \\ 1 & -1 & 1 \end{bmatrix}$$

a) What are the eigenvalues and eigenvectors of A^{-1} ?

The eigenvectors of A^{-1} are the same as those of A . Its eigenvalues are the inverses of those of A : $1, 3,$ and 2 .

b) What is the general solution (with 3 arbitrary constants c_1, c_2, c_3) to the differential equation $du/dt = Au$? Not enough to write e^{At} . Use the c 's.

The general solution is

$$\begin{aligned} u(t) &= c_1 e^{\lambda_1 t} x_1 + c_2 e^{\lambda_2 t} x_2 + c_3 e^{\lambda_3 t} x_3 \\ &= c_1 e^t \begin{bmatrix} 1 \\ 3 \\ 1 \end{bmatrix} + c_2 e^{t/3} \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} + c_3 e^{t/2} \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \end{aligned}$$

c) Start with the vector $u = (1, 4, 3)$ from adding up the three eigenvectors: $u = x_1 + x_2 + x_3$. Think about the vector $v = A^k u$ for VERY large powers k . What is the limit of v as $k \rightarrow \infty$?

We have

$$A^k u = A^k (x_1 + x_2 + x_3) = \lambda_1^k x_1 + \lambda_2^k x_2 + \lambda_3^k x_3 = x_1 + \left(\frac{1}{3}\right)^k x_2 + \left(\frac{1}{2}\right)^k x_3.$$

When k is very large, the two rightmost terms both go to 0, while the first one is an unchanging x_1 . The limit v is therefore equal to x_1 .

Problem 3. a) For a really large number N , will this matrix be positive definite? Show why or why not.

$$A = \begin{bmatrix} 2 & 4 & 3 \\ 4 & N & 1 \\ 3 & 1 & 4 \end{bmatrix}$$

The easiest test to use here is going to be to check whether the upper-left determinants are positive.

1×1 : This is 2, which is always greater than 0.

2×2 : This is $2N - 16$, which is greater than 0 if N is really large (in particular if $N > 8$).

3×3 : Use the method of your choice to compute the determinant of A , in terms of N . By the (not so) big formula, it's

$$\det A = 8N + 12 + 12 - 2 - 64 - 9N = -42 - N.$$

This is going to be very negative if N is really large. So the matrix will not be positive definite.

b)

Suppose: A is positive definite symmetric
 Q is orthogonal (same size as A)
 B is $Q^T A Q = Q^{-1} A Q$.

Show that: B is also symmetric.
 B is also positive definite.

First we show that B is symmetric. This means we need to check $B^T = B$. Using what we're told,

$$B^T = (Q^T A Q)^T = Q^T A^T (Q^T)^T = Q^T A Q = B,$$

Note that in the next-to-last step we used the fact that A itself is symmetric ($A^T = A$).

For positive definiteness, one way is to use the energy test. If x is any nonzero vector, then

$$x^T B x = x^T (Q^T A Q) x = (Qx)^T A (Qx) = y^T A y,$$

where $y = Qx$. We know that y is nonzero, because Q is orthogonal and therefore has no nullspace.

Another approach is via eigenvalues. We know that $B = Q^{-1} A Q$, so B is similar to A . That means that they have the same eigenvalues. Since A is positive definite, its eigenvalues are all positive, so those of B are as well.

A third approach: A is positive definite, so $A = R^T R$ for some R with independent columns. Then $B = Q^T R^T R Q = (RQ)^T (RQ)$. RQ is a matrix with independent columns, since Q is orthogonal. So B is positive definite.

c) If the SVD of A is $U \Sigma V^T$, how do you find the orthogonal V and the diagonal Σ from the matrix A ?

First compute the matrix $A^T A$. Find the eigenvalues and eigenvectors. The first r columns of V should be length 1 eigenvectors of $A^T A$, corresponding to nonzero eigenvalues, arranged

in order of decreasing eigenvalue. (A small complication: if there is a repeated eigenvalue, make sure to pick orthogonal eigenvectors for that eigenvalue). The diagonal entries of Σ should be square roots of the eigenvalues of $A^T A$, again in decreasing order.

The remaining columns of V should be an orthonormal basis for the nullspace of $A^T A$ (which is the same thing as the nullspace of A). This will give enough columns for V to be a square matrix. The other diagonal entries of Σ should be 0.