18.06 (Fall '13) Problem Set 10 Solutions

- 1. (a) Linear. XB is linear since by definition of matrix multiplication each entry of XB is just a linear combination of the entries of X. Similarly, AX is linear. Since a composition of linear transformations is linear, we also have AXB is linear.
 - (b) Not linear. Consider any non-zero X. Then $(2X)^T A(2X) = 4X^T A X \neq 2X^T A X$.
 - (c) Linear. AX and XB are linear as before, and the sum of linear transformations is linear.
 - (d) Linear. The trace is just a linear combination of the entries of X.
 - (e) Not linear. Consider X = I, the 2 by 2 identity matrix. Then $det(2I) = 4 \neq 2 det(I)$.
- 2. Yes, it is linear.

We have the transformation $T(f(x)) = g(x) = f(x^2 + x)$. This is just saying that our transformation T replaces each x with $x^2 + x$. For linearity, we need to check that cf(x) goes to cg(x) and that $f_1(x) + f_2(x)$ goes to $g_1(x) + g_2(x)$. Clearly,

$$T(cf(x)) = cf(x^2 + x) = cg(x)$$

and

$$T(f_1(x) + f_2(x)) = f_1(x^2 + x) + f_2(x^2 + x) = g_1(x) + g_2(x),$$

thus this transformation is linear.

3. <u>Problem 37 from 7.2.</u>

We first find the result of the proposed transformation on each of the input basis "vectors" v_1, v_2, v_3, v_4 . These can be written as linear combinations of the same basis "vectors".

For example,

$$T(v_1) = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} = \begin{bmatrix} a & 0 \\ c & 0 \end{bmatrix} = av_1 + cv_3.$$

Similarly,

$$T(v_2) = av_2 + cv_4, \ T(v_3) = bv_1 + dv_3, \ T(v_4) = bv_2 + dv_4$$

Noting that the transformation of the basis "vector" v_i gives us the *i*th column of A, we conclude

A =	$\begin{bmatrix} a \\ 0 \end{bmatrix}$	$\begin{array}{c} 0 \\ a \end{array}$	$b \\ 0$	$\begin{bmatrix} 0\\b \end{bmatrix}$
	$\begin{vmatrix} c \\ 0 \end{vmatrix}$	$0 \\ c$	d	$\begin{bmatrix} 0 \\ d \end{bmatrix}$
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4. <u>Problem 35 from 7.2.</u>

The Haar wavelet basis for \mathbb{R}^8 is

$$w_{1} = [1, 1, 1, 1, 1, 1, 1]^{T}$$

$$w_{2} = [1, 1, 1, 1, -1, -1, -1, -1]^{T}$$

$$w_{3} = [1, 1, -1, -1, 0, 0, 0, 0]^{T}$$

$$w_{4} = [0, 0, 0, 0, 1, 1, -1, -1]^{T}$$

$$w_{5} = [1, -1, 0, 0, 0, 0, 0, 0]^{T}$$

$$w_{6} = [0, 0, 1, -1, 0, 0, 0, 0]^{T}$$

$$w_{7} = [0, 0, 0, 0, 1, -1, 0, 0]^{T}$$

$$w_{8} = [0, 0, 0, 0, 0, 0, 1, -1]^{T}.$$

Note that these vectors form an orthogonal basis for \mathbb{R}^8 .

5. Problem 5 from 7.2.

T is a linear transformation from the three-dimensional space V to the three-dimensional space W. $T(v_i)$ is a combination $a_{1i}w_1 + a_{2i}w_2 + a_{3i}w_3$ of the output basis for W. The a's then form the *i*th column of the matrix A. For example,

$$T(v_1) = 0w_1 + 1w_2 + 0w_3$$

gives the first column: $[0, 1, 0]^T$. Repeating this we find,

$$T(v_2) = 1w_1 + 0w_2 + 1w_3,$$

$$T(v_3) = 1w_1 + 0w_2 + 1w_3.$$

Therefore,

$$A = \begin{bmatrix} 0 & 1 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 1 \end{bmatrix},$$

and

$$A\begin{bmatrix}1\\1\\1\end{bmatrix} = \begin{bmatrix}0 & 1 & 1\\1 & 0 & 0\\0 & 1 & 1\end{bmatrix} \begin{bmatrix}1\\1\\1\end{bmatrix} = \begin{bmatrix}2\\1\\2\end{bmatrix}.$$

This is equivalent to the fact that $T(v_1+v_2+v_3) = 2w_1+w_2+2w_3$, which is demonstrable by virtue of the linearity of T:

$$T(v_1 + v_2 + v_3) = T(v_1) + T(v_2) + T(v_3) = (w_2) + (w_1 + w_3) + (w_1 + w_3) = 2w_1 + w_2 + 2w_3.$$

6. <u>Problem 23 from 7.2.</u>

We require that the matrix
$$M = \begin{bmatrix} m_1 & m_4 & m_7 \\ m_2 & m_5 & m_8 \\ m_3 & m_6 & m_9 \end{bmatrix}$$
 is invertible, namely $\det(M) \neq 0$.

Note: the matrix M represents a change of basis matrix that takes parabolas in the proposed basis v_1, v_2, v_3 to a different (obviously complete) basis for parabolas $w_1 = 1, w_2 = x, w_3 = x^2$. Thus to be able to represent all parabolas from this complete basis (w_1, w_2, w_3) in the proposed basis (v_1, v_2, v_3) , we must require that M^{-1} exists.

7. <u>Problem 8 from 9.3.</u>

To find $|\lambda|_{max}$ we need to find the eigenvalues of the iteration matrix $B = S^{-1}T$.

For **Jacobi**,
$$S = \begin{bmatrix} a & 0 \\ 0 & d \end{bmatrix}$$
 and $T = \begin{bmatrix} 0 & b \\ c & 0 \end{bmatrix}$.
So we have $B = S^{-1}T = \begin{bmatrix} 1/a & 0 \\ 0 & 1/d \end{bmatrix} \begin{bmatrix} 0 & b \\ c & 0 \end{bmatrix} = \begin{bmatrix} 0 & b/a \\ c/d & 0 \end{bmatrix}$.
The characteristic polynomial of B is $\lambda^2 - bc/ad = 0$ which gives $\lambda = \pm (bc/ad)^{1/2}$.
So $|\lambda| = |(bc/ad)^{1/2}| = |bc/ad|^{1/2}$. Therefore $\boxed{|\lambda|_{max} = |bc/ad|^{1/2}}$.
For **Gauss-Seidel**, $S = \begin{bmatrix} a & 0 \\ c & d \end{bmatrix}$ and $T = \begin{bmatrix} 0 & b \\ 0 & 0 \end{bmatrix}$.
So we have $B = S^{-1}T = \begin{bmatrix} 1/a & 0 \\ -c/ad & 1/d \end{bmatrix} \begin{bmatrix} 0 & b \\ 0 & 0 \end{bmatrix} = \begin{bmatrix} 0 & b/a \\ 0 & -bc/ad \end{bmatrix}$.
B is upper triangular so we can read the eigenvalues off the diagonal: $\lambda = 0, -bc/ad$.
So $|\lambda| = 0, |bc/ad|$. Therefore $\boxed{|\lambda|_{max} = |bc/ad|}$.