

18.06 Problem Set 8

SOLUTIONS

1. Section 6.2, Problem 42

Answers: B has eigenvalues $\lambda = i, -i$, so B^4 has eigenvalues $\lambda^4 = 1, 1$; C has eigenvalues $\lambda = (1 \pm i\sqrt{3})/2 = \exp(\pm\pi i/3)$, so C^3 has eigenvalues $\lambda^3 = -1, -1$. Thus $C^3 = -I$ and $C^{1024} = -C$.

2. Section 6.3, Problem 3

Answers: $\begin{bmatrix} y' \\ y'' \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ 4 & 5 \end{bmatrix} \begin{bmatrix} y \\ y' \end{bmatrix}$, and $\lambda = \frac{1}{2}(5 \pm \sqrt{41})$.

3. Section 6.3, Problem 10

Solution: (b) When A is skew-symmetric, $\|u(t)\| = \|e^{At}u(0)\| = \|u(0)\|$. So e^{At} is an *orthogonal* matrix. Another argument:

$$Q = e^{At} = \sum_{k=0}^{\infty} \frac{A^k t^k}{k!},$$

so

$$Q^T = \sum_{k=0}^{\infty} \frac{(A^T)^k t^k}{k!} = \sum_{k=0}^{\infty} \frac{(-A)^k t^k}{k!} = e^{-At}.$$

Hence $Q^T Q = e^{-At} e^{At} = I$.

4. Section 6.3, Problem 11

Answers: (a) $\begin{bmatrix} 1 \\ 0 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} 1 \\ i \end{bmatrix} + \frac{1}{2} \begin{bmatrix} 1 \\ -i \end{bmatrix}$.

(b) $u(t) = \frac{1}{2} e^{it} \begin{bmatrix} 1 \\ i \end{bmatrix} + \frac{1}{2} e^{-it} \begin{bmatrix} 1 \\ -i \end{bmatrix} = \begin{bmatrix} \cos t \\ \sin t \end{bmatrix}$.

5. Section 6.3, Problem 23

Solution: We have $A^2 = A$, so $A^3 = A^4 = \dots = A$, and

$$e^{At} = I + \sum_{k=1}^{\infty} \frac{A^k t^k}{k!} = I + \sum_{k=1}^{\infty} \frac{A t^k}{k!} = I + \left(\sum_{k=1}^{\infty} \frac{t^k}{k!} \right) \cdot A = I + (e^t - 1)A = \begin{bmatrix} e^t & 3(e^t - 1) \\ 0 & 1 \end{bmatrix}.$$

6. Section 8.3, Problem 7

Answers: $\begin{bmatrix} .8 & .3 \\ .2 & .7 \end{bmatrix} = \begin{bmatrix} .6 & -1 \\ .4 & 1 \end{bmatrix} \begin{bmatrix} 1 & \\ & .5 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ -.4 & .6 \end{bmatrix}$; A^{16} has the same factors with $(.5)^{16}$ instead of .5 in the middle matrix.

7. Section 8.3, Problem 8

Answers: $(.5)^k \rightarrow 0$ gives $A^k \rightarrow A^\infty$; the general form of a matrix producing the steady state $(.6, .4)$ is $A = \begin{bmatrix} .6 + .4a & .6 - .6a \\ .4 - .4a & .4 + .6a \end{bmatrix}$ with $-2/3 \leq a \leq 1$.

8. Section 8.3, Problem 9

Answers: $u_1 = (0, 0, 1, 0)$, $u_2 = (0, 1, 0, 0)$, $u_3 = (1, 0, 0, 0)$, $u_4 = u_0 = (0, 0, 0, 1)$. The eigenvalues are all the fourth roots of 1, namely, $1, i, -1, -i$. As demonstrated by this example, a Markov matrix with zeroes may have more than one eigenvalue of magnitude 1; a Markov matrix containing only positive entries has exactly one eigenvalue of magnitude 1 (and equal to 1).

9. Section 8.3, Problem 10

Solution: Suppose M is a Markov matrix. Since the entries of M are nonnegative, so are the entries of M^2 . The columns of M each add up to 1, i.e. $[1 \ 1 \ \dots \ 1]M = [1 \ 1 \ \dots \ 1]$, hence

$$[1 \ 1 \ \dots \ 1]M^2 = ([1 \ 1 \ \dots \ 1]M) \cdot M = [1 \ 1 \ \dots \ 1]M = [1 \ 1 \ \dots \ 1],$$

i.e. the columns of M^2 each add up to 1. We conclude that M^2 is also a Markov matrix.

10. Section 8.3, Problem 12

Solution: To make the columns add up to 1, the last row has to be $.2, .3, .5$. If A is a symmetric Markov matrix, then not only its columns but also its rows each add up to 1, and hence

$$A \cdot \begin{bmatrix} 1 \\ 1 \\ \dots \\ 1 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ \dots \\ 1 \end{bmatrix},$$

i.e. $(1, \dots, 1)$ is the steady state eigenvector of A .

