

18.06 Problem Set 3

Due Wednesday, Feb. 28, 2007 at 4:00 p.m. in 2-106

Each problem is worth 10 points. The date next to the problem number indicates the lecture in which the material is covered.

Problem 1 Tuesday 2/20

For each of the following questions, please explain your answer.

(a) Let $F = \left\{ \begin{bmatrix} x \\ y \\ z \end{bmatrix} : x \geq y \geq z \geq 0 \right\}$. Is F a subspace of \mathbb{R}^3 ?

(b) The set of all real functions forms a vector space. Is the set of all functions of the form $f(x) = ax^2$ (where a can take any real value) a subspace? How about the set of all functions of the form $f(x) = x^2 + bx + c$ (where b and c can take any real value)?

(c) Let A be a fixed 3×2 matrix. Let F be the set of all 3×3 matrices B such that $BA = \begin{bmatrix} 0 & 0 \\ 0 & 0 \\ 0 & 0 \end{bmatrix}$.

Is F a subspace of the space of all 3×3 matrices?

Problem 2 Tuesday 2/20

Do problem 22 of section 3.1 in your book.

Problem 3 Wednesday 2/21

Do problems 5, 6 and 7 of section 3.2 in your book.

Problem 4 Wednesday 2/21

Do problem 25 of section 3.2 in your book.

Problem 5 Friday 2/23

Do problem 7 of section 3.4 in your book.

Problem 6 Friday 2/23

Do problem 21 of section 3.4 in your book.

Problem 7 Friday 2/23

Let $A = \begin{bmatrix} 1 & 2 & -2 & 1 & 0 \\ 2 & 4 & -3 & 3 & 0 \\ -3 & -6 & 5 & 4 & 2 \\ 5 & 10 & -9 & 6 & 0 \end{bmatrix}$.

- Transform A to (ordinary) echelon form.
- What are the pivots? What are the free variables?
- Now transform A to row reduced echelon form.
- Give the special solutions. What is the nullspace $N(A)$?
- What is the rank of A ?

- (f) Give the complete solution to $Ax = b$, where $b = A \begin{bmatrix} 1 \\ 0 \\ 1 \\ 0 \\ 1 \end{bmatrix}$.

Problem 8 Monday 2/26

Suppose the $m \times n$ matrix R is in row reduced echelon form $\begin{bmatrix} I & F \\ \mathbf{0} & \mathbf{0} \end{bmatrix}$, with r nonzero rows and first r columns as pivot columns.

- (a) Describe the column space and the nullspace of R .
(b) Do the same for the $m \times 2n$ matrix $B = [R \ R]$.
(c) Do the same for the $2m \times n$ matrix $C = \begin{bmatrix} R \\ R \end{bmatrix}$.
(d) Do the same for the $2m \times 2n$ matrix $D = \begin{bmatrix} R & R \\ R & R \end{bmatrix}$.

Problem 9 Monday 2/26

Do problem 17 of section 3.3 in your book.

Problem 10 Monday 2/26

Suppose the $m \times n$ matrix A ($m < n$) has a *right inverse* B , that is, a matrix B such that $AB = I$, the identity.

- (a) What must the dimensions (the height and width) of B and of I be?
(b) Try calculating B in MATLAB: let $A = \begin{bmatrix} 4 & -3 & 1 \\ -2 & 0 & 2 \end{bmatrix}$ and use `A \ I`. (This is the code in MATLAB for finding a matrix B such that $AB = I$. The $k \times k$ identity matrix is `eye(k)` in MATLAB.)
(c) Now try calculating B another way, with `rref([A I])`. (This is the reduced row echelon form, the result of Gauss-Jordan elimination.) What do you get? Use your result to state another, different, B with $AB = I$. Why is B not unique?
(d) Why can't there be a left inverse $CA = I$?