11. (a) After reordering the eigenvalues and scaling the eigenvectors, we obtain the following

results:

$$\begin{aligned}
 A_4 &= \begin{bmatrix} 1 & 2 & 3 & 4 \\ 2 & 1 & 2 & 3 \\ 3 & 2 & 1 & 2 \\ 4 & 3 & 2 & 1 \end{bmatrix} \begin{bmatrix} 1 & & & \\ & 2 & & \\ & & 3 & \\ & & & 4 \end{bmatrix} \begin{bmatrix} -0.4 & 0.5 & 0 & 0.1 \\ 0.5 & -1 & 0.5 & 0 \\ 0 & 0.5 & -1 & 0.5 \\ 0.1 & 0 & 0.5 & -0.4 \end{bmatrix}; \\
 A_5 &= \begin{bmatrix} 1 & 2 & 3 & 4 & 5 \\ 2 & 1 & 2 & 3 & 4 \\ 3 & 2 & 1 & 2 & 3 \\ 4 & 3 & 2 & 1 & 2 \\ 5 & 4 & 3 & 2 & 1 \end{bmatrix} \begin{bmatrix} 1 & & & & \\ & 2 & & & \\ & & 3 & & \\ & & & 4 & \\ & & & & 5 \end{bmatrix} \cdot \frac{1}{12} \begin{bmatrix} -5 & 6 & 0 & 0 & 1 \\ 6 & -12 & 6 & 0 & 0 \\ 0 & 6 & -12 & 6 & 0 \\ 0 & 0 & 6 & -12 & 6 \\ 1 & 0 & 0 & 6 & -5 \end{bmatrix}; \\
 A_6 &= \begin{bmatrix} 1 & 2 & 3 & 4 & 5 & 6 \\ 2 & 1 & 2 & 3 & 4 & 5 \\ 3 & 2 & 1 & 2 & 3 & 4 \\ 4 & 3 & 2 & 1 & 2 & 3 \\ 5 & 4 & 3 & 2 & 1 & 2 \\ 6 & 5 & 4 & 3 & 2 & 1 \end{bmatrix} \begin{bmatrix} 1 & & & & & \\ & 2 & & & & \\ & & 3 & & & \\ & & & 4 & & \\ & & & & 5 & \\ & & & & & 6 \end{bmatrix} \cdot \frac{1}{14} \begin{bmatrix} -6 & 7 & 0 & 0 & 0 & 1 \\ 7 & -14 & 7 & 0 & 0 & 0 \\ 0 & 7 & -14 & 7 & 0 & 0 \\ 0 & 0 & 7 & -14 & 7 & 0 \\ 0 & 0 & 0 & 7 & -14 & 7 \\ 1 & 0 & 0 & 0 & 7 & -6 \end{bmatrix}.
 \end{aligned}$$

(b) The data from part (a) suggest that

$$v_k = \begin{bmatrix} k \\ k-1 \\ k-2 \\ \dots \\ 1 \\ 2 \\ 3 \\ \dots \\ n-k+1 \end{bmatrix}$$

is an eigenvector of A_n with eigenvalue k . Let us prove it formally by carrying out the multiplication $A_n v_k$. Let $r_n^{(i)}$ denote the i -th row of n . Then

$$\begin{aligned}
 r_n^{(1)} \cdot v_k &= \frac{1}{n+1} \left(\frac{k(n+1)(n+2)}{2} + k + ((k-1) + (k-2) + \dots + 1)(n+1) + \right. \\
 &\quad \left. + (2+3+\dots+(n-k))(n+1) - \frac{n(n+1)(n+1-k)}{2} + n+1-k \right) = \\
 &= \frac{1}{n+1} \left(\frac{k(n+1)(n+2)}{2} + \frac{k(k-1)(n+1)}{2} + \right.
 \end{aligned}$$

$$\begin{aligned}
& + \frac{(n-k-1)(n-k+2)(n+1)}{2} - \frac{n(n+1)(n+1-k)}{2} + n+1 \Big) = \\
& = \frac{1}{n+1} \left(\frac{n+1}{2} \cdot (k(n+2) + k(k-1) + (n-k-1)(n-k+2) - n(n+1-k) + 2) \right) = \\
& = \frac{1}{2} \cdot 2k^2 = k^2,
\end{aligned}$$

which is k times the first entry of v_k , as needed. Then

$$r_n^{(2)} \cdot v_k - r_n^{(1)} \cdot v_k = \frac{1}{n+1}((-1-2n)k + (n+1)v_k(2) + n+1-k) = v_k(2) - 2k + 1,$$

where $v_k(2)$ is the second entry of v_k (we simply examine the differences between the corresponding entries in the first and in the second row). For $k=1$, this difference is 1, hence $r_n^{(2)} \cdot v_k = 2$, and for $k > 1$, this difference is $k-1-2k+1 = -k$, hence $r_n^{(2)} \cdot v_k = k^2 - k$, as needed. For $3 \leq i \leq n-1$, we have

$$\begin{aligned}
r_n^{(i)} \cdot v_k - r_n^{(i-1)} \cdot v_k &= \frac{1}{n+1}(k-i(n+1)v_k(i-1) + (i-1)(n+1)v_k(i) + n+1-k) = \\
&= i(v_k(i) - v_k(i-1)) - v_k(i) + 1.
\end{aligned}$$

If $i \leq k$, then we have $v_k(i) = k-i+1$ and $v_k(i-1) = k-i+2$, so the above difference equals $-k$. If $i > k$, then $v_k(i) = i-k+1$ and $v_k(i-1) = i-k$, so the above difference equals k . Hence

$$\begin{aligned}
r^{(1)} \cdot v_k &= k^2; \\
r^{(2)} \cdot v_k &= k^2 - k; \\
r^{(3)} \cdot v_k &= k^2 - 2k; \\
&\dots \\
r^{(k)} \cdot v_k &= k; \\
r^{(k+1)} \cdot v_k &= 2k; \\
&\dots \\
r^{(n-1)} \cdot v_k &= (n-k)k.
\end{aligned}$$

A calculation similar to the computation of the product $r^{(1)} \cdot v_k$ shows that $r^{(n)} \cdot v_k = (n+1-k)k$. Hence v_k is indeed an eigenvector of A_n with eigenvalue k .